



# **INVERTER FR-A800**



## **FR-A806 (IP55/UL Type 12 SPECIFICATIONS) INSTRUCTION MANUAL (HARDWARE)**

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**FR-A846-00250(7.5K) to 00470(18.5K)**



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Thank you for choosing this Mitsubishi inverter.

This Instruction Manual describes handling and cautions about the hardware, such as installation and wiring, for the FR-A806(IP55/UL Type12 specification product) that are different from the FR-800.

Information about the software, such as basic operations and parameters, is described in the FR-A800 Instruction Manual (Detailed) in the CD-ROM enclosed with the product.

In addition to this manual, please read the manuals in the enclosed CD-ROM carefully. Do not use this product until you have a full knowledge of the equipment, safety information and instructions.

Please forward this Instruction Manual to the end user.

### Safety Instructions

Do not attempt to install, operate, maintain or inspect the product until you have read through this Instruction Manual (Detailed) and appended documents carefully and can use the equipment correctly. Do not use this product until you have a full knowledge of the equipment, safety information and instructions.

Installation, operation, maintenance and inspection must be performed by qualified personnel. Here, an expert means a person who meets all the conditions below.

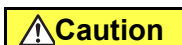
- A person who took a proper engineering training. Such training may be available at your local Mitsubishi Electric office. Contact your local sales office for schedules and locations.
- A person who can access operating manuals for the protective devices (e.g. light curtain) connected to the safety control system. A person who has read and familiarized himself/herself with the manuals.

In this Instruction Manual (Detailed), the safety instruction levels are classified into "Warning" and "Caution"



#### Warning

Incorrect handling may cause hazardous conditions, resulting in death or severe injury.



#### Caution

Incorrect handling may cause hazardous conditions, resulting in medium or slight injury, or may cause only material damage.

The **Caution** level may even lead to a serious consequence according to conditions. Both instruction levels must be followed because these are important to personal safety.

### Electric Shock Prevention

#### Warning

- While the inverter power is ON, do not open the front cover or the wiring cover. Do not run the inverter with the front cover or the wiring cover removed. Otherwise you may access the exposed high voltage terminals or the charging part of the circuitry and get an electric shock.
- Even if power is OFF, do not remove the front cover except for wiring or periodic inspection. You may accidentally touch the charged inverter circuits and get an electric shock.
- Before wiring or inspection, LED indication of the operation panel must be switched OFF. Any person who is involved in wiring or inspection shall wait for at least 10 minutes after the power supply has been switched OFF and check that there are no residual voltage using a tester or the like. The capacitor is charged with high voltage for some time after power OFF, and it is dangerous.
- This inverter must be earthed (grounded). Earthing (grounding) must conform to the requirements of national and local safety regulations and electrical code (NEC section 250, IEC 536 class 1 and other applicable standards). A neutral-point earthed (grounded) power supply in compliance with EN standard must be used.
- Any person who is involved in wiring or inspection of this equipment shall be fully competent to do the work.
- The inverter must be installed before wiring. Otherwise you may get an electric shock or be injured.
- Setting dial and key operations must be performed with dry hands to prevent an electric shock. Otherwise you may get an electric shock.
- Do not subject the cables to scratches, excessive stress, heavy loads or pinching. Otherwise you may get an electric shock.
- Do not change the cooling fan while power is ON. It is dangerous to change the cooling fan while power is ON.
- Do not touch the printed circuit board or handle the cables with wet hands. Otherwise you may get an electric shock.
- When measuring the main circuit capacitor capacity, the DC voltage is applied to the motor for 1s at powering OFF. Never touch the motor terminal, etc. right after powering OFF to prevent an electric shock.
- An PM motor is a synchronous motor with high-performance magnets embedded in the rotor. Motor terminals holds high-voltage while the motor is running even after the inverter power is turned OFF. Before wiring or inspection, the motor must be confirmed to be stopped. In an application, such as fan and blower, where the motor is driven by the load, a low-voltage manual motor starter must be connected at the inverter's output side, and wiring and inspection must be performed while the motor starter is open. Otherwise you may get an electric shock.

### Fire Prevention

#### Caution

- Inverter must be installed on a nonflammable wall without holes (so that nobody touches the inverter heatsink on the rear side, etc.). Mounting it to or near flammable material may cause a fire.
- If the inverter has become faulty, the inverter power must be switched OFF. A continuous flow of large current may cause a fire.
- Resistors are not applicable. Do not connect a resistor directly to the DC terminals P/+ and N/-. Doing so could cause a fire.
- Be sure to perform daily and periodic inspections as specified in the Instruction Manual. If a product is used without any inspection, a burst, breakage, or a fire may occur.

### Injury Prevention

#### Caution

- The voltage applied to each terminal must be the ones specified in the Instruction Manual. Otherwise burst, damage, etc. may occur.
- The cables must be connected to the correct terminals. Otherwise burst, damage, etc. may occur.
- The polarity (+ and -) must be correct. Otherwise burst, damage, etc. may occur.
- While power is ON or for some time after power-OFF, do not touch the inverter as it will be extremely hot. Touching these devices may cause a burn.

#### ◆ Additional Instructions

The following instructions must be also followed. If the product is handled incorrectly, it may cause unexpected fault, an injury, or an electric shock.

#### Caution

##### Transportation and Mounting

- Any person who is opening a package using a sharp object, such as a knife and cutter, must wear gloves to prevent injuries caused by the edge of the sharp object.
- The product must be transported in correct method that corresponds to the weight. Failure to do so may lead to injuries.
- Do not stand or rest heavy objects on the product.
- Do not stack the boxes containing inverters higher than the number recommended.
- When carrying the inverter, do not hold it by the front cover; it may fall off or fail.
- During installation, caution must be taken not to drop the inverter as doing so may cause injuries.
- The product must be installed on the surface that withstands the weight of the inverter.
- Do not install the product on a hot surface.
- The mounting orientation of the inverter must be correct.
- The inverter must be installed on a strong surface securely with screws so that it will not drop.
- Do not install or operate the inverter if it is damaged or has parts missing.
- Foreign conductive objects must be prevented from entering the inverter. That includes screws and metal fragments or other flammable substance such as oil.
- As the inverter is a precision instrument, do not drop or subject it to impact.
- The surrounding air temperature must be between -10 and +40°C (non-freezing). Otherwise the inverter may be damaged.
- The ambient humidity must be 95%RH or less (non-condensing). Otherwise the inverter may be damaged. (Refer to [page 16](#) for details.)
- The storage temperature (applicable for a short time, e.g. during transit) must be between -20 and +65°C. Otherwise the inverter may be damaged.
- The inverter must be used indoors (without corrosive gas, flammable gas, oil mist, dust and dirt etc.) Otherwise the inverter may be damaged.
- The inverter must be used at an altitude of 2500 m above sea level, with vibration at 5.9 m/s<sup>2</sup> or less, 10 to 55 Hz (directions of X, Y, Z axes). Otherwise the inverter may be damaged. (Refer to [page 16](#) for details.)
- If halogen-based materials (fluorine, chlorine, bromine, iodine, etc.) infiltrate into a Mitsubishi product, the product will be damaged. Halogen-based materials are often included in fumigant, which is used to sterilize or disinfest wooden packages. When packaging, prevent residual fumigant components from being infiltrated into Mitsubishi products, or use an alternative sterilization or disinfection method (heat disinfection, etc.) for packaging. Sterilization of disinfection of wooden package should also be performed before packaging the product.

##### Wiring


- Do not install a power factor correction capacitor or surge suppressor/capacitor type filter on the inverter output side. These devices on the inverter output side may be overheated or burn out.
  - The output side terminals (terminals U, V, and W) must be connected correctly. Otherwise the motor will rotate inversely.
  - PM motor terminals (U, V, W) hold high-voltage while the PM motor is running even after the power is turned OFF. Before wiring, the PM motor must be confirmed to be stopped. Otherwise you may get an electric shock.
  - Never connect an PM motor to the commercial power supply.
- Applying the commercial power supply to input terminals (U, V, W) of an PM motor will burn the PM motor. The PM motor must be connected with the output terminals (U, V, W) of the inverter.

##### Trial run

- Before starting operation, each parameter must be confirmed and adjusted. A failure to do so may cause some machines to make unexpected motions.

#### Warning

##### Usage

- Everyone must stay away from the equipment when the retry function is set as it will restart suddenly after a trip.
-  Since pressing a key may not stop output depending on the function setting status, separate circuit and switch that make an emergency stop (power OFF, mechanical brake operation for emergency stop, etc.) must be provided.
- OFF status of the start signal must be confirmed before resetting the inverter fault. Resetting inverter fault with the start signal ON restarts the motor suddenly.
- Do not use an PM motor for an application where the PM motor is driven by its load and runs at a speed higher than the maximum motor speed.
- Use this inverter only with three-phase induction motors or with an PM motor. Connection of any other electrical equipment to the inverter output may damage the equipment.
- Performing pre-excitation (LX signal and X13 signal) under torque control (Real sensorless vector control) may start the motor running at a low speed even when the start command (STF or STR) is not input. The motor may run also at a low speed when the speed limit value = 0 with a start command input. It must be confirmed that the motor running will not cause any safety problem before performing pre-excitation.
- Do not modify the equipment.
- Do not perform parts removal which is not instructed in this manual. Doing so may lead to fault or damage of the product.

### Caution

#### Usage

- The electronic thermal relay function does not guarantee protection of the motor from overheating. It is recommended to install both an external thermal and PTC thermistor for overheat protection.
  - Do not use a magnetic contactor on the inverter input for frequent starting/stopping of the inverter. Otherwise the life of the inverter decreases.
  - The effect of electromagnetic interference must be reduced by using a noise filter or by other means. Otherwise nearby electronic equipment may be affected.
  - Appropriate measures must be taken to suppress harmonics. Otherwise power supply harmonics from the inverter may heat/damage the power factor correction capacitor and generator.
  - When driving a 400V class motor by the inverter, the motor must be an insulation-enhanced motor or measures must be taken to suppress surge voltage. Surge voltage attributable to the wiring constants may occur at the motor terminals, deteriorating the insulation of the motor.
  - When parameter clear or all parameter clear is performed, the required parameters must be set again before starting operations. because all parameters return to their initial values.
  - The inverter can be easily set for high-speed operation. Before changing its setting, the performances of the motor and machine must be fully examined.
  - Stop status cannot be hold by the inverter's brake function. In addition to the inverter's brake function, a holding device must be installed to ensure safety.
  - Before running an inverter which had been stored for a long period, inspection and test operation must be performed.
  - Static electricity in your body must be discharged before you touch the product.
  - Only one PM motor can be connected to an inverter.
  - An PM motor must be used under PM sensorless vector control. Do not use a synchronous motor, induction motor, or synchronous induction motor.
  - Do not connect an PM motor in the induction motor control settings (initial settings). Do not use an induction motor in the PM sensorless vector control settings. It will cause a failure.
  - In the system with an PM motor, the inverter power must be turned ON before closing the contacts of the contactor at the output side.
- #### Emergency stop
- A safety backup such as an emergency brake must be provided to prevent hazardous conditions to the machine and equipment in case of inverter failure.
  - When the breaker on the inverter input side trips, the wiring must be checked for fault (short circuit), and internal parts of the drive unit for a damage, etc. The cause of the trip must be identified and removed before turning ON the power of the breaker.
  - When a protective function activates, take an appropriate corrective action, then reset the inverter, and resume the operation.

#### Maintenance, inspection and parts replacement

- Do not carry out a megger (insulation resistance) test on the control circuit of the inverter. It will cause a failure.

#### Disposal

- The inverter must be treated as industrial waste.

### General instruction

- Many of the diagrams and drawings in the Instruction Manual show the product without a cover or partially open for explanation. Never operate the product in this manner. The cover must be always reinstalled and the instruction in the Instruction Manual must be followed when operating the product. For more details on the PM motor, refer to the Instruction Manual of the PM motor.

### Caution

#### Waterproof and dustproof performances

- The inverter is rated with an IPX5\*1 waterproof rating and an IP5X\*2 dustproof rating when the operation panel (FR-DU08-01), the front cover, the wiring cover, and the cable glands are securely fixed with screws.
- The items enclosed with the inverter such as the Instruction Manual or CD are not rated with the IPX5 waterproof or IP5X dustproof ratings.
- Although the inverter is rated with the IPX5 waterproof and IP5X dustproof ratings, it is not intended for use in water. Also, the ratings do not guarantee protection of the inverter from needless submersion in water or being washed under strong running water such as a shower.
- Do not pour or apply the following liquids over the inverter: water containing soap, detergent, or bath additives; sea water; swimming pool water; warm water; boiling water; and the like.
- The inverter is intended for indoor\*4 installation and not for outdoor installation. Avoid places where the inverter is subjected to direct sunlight, rain, sleet, snow, or freezing temperatures.
- If the operation panel (FR-DU08-01) is not installed, if the screws of the FR-DU08-01 are not tightened, or if the FR-DU08-01 is damaged or deformed, the IPX5 waterproof performance and the IP5X dustproof performance are impaired. If any abnormalities are found on the FR-DU08-01, ask for an inspection and repair.
- If the screws of the front cover or the wiring cover are not tightened, if any foreign matter (hair, sand grain, fiber, etc.) is stuck between the inverter and the packing, if the packing is damaged, or if the front cover or the wiring cover is damaged or deformed, the IPX5 waterproof performance and the IP5X dustproof performance are impaired. If any abnormalities are found on the front cover, wiring cover, or the packing of the inverter, ask for an inspection and repair.
- Cable glands are important components to maintain the waterproof and dustproof performances. Be sure to use cable glands of the recommended size and shape or equivalent. The standard protective bushes cannot sufficiently maintain the IPX5 waterproof performance and the IP5X dustproof performance.
- If a cable gland is damaged or deformed, the IPX5 waterproof performance and the IP5X dustproof performance are impaired. If any abnormalities are found on the cable glands, ask the manufacturer of the cable glands for an inspection and repair.
- To maintain the waterproof and dustproof performances of the inverter, daily and periodic inspections are recommended regardless of the presence or absence of abnormalities.

\*1 IPX5 refers to protection of the inverter functions against water jets from any direction when about 12.5-liter water\*3 is injected from a nozzle with an inside diameter of 6.3 mm from the distance of about 3 m for at least 3 minutes.

\*2 IP5X refers to protection of the inverter functions and maintenance of safety when the inverter is put into a stirring device containing dust of 75 µm or smaller in diameter, stirred for 8 hours, and then removed from the device.

\*3 Water here refers to fresh water at room temperature (5 to 35°C).

\*4 Indoor here refers to the environments that are not affected by climate conditions.



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# 1 INTRODUCTION

This chapter contains the descriptions that must be read before using this product.

Always read the instructions before using the equipment.

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| <b>1.1</b> | <b>Product checking and accessories</b> | <b>8</b>  |
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## <Abbreviations>

|                                  |   |
|----------------------------------|---|
| DU                               | Operation panel (FR-DU08-01)  |
| PU                               | Operation panel (FR-DU08-01) and parameter unit (FR-PU07)                   |
| Inverter                         | Mitsubishi inverter FR-A800 series (IP55 compatible model)                  |
| Pr.                              | Parameter number (Number assigned to function)                              |
| PU operation                     | Operation using the PU (FR-DU08-01/FR-PU07)                                 |
| External operation               | Operation using the control circuit signals                                 |
| Combined operation               | Combined operation using the PU (FR-DU08-01/FR-PU07) and External operation |
| Mitsubishi standard motor        | SF-JR   |
| Mitsubishi constant-torque motor | SF-HRCA   |
| Vector control dedicated motor   | SF-V5RU   |

## <Trademarks>

- Company and product names herein are the trademarks and registered trademarks of their respective owners.

## <Notes on descriptions in this Instruction Manual>

- Connection diagrams in this Instruction Manual suppose that the control logic of the input terminal is the sink logic, unless otherwise specified. (For the control logic, refer to [page 32.](#))

## Harmonic Suppression Guidelines

All the models of the inverters used by specific consumers are covered by "the Harmonic Suppression Guidelines for Consumers Who Receive High Voltage or Special High Voltage". (For details, refer to [page 68.](#))

# 1.1 Product checking and accessories

Unpack the product and check the capacity plate on the front cover and the rating plate on the side to ensure that the model agrees with the order and the product is intact.

●Inverter model

| Symbol | Voltage class |
|--------|---------------|
| 4      | 400V class    |

| Symbol | Structure, functionality |
|--------|--------------------------|
| 6      | IP55 compatible model    |

| Symbol         | Description   |
|----------------|---|
| 7.5K to 18.5K  | ND rated inverter capacity (kW)   |
| 00250 to 00470 | Rated inverter current (SLD rated current of the A800 standard model) (A) |

| Symbol | Type*1 |
|--------|--------|
| -1     | FM     |
| -2     | CA     |

FR - A 8 4 6 - 00250 - 1 - 60 C3

| Symbol | Plated conductor |
|--------|------------------|
| -60    | Not used         |
| -06    | Used             |

| Symbol | EMC filter         |
|--------|--------------------|
| C2     | Built-in C2 filter |
| C3     | Built-in C3 filter |

Rating plate

MITSUBISHI ELECTRIC INVERTER PASSED

MODEL FR-A846-00250-1-60C3

INPUT : XXXXX

OUTPUT : XXXXX

SERIAL : XXXXXXXXXX DATE : XXXX-XX

→ Inverter model

→ Input rating

→ Output rating

→ SERIAL

→ Manufactured year and month

\*1 Specification differs by the type as follows.

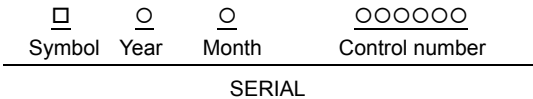
| Type                               | Motor output   | Initial setting     |               |                 |   |
|------------------------------------|--|---------------------|---------------|-----------------|---|
|                                    |  | Built-in EMC filter | Control logic | Rated frequency | Pr.19 Base frequency voltage            |
| FM<br>(terminal FM equipped model) | Terminal FM (pulse train output)<br>Terminal AM (analog voltage output (0 to ±10 VDC))                   | OFF                 | Sink logic    | 60 Hz           | 9999 (same as the power supply voltage) |
| CA<br>(terminal CA equipped model) | Terminal CA (analog current output (0 to 20 mADC))<br>Terminal AM (analog voltage output (0 to ±10 VDC)) | ON                  | Source logic  | 50 Hz           | 8888 (95% of the power supply voltage)  |

REMARKS

- Hereinafter, the inverter model name consists of the applicable motor capacity and the rated current value (SLD rated current value of the A800 standard model).  
(Example) FR-A846-00250(7.5K)

● How to read the SERIAL number

Rating plate example

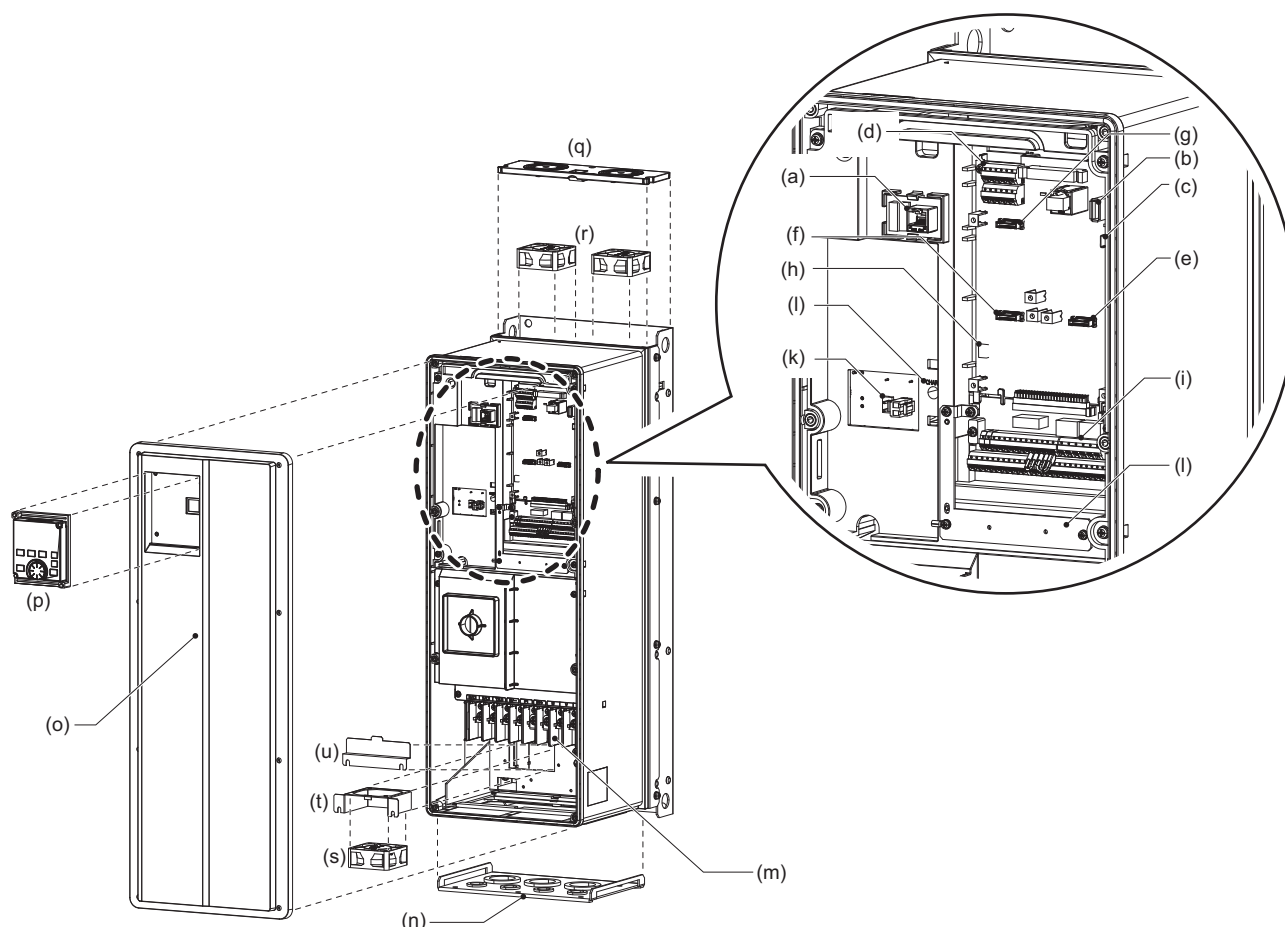


The SERIAL consists of one symbol, two characters indicating the production year and month, and six characters indicating the control number. The last digit of the production year is indicated as the Year, and the Month is indicated by 1 to 9, X (October), Y (November), or Z (December.)



# 1.2 Component names

Component names are shown below.



| Symbol | Name                                   | Description  | Refer to page                    |
|--------|--|--|----------------------------------|
| (a)    | PU connector                           | Connects the operation panel (FR-DU08-01) or the parameter unit (FR-PU07). This connector also enables the RS-485 communication.   | 44                               |
| (b)    | USB A connector                        | Connects a USB memory device.  | 45                               |
| (c)    | USB mini B connector                   | Connects a personal computer and enables communication with FR Configurator 2.   | 45                               |
| (d)    | RS-485 terminals                       | Enables RS-485, Modbus-RTU communication.  | 47                               |
| (e)    | Plug-in option connector1              | Connects a plug-in option or a communication option.   | Instruction Manual of the option |
| (f)    | Plug-in option connector2              |  |                                  |
| (g)    | Plug-in option connector3              |  |                                  |
| (h)    | Voltage/current input switch           | Selects between voltage and current for the terminal 2 and 4 inputs.   | *1                               |
| (i)    | Control circuit terminal block         | Connects cables for the control circuit.   | 28                               |
| (j)    | EMC filter ON/OFF connector            | Turns ON/OFF the EMC filter.   | 66                               |
| (k)    | Charge lamp                            | Stays ON while the power is supplied to the main circuit.  | 23                               |
| (l)    | Metal fitting for earthing (grounding) | Earths (grounds) the shielded wires of the encoder cable, etc.   | 53                               |
| (m)    | Main circuit terminal block            | Connects cables for the main circuit.  | 23                               |
| (n)    | Wiring cover                           | Remove the protective bushes to connect cables.  | 15                               |
| (o)    | Front cover                            | Remove this cover for the installation of the product, installation of a plug-in (communication) option, RS-485 terminal wiring, switching of the voltage/current input switch, etc. | 15                               |
| (p)    | Operation panel (FR-DU08-01)           | Operates and monitors the inverter.  | 42                               |
| (q)    | Fan cover                              | Remove this cover for replacement of the cooling fan.  | 87                               |
| (r)    | Cooling fan                            | Cools off the inverter.  | 87                               |
| (s)    | Internal fan                           |  | 89                               |
| (t)    | Bracket                                |  | 89                               |
| (u)    | Protective cover                       | Protects the fan to avoid contacting the wiring.   | 89                               |

\*1 Refer to the FR-A800 Instruction Manual (Detailed)

# 1.3 About the related manuals

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The manuals related to FR-A806 are shown below.

Related manuals

| Manual name                                     | Manual number  |
|---|----------------|
| FR-A800 Instruction Manual (Detailed)           | IB-0600503ENG  |
| FR Configurator 2 Instruction Manual            | IB-0600516ENG  |
| FR-A800 PLC function programming manual         | IB-0600492ENG  |
| FR-A800 Safety stop function instruction manual | BCN-A23228-001 |

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# **2 INSTALLATION AND WIRING**

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This chapter explains the "INSTALLATION" and the "WIRING" of this product.

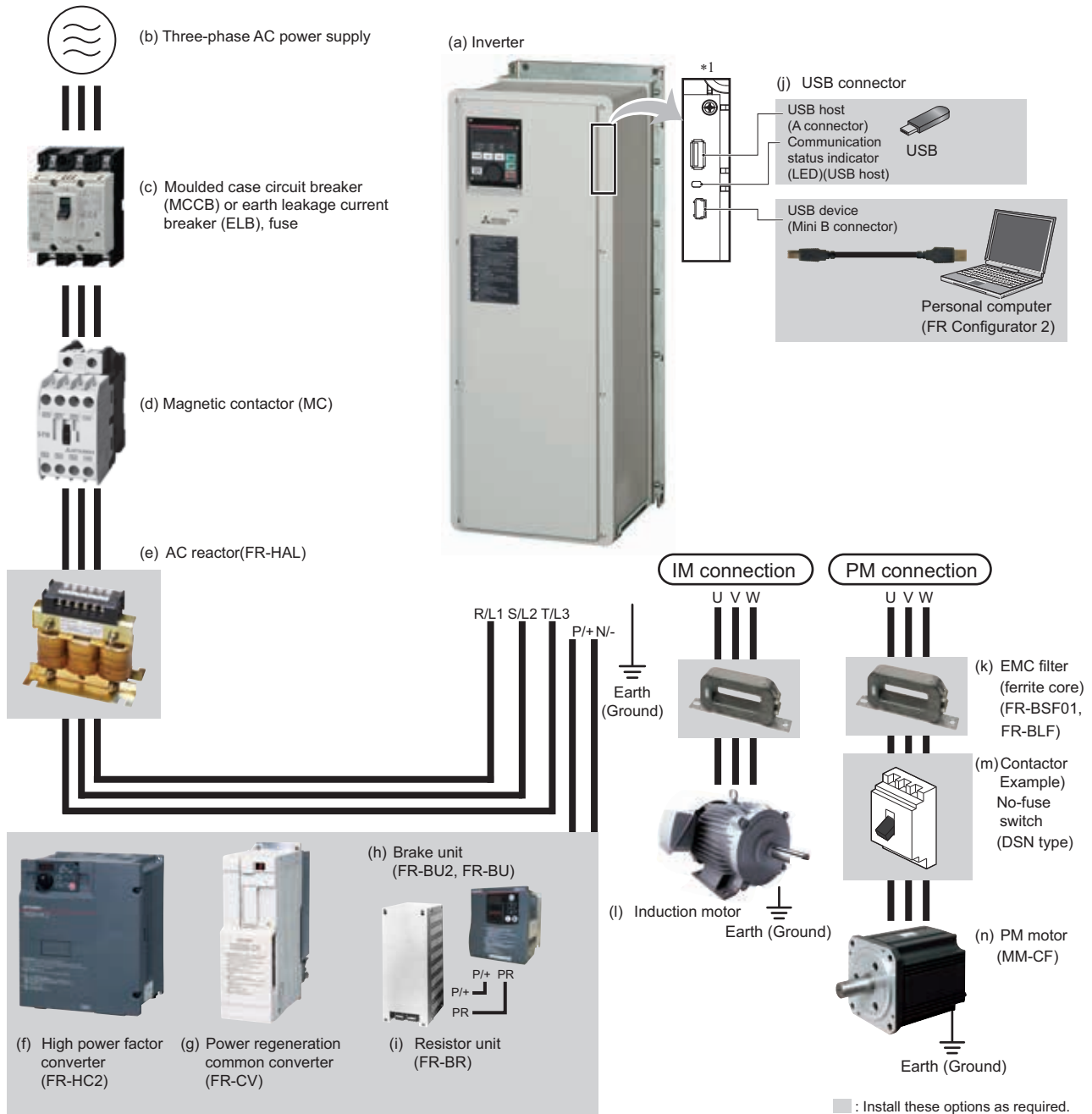
Always read the instructions before using the equipment.

---

|             |  |           |
|-------------|--|-----------|
| <b>2.1</b>  | <b>Peripheral devices .....</b>                                | <b>12</b> |
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| <b>2.9</b>  | <b>Connection of motor with encoder (vector control) .....</b> | <b>48</b> |
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## 2.1 Peripheral devices

### 2.1.1 Inverter and peripheral devices



\*1 The figure shows the area with the front cover removed.

#### REMARKS

- To prevent an electric shock, always earth (ground) the motor and inverter.
- Do not install a power factor correction capacitor or surge suppressor or capacitor type filter on the inverter's output side. Doing so will cause the inverter to trip or the capacitor and surge suppressor to be damaged. If any of the above devices is connected, immediately remove it. When installing a molded case circuit breaker on the output side of the inverter, contact the manufacturer of the molded case circuit breaker.
- Electromagnetic wave interference  
The input/output (main circuit) of the inverter includes high frequency components, which may interfere with the communication devices (such as AM radios) used near the inverter. In this case, activating the EMC filter may minimize interference. (Refer to [page 66.](#))
- For details of options and peripheral devices, refer to the Instruction Manual of each.
- A PM motor cannot be driven by the commercial power supply.
- A PM motor is a motor with permanent magnets embedded inside. High voltage is generated at the motor terminals while the motor is running. Before closing the contactor at the output side, make sure that the inverter power is ON and the motor is stopped.

| Symbol | Name   | Overview  | Refer to page  |
|--------|--|---|--|
| (a)    | Inverter (FR-A806)   | The life of the inverter is influenced by the surrounding air temperature. The surrounding air temperature should be as low as possible within the permissible range.<br>Incorrect wiring may lead to damage of the inverter. The control signal lines must be kept fully away from the main circuit lines to protect them from noise.<br>The built-in EMC filter can reduce the noise.<br>A DC reactor and common mode choke are built in this inverter to suppress harmonics and to improve the power factor. | <a href="#">16</a><br><a href="#">19</a><br><a href="#">66</a> |
| (b)    | Three-phase AC power supply  | Must be within the permissible power supply specifications of the inverter.   | <a href="#">98</a>   |
| (c)    | Molded case circuit breaker (MCCB), earth leakage circuit breaker (ELB), or fuse | Must be selected carefully since an inrush current flows in the inverter at power ON.   | <a href="#">14</a>   |
| (d)    | Magnetic contactor (MC)  | Install this to ensure safety.<br>Do not use this to start and stop the inverter. Doing so will shorten the life of the inverter.   | <a href="#">71</a>   |
| (e)    | AC reactor (FR-HAL)  | Install this to suppress harmonics and to improve the power factor.<br>An AC reactor (FR-HAL) (option) is required when installing the inverter near a large power supply system (1000 kVA or more). Under such condition, the inverter may be damaged if you do not use a reactor. Select a reactor according to the applied motor capacity.   | <a href="#">70</a>   |
| (f)    | High power factor converter (FR-HC2)   | Suppresses the power supply harmonics significantly. Install this as required.  | <a href="#">59</a>   |
| (g)    | Power regeneration common converter (FR-CV)                                      | Provides a great braking capability. Install this as required.  | <a href="#">60</a>   |
| (h)    | Brake unit (FR-BU2, FR-BU)   | Allows the inverter to provide the optimal regenerative braking capability.   | <a href="#">56</a>   |
| (i)    | Resistor unit (FR-BR)  | Install this as required.   |  |
| (j)    | USB connection   | A USB (Ver. 1.1) cable connects the inverter with a personal computer.<br>A USB memory device enables parameter copies and the trace function.  | <a href="#">45</a>   |
| (k)    | Noise filter (FR-BSF01, FR-BLF)  | Install this to reduce the electromagnetic noise generated from the inverter. The noise filter is effective in the range from about 0.5 MHz to 5 MHz.<br>A wire should be wound four turns at maximum.  | <a href="#">64</a>   |
| (l)    | Induction motor  | Connect a squirrel-cage induction motor.  | —  |
| (m)    | Contactor<br>Example) No-fuse switch (DSN type)                                  | Connect this for an application where a PM motor is driven by the load even while the inverter power is OFF. Do not open or close the contactor while the inverter is running (outputting).   | —  |
| (n)    | PM motor   | When PM sensorless vector control is selected, a PM motor can be driven.  | —  |



## 2.1.2 Peripheral devices

Check the model of the inverter you purchased. Appropriate peripheral devices must be selected according to the capacity. Refer to the table below to prepare appropriate peripheral devices.

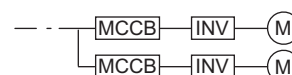
| Motor output (kW) *1 | Applicable inverter model | Molded case circuit breaker (MCCB) *2 or earth leakage circuit breaker (ELB) (NF, NV type) | Input-side magnetic contactor *3 |
|----------------------|---------------------------|--|----------------------------------|
| 7.5                  | FR-A846-00250(7.5K)       | 30A  | S-T20, T21                       |
| 11                   | FR-A846-00310(11K)        | 40A  | S-T20, T21                       |
| 15                   | FR-A846-00380(15K)        | 50A  | S-T20, T21                       |
| 18.5                 | FR-A846-00470(18.5K)      | 60A  | S-T25                            |

\*1 Assumes the use of a Mitsubishi 4-pole standard motor with the power supply voltage of 400 VAC 50 Hz.

\*2 Select an MCCB according to the power supply capacity.

Install one MCCB per inverter.

For the use in the United States or Canada, provide the appropriate UL and cUL listed fuse or UL489 molded case circuit breaker (MCCB) that is suitable for branch circuit protection. (Refer to [page 107](#).)



\*3 Magnetic contactor is selected based on the AC-1 class. The electrical durability of magnetic contactor is 500,000 times. When the magnetic contactor is used for emergency stops during motor driving, the electrical durability is 25 times.

If using an MC for emergency stop during motor driving, select an MC regarding the drive unit input side current as JEM1038-AC-3 class rated current.

When using a magnetic contactor for the power supply switching to the commercial power supply during general-purpose motor operation, select a magnetic contactor with the class JEM1038-AC-3 rated current for the rated motor current.

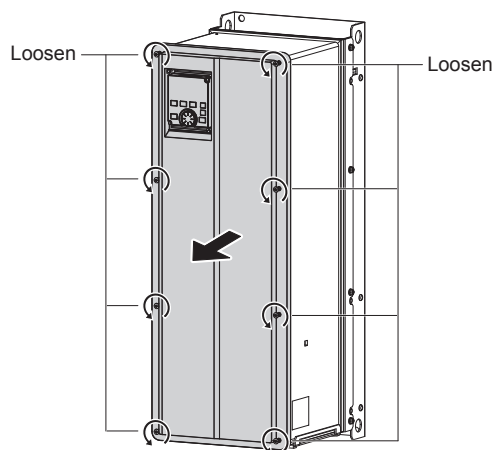
### REMARKS

- When the inverter capacity is larger than the motor capacity, select an MCCB and a magnetic contactor according to the inverter model, and select cables and reactors according to the motor output.
- When the breaker on the inverter's input side trips, check for the wiring fault (short circuit), damage to internal parts of the inverter etc. The cause of the trip must be identified and removed before turning ON the power of the breaker..

## 2.2 Removal and reinstallation of the front cover

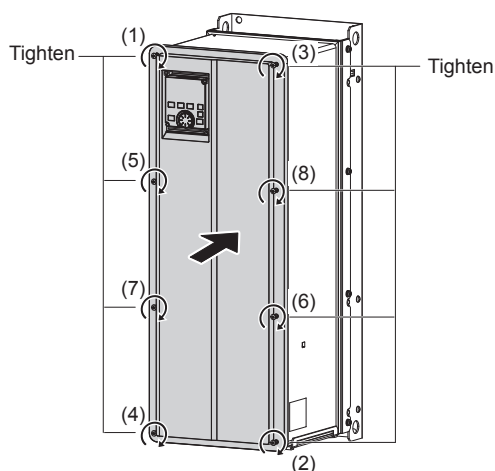
### (1) Removal of the front cover

- Remove the front cover installation screws (hexalobular screws, screw size: M4, screwdriver size: T20) to remove the front cover.



### (2) Reinstallation of the front cover

- Fix the front cover with the front cover installation screws. (Tightening torque: 1.4 to 1.9 N·m)  
Tighten the front cover installation screws in the numerical order in the figure shown below.



#### REMARKS

- When installing the front cover, fit the connector of the operation panel securely along the guides of the PU connector.
- Before installing the front cover, check the waterproof packing to make sure that it is not damaged. If it is damaged, contact the nearest Mitsubishi FA center.
- Securely install the front cover to fit closely to the waterproof packing. Do not let the waterproof packing stuck between the front cover edge and the inverter. Otherwise, water may get into the inverter. Also, do not let any foreign matter stuck between the waterproof packing and the front cover.
- Keep the waterproof packing of the inverter clean. Otherwise, water may get into the inverter. When there are any stains on the packing, make sure to remove them.
- Fully make sure that the front cover is installed securely. Always tighten the mounting screws of the front cover.

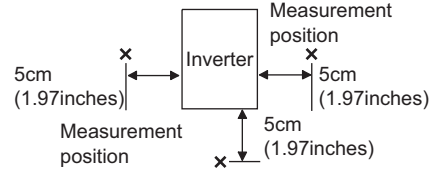
## 2.3 Installation of the inverter

An inverter unit uses many semiconductor devices. To ensure higher reliability and long period of operation, operate the inverter in the ambient environment that completely satisfies the equipment specifications.

### 2.3.1 Inverter installation environment

The following table lists the standard specifications of the inverter installation environment. Using the inverter in the environment that does not satisfy the conditions deteriorates the performance, shortens the life, and causes a failure. Refer to the following points, and take adequate measures.

#### (1) Standard environmental specifications of the inverter

| Item                        | Description   |  |
|-----------------------------|---|--|
| Surrounding air temperature | -10 to +40°C (non-freezing)   |  |
| Ambient humidity            | 95% RH or less (non-condensing)   |  |
| Storage temperature         | -20 to +65°C*1  |  |
| Atmosphere                  | Indoors (free from corrosive gas, flammable gas, oil mist, dust and dirt) |  |
| Altitude                    | Maximum 1,000 m above sea level.*2  |  |
| Vibration                   | 5.9 m/s <sup>2</sup> or less at 10 to 55 Hz (directions of X, Y, Z axes)  |  |

\*1 Temperature applicable for a short time, e.g. in transit.

\*2 For the installation at an altitude above 1,000 m (3280.80 feet) up to 2,500 m (8202 feet), derate the rated current 3% per 500 m (1640.40 feet).

#### (2) Temperature

The permissible surrounding air temperature of the inverter is between -10°C and +40°C. Always operate the inverter within this temperature range. Operation outside this range will considerably shorten the service lives of the semiconductors, parts, capacitors and others. Take the following measures to keep the surrounding air temperature of the inverter within the specified range.

##### (a) Measures against high temperature

- Ventilate the room.
- Install the inverter in an air-conditioned electric chamber.
- Block direct sunlight.
- Provide a shield or similar plate to avoid direct exposure to the radiated heat and wind of a heat source.
- Ventilate the area around the inverter well.

##### (b) Measures against low temperature

- Provide a heater around the inverter.
- Do not power OFF the inverter. (Keep the start signal of the inverter OFF.)

##### (c) Sudden temperature changes

- Select an installation place where temperature does not change suddenly.
- Avoid installing the inverter near the air outlet of an air conditioner.
- If temperature changes are caused by opening/closing of a door, install the inverter away from the door.

### (3) Humidity

Normally operate the inverter within the ambient air humidity of 45 to 95%. Too high humidity will pose problems of reduced insulation and metal corrosion. On the other hand, too low humidity may cause a spatial electrical breakdown. The insulation distance defined in JEM1103 "Control Equipment Insulator" is humidity of 45 to 85%.

#### (a) Measures against high humidity

- Provide dry air into the room from outside.
- Use a dehumidifier.

#### (b) Measures against low humidity

Air with proper humidity can be blown into the room from outside. Also when installing or inspecting the unit, discharge your body (static electricity) beforehand, and keep your body away from the parts and patterns.

#### (c) Measures against condensation

Condensation may occur if frequent operation stops change the in-room temperature suddenly or if the outside air temperature changes suddenly.

Condensation causes such faults as reduced insulation and corrosion.

- Take the measures against high humidity in (a).
- Do not power OFF the inverter. (Keep the start signal of the inverter OFF.)

### (4) Dust, dirt, oil mist

Dust and dirt will cause faults such as poor contacts, reduction in insulation and cooling effect due to accumulation of moisture-absorbed dust and dirt, and equipment internal temperature rise due to a clogged ventilation filter in the room where the equipment is installed. In the atmosphere where conductive powder floats, dust and dirt will cause such faults as malfunction, deteriorated insulation and short circuit in a short time.

Since oil mist will cause similar conditions, it is necessary to take adequate measures.

Countermeasure

- Purge air.  
Pump clean air from outside to make the in-enclosure air pressure higher than the outside air pressure.

### (5) Corrosive gas, salt damage

If the inverter is exposed to corrosive gas or to salt near a beach, the printed board patterns and parts will corrode or the relays and switches will result in poor contact.

In such a place, take the countermeasures described in "Dust, dirt, oil mist" above.

### (6) Explosive, flammable gases

As the inverter is non-explosion proof, it must be contained in an explosion-proof enclosure. In places where explosion may be caused by explosive gas, dust or dirt, an enclosure cannot be used unless it structurally complies with the guidelines and has passed the specified tests. This makes the enclosure itself expensive (including the test charges). The best way is to avoid installation in such places and install the inverter in a non-hazardous place.

### (7) Highland

Use the inverter at an altitude of within 1000 m. For the installation at an altitude above 1,000 m (3280.80 feet) up to 2,500 m (8202 feet), derate the rated current 3% per 500 m (1640.40 feet).

If it is used at a higher place, it is likely that thin air will reduce the cooling effect and low air pressure will deteriorate dielectric strength.

### (8) Vibration, impact

The vibration resistance of the inverter is up to  $5.9 \text{ m/s}^2$  at 10 to 55 Hz frequency and 1 mm amplitude for the directions of X, Y, Z axes. Applying vibration and impact for a long time may loosen the structures and cause poor contacts of connectors, even if those vibration and impacts are within the specified values.

Especially when impact is applied repeatedly, caution must be taken because such impacts may break the installation feet.

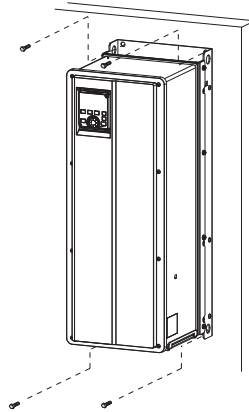
Countermeasure

- Strengthen the structure to prevent the installation surface from resonance.
- Install the inverter away from the sources of the vibration.

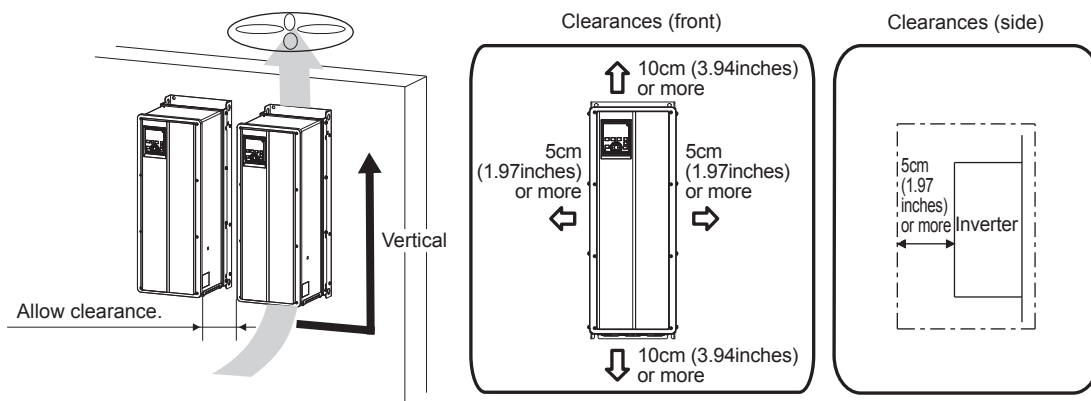
### 2.3.2 Inverter installation

#### (1) Inverter placement

- Install the inverter on a strong flat surface securely with screws.



- Leave enough clearances and take cooling measures.
- Avoid places where the inverter is subjected to direct sunlight, high temperature and high humidity.
- Install the inverter on a nonflammable wall surface.
- For heat dissipation and maintenance, keep clearance between the inverter and the other devices. The clearance below the inverter is required as a wiring space, and the clearance above the inverter is required as a heat dissipation space.



#### (2) Installation orientation of the inverter

Install the inverter on a wall as specified. Do not mount it horizontally or any other way.

#### (3) Above the inverter

Heat is blown up from inside the inverter by the small fan built in the unit. Any equipment placed above the inverter should be heat resistant.



**(1) FM type**

○ Control circuit terminal



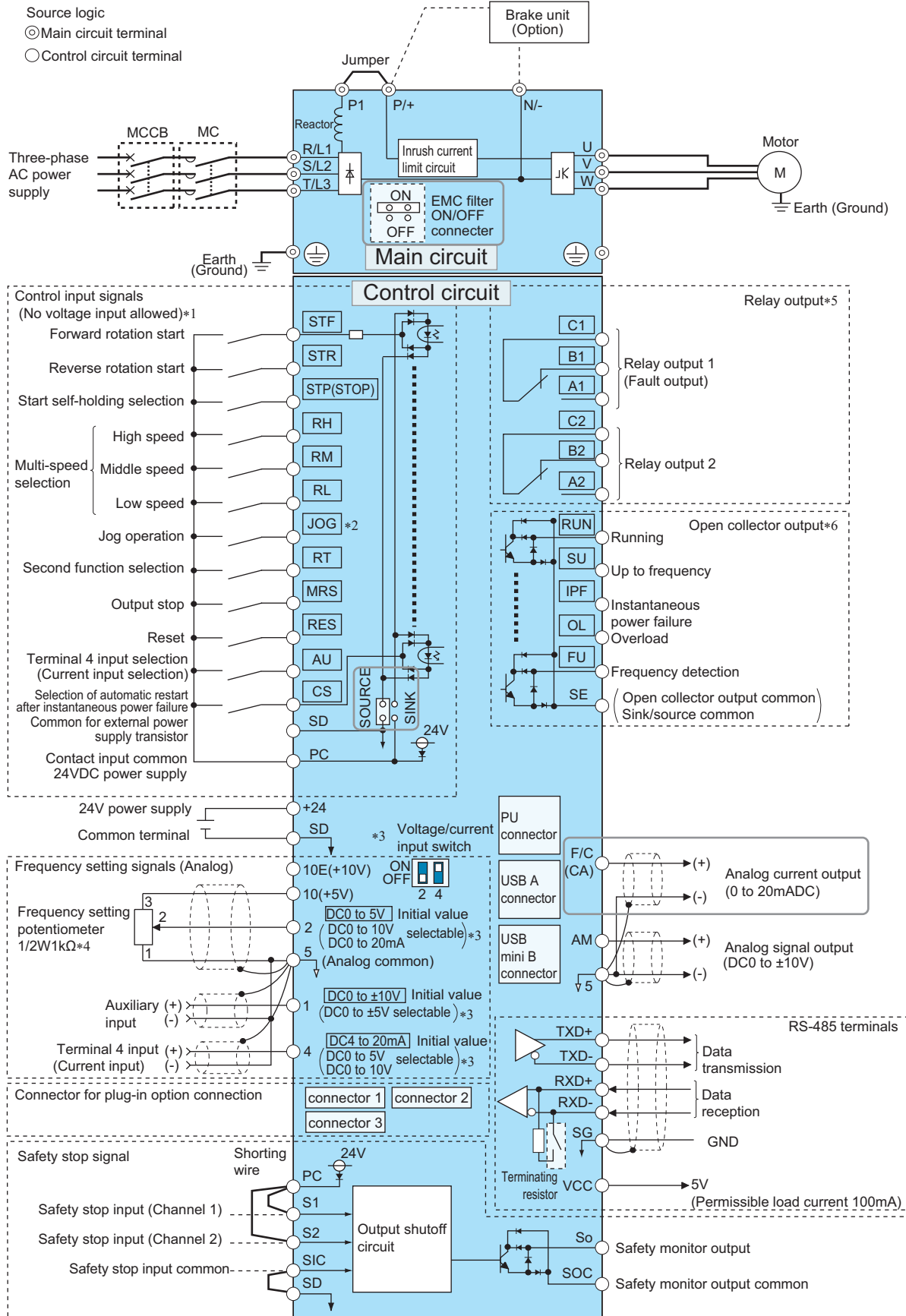
## Terminal connection diagrams

- \*1 The function of these terminals can be changed with the input terminal assignment (**Pr.178 to Pr.189**). (Refer to the FR-A800 Instruction Manual (Detailed).)
- \*2 Terminal JOG is also used as a pulse train input terminal. Use **Pr.291** to choose JOG or pulse.
- \*3 Terminal input specifications can be changed by analog input specification switchover (**Pr.73, Pr.267**). To input a voltage (0 to 5 V/0 to 10 V), set the voltage/current input switch OFF. To input a current (4 to 20 mA), set the voltage/current input switch ON. Terminals 10 and 2 are also used as a PTC input terminal. (**Pr.561**) (Refer to the FR-A800 Instruction Manual (Detailed).)
- \*4 It is recommended to use 2 W 1 k $\Omega$  when the frequency setting signal is changed frequently.
- \*5 The function of these terminals can be changed with the output terminal assignment (**Pr.195, Pr.196**). (Refer to the FR-A800 Instruction Manual (Detailed).)
- \*6 The function of these terminals can be changed with the output terminal assignment (**Pr.190 to Pr.194**). (Refer to the FR-A800 Instruction Manual (Detailed).)
- \*7 The terminal FM can be used to output pulse trains as open collector output by setting **Pr.291**.
- \*8 Not required when calibrating the scale with the operation panel.

### REMARKS

- To prevent a malfunction due to noise, keep the signal cables 10 cm (3.94 inches) or more away from the power cables. Also, separate the main circuit cables at the input side from the main circuit cables at the output side.
- After wiring, wire offcuts must not be left in the inverter.  
Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean.  
When drilling mounting holes in a wall or the side of the enclosure etc., take caution not to allow chips and other foreign matters to enter the inverter.
- Set the voltage/current input switch correctly. Incorrect setting may cause a fault, failure or malfunction.

(2) CA type



## Terminal connection diagrams


- \*1 The function of these terminals can be changed with the input terminal assignment (**Pr.178 to Pr.189**). (Refer to the FR-A800 Instruction Manual (Detailed).)
- \*2 Terminal JOG is also used as a pulse train input terminal. Use **Pr.291** to choose JOG or pulse.
- \*3 Terminal input specifications can be changed by analog input specification switchover (**Pr.73, Pr.267**). To input a voltage (0 to 5 V/0 to 10 V), set the voltage/current input switch OFF. To input a current (4 to 20 mA), set the voltage/current input switch ON. Terminals 10 and 2 are also used as a PTC input terminal. (**Pr.561**) (Refer to the FR-A800 Instruction Manual (Detailed).)
- \*4 It is recommended to use 2 W 1 k $\Omega$  when the frequency setting signal is changed frequently.
- \*5 The function of these terminals can be changed with the output terminal assignment (**Pr.195, Pr.196**). (Refer to the FR-A800 Instruction Manual (Detailed).)
- \*6 The function of these terminals can be changed with the output terminal assignment (**Pr.190 to Pr.194**). (Refer to the FR-A800 Instruction Manual (Detailed).)

### REMARKS

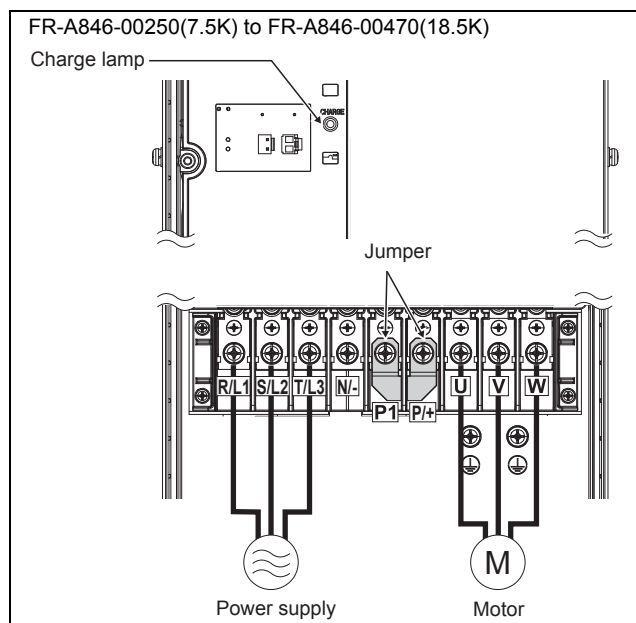
- To prevent a malfunction due to noise, keep the signal cables 10 cm (3.94 inches) or more away from the power cables. Also, separate the main circuit cables at the input side from the main circuit cables at the output side.
- After wiring, wire offcuts must not be left in the inverter.  
Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean.  
When drilling mounting holes in a wall or the side of the enclosure etc., take caution not to allow chips and other foreign matters to enter the inverter.
- Set the voltage/current input switch correctly. Incorrect setting may cause a fault, failure or malfunction.

## 2.5 Main circuit terminals

### 2.5.1 Details on the main circuit terminals

| Terminal symbol   | Terminal name         | Terminal function description   | Refer to page |
|---|-----------------------|---|---------------|
| R/L1,<br>S/L2,<br>T/L3  | AC power input        | Connect these terminals to the commercial power supply.<br>Do not connect anything to these terminals when using the high power factor converter (FR-HC2) or the power regeneration common converter (FR-CV). | —             |
| U, V, W   | Inverter output       | Connect these terminals to a three-phase squirrel cage motor or a PM motor.   | —             |
| P/+, N/-  | Brake unit connection | Connect the brake unit (FR-BU2, FR-BU, BU), power regeneration common converter (FR-CV), high power factor converter (FR-HC2), or DC power supply (under DC feeding mode).                                    | 56            |
| P/+, P1   | —                     | The jumper across terminals P/+ and P1 should not be removed.   | —             |
|  | Earth (ground)        | For earthing (grounding) the inverter chassis. This must be earthed (grounded).   | 27            |

### 2.5.2 Terminal layout of the main circuit terminals, wiring of power supply and the motor



#### REMARKS

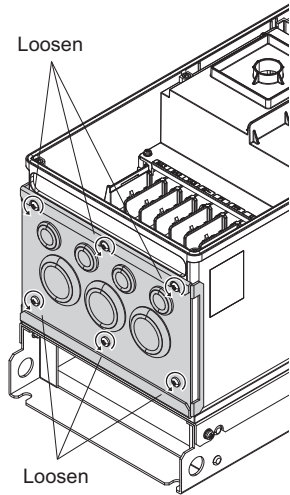
- Make sure the power cables are connected to the R/L1, S/L2, and T/L3. (Phase need not be matched.) Never connect the power cable to the U, V, and W of the inverter. Doing so will damage the inverter.
- Connect the motor to U, V, and W. The phase need to be matched.



### 2.5.3 Handling of the wiring cover

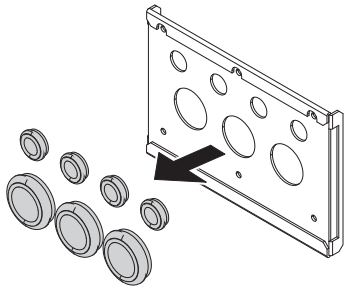
● Removing the wiring cover

- (1) Remove the front cover of the inverter. (Refer to [page 15](#))
- (2) Remove the wiring cover installation screws (hexalobular screws, screw size: M5, screwdriver size: T20, tightening torque: 2.8 to 3.7 N·m) to remove the wiring cover.

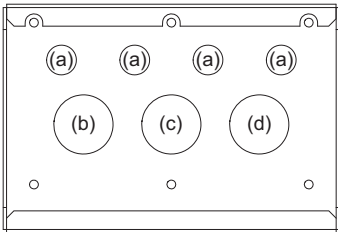


● Removal of protective bushes and wiring layout

- (1) Remove the protective bushes from the wiring cover. (Do not remove the protective bushes from the holes that are not used for wiring of cables.)



- (2) Fix the cables using a cable gland and a nut, according to the diameter of the holes. For the details such as wiring cover hole diameters and recommended cable glands, refer to the following table.



| Inverter capacity                           | Symbol | Recommended layout example   | Hole diameter (mm) | Recommended cable gland                      | Recommended nut                             |
|---|--------|------------------------------|--------------------|--|---|
|   |        |                              |                    | SKINTOP MS-SC-M (Manufactured by LAPP KABEL) | SKINDICHT SM-M (Manufactured by LAPP KABEL) |
| FR-A846-00250(7.5K) to FR-A846-00470(18.5K) | (a)    | Control circuit wiring       | 20.3               | 53112630                                     | 52103020                                    |
|   | (b)    | AC power input wiring        | 40.4               | 53112660                                     | 52103050                                    |
|   | (c)    | Brake unit connection wiring |                    |  |   |
|   | (d)    | Inverter output wiring       |                    |  |   |

**WARNING**

- Always use a waterproof cable gland (IP55 or higher) for the hole from which the protective bush is removed because water may get into the inverter.

## 2.5.4 Applicable cables and the wiring length

Select a recommended cable size to ensure that a voltage drop will be 2% or less.

If the wiring distance is long between the inverter and motor, a voltage drop in the main circuit wires will cause the motor torque to decrease especially at a low speed.

The following table indicates a selection example for the wiring length of 20 m.

**400 V class (440 V input power supply (with 150% rated current for one minute))**

| Applicable inverter model<br>FR-A846-[ ] | Terminal screw size*4 | Tightening torque<br>N·m | Crimping terminal |         | Cable gauge                           |         |         |                            |                  |         |                                       |         |                            |
|--|-----------------------|--------------------------|-------------------|---------|---------------------------------------|---------|---------|----------------------------|------------------|---------|---------------------------------------|---------|----------------------------|
|  |                       |                          |                   |         | HIV cables, etc. (mm <sup>2</sup> )*1 |         |         |                            | AWG/MCM*2        |         | PVC cables, etc. (mm <sup>2</sup> )*3 |         |                            |
|  |                       |                          | R/L1, S/L2, T/L3  | U, V, W | R/L1, S/L2, T/L3                      | U, V, W | P/+, P1 | Earthing (grounding) cable | R/L1, S/L2, T/L3 | U, V, W | R/L1, S/L2, T/L3                      | U, V, W | Earthing (grounding) cable |
| 00250(7.5K)                              | M6                    | 4.4                      | 5.5-6             | 5.5-6   | 3.5                                   | 3.5     | 3.5     | 3.5                        | 12               | 12      | 4                                     | 4       | 4                          |
| 00310(11K)                               | M6                    | 4.4                      | 5.5-6             | 5.5-6   | 5.5                                   | 5.5     | 5.5     | 5.5                        | 10               | 10      | 6                                     | 6       | 10                         |
| 00380(15K)                               | M6                    | 4.4                      | 8-6               | 8-6     | 8                                     | 8       | 8       | 5.5                        | 8                | 8       | 10                                    | 10      | 10                         |
| 00470(18.5K)                             | M6                    | 4.4                      | 14-6              | 8-6     | 14                                    | 8       | 14      | 8                          | 6                | 8       | 16                                    | 10      | 16                         |

\*1 It is the gauge of a cable with the continuous maximum permissible temperature of 75°C (HIV cable (600 V grade heat-resistant PVC insulated wire), etc.). It assumes a surrounding air temperature of 50°C or lower and the wiring distance of 20 m or shorter.

\*2 It is the gauge of a cable with the continuous maximum permissible temperature of 75°C (THHW cable). It assumes a surrounding air temperature of 40°C or lower and the wiring distance of 20 m or shorter. (Selection example for use mainly in the United States.)

\*3 It is the gauge of a cable with the continuous maximum permissible temperature of 70°C (PVC cable). It assumes a surrounding air temperature of 40°C or lower and the wiring distance of 20 m or shorter. (Selection example for use mainly in Europe.)

\*4 The terminal screw size indicates the size of terminal screw for R/L1, S/L2, T/L3, U, V, W, P/+, N/-, P1, and a screw for earthing (grounding).

The line voltage drop can be calculated by the following formula:

$$\text{Line voltage drop [V]} = \frac{\sqrt{3} \times \text{wire resistance [m}\Omega/\text{m}] \times \text{wiring distance [m]} \times \text{current [A]}}{1000}$$

Use a larger diameter cable when the wiring distance is long or when it is desired to decrease the voltage drop (torque reduction) in the low speed range.

### REMARKS

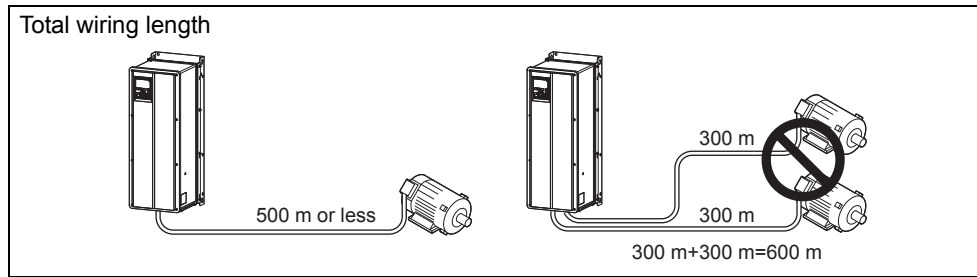
- Tighten the terminal screw to the specified torque.  
A screw that has been tightened too loosely can cause a short circuit or malfunction.  
A screw that has been tightened too tightly can cause a short circuit or malfunction due to the unit breakage.
- Use crimping terminals with insulation sleeves to wire the power supply and motor.

## Main circuit terminals

### (1) Total wiring length

#### ●With induction motor

Connect one or more general-purpose motors within the total wiring length of 500 m. (The wiring length should be 100 m or less under vector control.)



When driving a 400 V class motor by the inverter, surge voltages attributable to the wiring constants may occur at the motor terminals, deteriorating the insulation of the motor. In this case, take one of the following measures.

- Use a "400 V class inverter-driven insulation-enhanced motor" and set **Pr.72 PWM frequency selection** according to the wiring length.

| Wiring length 50 m or shorter | Wiring length 50 m to 100 m | Wiring length longer than 100 m |
|-------------------------------|-----------------------------|---------------------------------|
| 15 (14.5 kHz) or lower        | 9 (9 kHz) or lower          | 4 (4 kHz) or lower              |

- Connect a surge voltage suppression filter (FR-ASF-H/FR-BMF-H) at the output side of the inverter.

#### ●With PM motor

The wiring length should be 100 m or shorter when connecting a PM motor.

Use one PM motor for one inverter. Multiple PM motors cannot be connected to an inverter.

When the wiring length exceeds 50 m for a 400 V class motor driven by an inverter under PM sensorless vector control, set "9" (6 kHz) or less in **Pr.72 PWM frequency selection**.

#### REMARKS

- Especially for long-distance wiring or wiring with shielded cables, the inverter may be affected by a charging current caused by stray capacitances of the wiring, leading to an activation of the overcurrent protection, malfunction of the fast-response current limit operation, or even to an inverter failure. It may also cause a malfunction or fault of the equipment connected ON the inverter output side. Stray capacitances of the wiring differ by the installation condition, use the total wiring length in the table above as reference values. If the fast-response current limit function malfunctions, disable this function. (Refer to **Pr.156 Stall prevention operation selection** on the FR-A800 Instruction Manual (Detailed).)
- A surge voltage suppression filter (FR-ASF-H/FR-BMF-H) can be used under V/F control and Advanced magnetic flux vector control. A sine wave filter (MT-BSL/BSC) can be used under V/F control. Do not use the filters under unspecified controls.
- For the details of **Pr.72 PWM frequency selection**, refer to the FR-A800 Instruction Manual (Detailed).
- Refer to [page 72](#) to drive a 400 V class motor by an inverter.
- The carrier frequency is limited during PM sensorless vector control. (Refer to the FR-A800 Instruction Manual (Detailed).)

## 2.5.5 Earthing (grounding) precautions

Always earth (ground) the motor and inverter.

### (1) Purpose of earthing (grounding)

Generally, an electrical apparatus has an earth (ground) terminal, which must be connected to the ground before use.

An electrical circuit is usually insulated by an insulating material and encased. However, it is impossible to manufacture an insulating material that can shut off a leakage current completely, and actually, a slight current flows into the case. The purpose of earthing (grounding) the case of an electrical apparatus is to prevent operators from getting an electric shock from this leakage current when touching it.

To avoid the influence of external noises, this earthing (grounding) is important to audio equipment, sensors, computers and other apparatuses that handle low-level signals or operate very fast.

### (2) Earthing (grounding) methods and earthing (grounding) work

As described previously, earthing (grounding) is roughly classified into an electrical shock prevention type and a noise-influenced malfunction prevention type. Therefore, these two types should be clearly distinguished, and the following work must be done to prevent the leakage current having the inverter's high frequency components from entering the malfunction prevention type earthing (grounding):

- Whenever possible, use the independent earthing (grounding) for the inverter.

If independent earthing (grounding) (I) is not available, use (II) common earthing (grounding) in the figure below where the inverter is connected with the other equipment at an earthing (grounding) point. Do not use the other equipment's earthing (grounding) cable to earth (ground) the inverter as shown in (III).

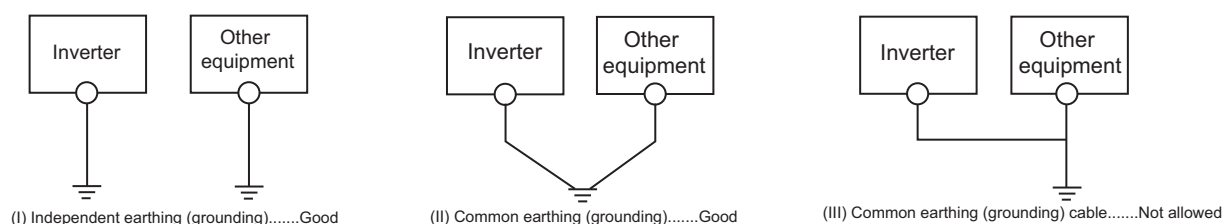
A leakage current containing many high frequency components flows into the earthing (grounding) cables of the inverter and peripheral devices. Because of this, the inverter must be earthed (grounded) separately from EMI-sensitive devices.

In a high building, it may be effective to use the EMI prevention type earthing (grounding) connecting to an iron structure frame, and electric shock prevention type earthing (grounding) with the independent earthing (grounding) together.

- This inverter must be earthed (grounded). Earthing (Grounding) must conform to the requirements of national and local safety regulations and electrical codes. (NEC section 250, IEC 536 class 1 and other applicable standards).

A neutral-point earthed (grounded) power supply in compliance with EN standard must be used.


- Use the thickest possible earthing (grounding) cable. The earthing (grounding) cable should be the size indicated in the table on [page 25](#).
- The earthing (grounding) point should be as close as possible to the inverter, and the earth (ground) wire length should be as short as possible.
- Run the earthing (grounding) cable as far away as possible from the I/O wiring of equipment sensitive to noises and run them in parallel in the minimum distance.



To be compliant with the EU Directive (Low Voltage Directive), refer to [page 105](#).

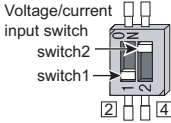
## 2.6 Control circuit

### 2.6.1 Details on the control circuit terminals

Input signal function of the terminals in  can be selected by setting **Pr.178 to Pr.196 (I/O terminal function selection)**. For the details of the control circuit terminal function selection, refer to the FR-A800 Instruction Manual (Detailed).

#### (1) Input signal

| Type          | Terminal Symbol | Terminal name  | Terminal function description   |   | Rated specification   |
|---------------|-----------------|--|---|---|---|
| Contact input | STF             | Forward rotation start   | Turn ON the STF signal to start forward rotation and turn it OFF to stop.   | When the STF and STR signals are turned ON simultaneously, the stop command is given. | Input resistance 4.7 kΩ<br>Voltage when contacts are open: 21 to 27 VDC<br>When contacts are short-circuited: 4 to 6 mADC |
|               | STR             | Reverse rotation start   | Turn ON the STR signal to start reverse rotation and turn it OFF to stop.   |   |   |
|               | STOP            | Start self-holding selection                                     | Turn ON the STOP signal to self-hold the start signal.  |   |   |
|               | RH, RM, RL      | Multi-speed selection  | Multi-speed can be selected according to the combination of RH, RM and RL signals.  |   |   |
|               | JOG             | Jog mode selection   | Turn ON the JOG signal to enable JOG operation (initial setting) and turn ON the start signal (STF or STR) to start JOG operation.  |   | Input resistance 2 kΩ<br>When contacts are short-circuited: 8 to 13 mADC  |
|               |                 | Pulse train input  | Terminal JOG is also used as a pulse train input terminal. To use as a pulse train input terminal, change the <b>Pr.291</b> setting. (maximum input pulse: 100k pulses/s)   |   |   |
|               | RT              | Second function selection  | Turn ON the RT signal to enable the second function.<br>When the second function such as "second torque boost" and "second V/F (base frequency)" is set, turning ON the RT signal enables the selected function.  |   | Input resistance 4.7 kΩ<br>Voltage when contacts are open: 21 to 27 VDC<br>When contacts are short-circuited: 4 to 6 mADC |
|               | MRS             | Output stop  | Turn ON the MRS signal (20ms or more) to stop the inverter output.<br>Use this signal to shut off the inverter output when stopping the motor with an electromagnetic brake.  |   |   |
|               | RES             | Reset  | Use this signal to reset a fault output provided when a protective function is activated. Turn ON the RES signal for 0.1 s or longer, then turn it OFF.<br>In the initial setting, reset is set always-enabled. By setting <b>Pr.75</b> , reset can be set enabled only at fault occurrence. The inverter recovers about 1 s after the reset is released. |   |   |
|               | AU              | Terminal 4 input selection                                       | The terminal 4 function is available only when the AU signal is turned ON.<br>Turning the AU signal ON makes terminal 2 invalid.  |   |   |
|               | CS              | Selection of automatic restart after instantaneous power failure | When the CS signal is left ON, the inverter restarts automatically at power restoration. Note that restart setting is necessary for this operation. In the initial setting, a restart is disabled.  |   |   |
|               | SD              | Contact input common (sink)*2                                    | Common terminal for the contact input terminal (sink logic), terminal FM.   |   | —   |
|               |                 | External transistor common (source)*3                            | Connect this terminal to the power supply common terminal of a transistor output (open collector output) device, such as a programmable controller, in the source logic to avoid malfunction by undesirable current.  |   |   |
|               |                 | 24 VDC power supply common                                       | Common terminal for the 24 VDC power supply (terminal PC, terminal +24)<br>Isolated from terminals 5 and SE.  |   |   |
|               | PC              | External transistor common (sink)*2                              | Connect this terminal to the power supply common terminal of a transistor output (open collector output) device, such as a programmable controller, in the sink logic to avoid malfunction by undesirable currents. (Refer to <a href="#">page 33.</a> )  |   | Power supply voltage range 19.2 to 28.8 VDC<br>Permissible load current 100 mA  |
|               |                 | Contact input common (source)*3                                  | Common terminal for contact input terminal (source logic). (Refer to <a href="#">page 33.</a> )   |   |   |
|               |                 | 24 VDC power supply  | Can be used as 24 VDC 0.1 A power supply.   |   |   |

| Type               | Terminal Symbol | Terminal name                    | Terminal function description   | Rated specification  |
|--------------------|-----------------|----------------------------------|---|--|
| Frequency setting  | 10E             | Frequency setting power supply   | When connecting the frequency setting potentiometer at an initial status, connect it to the terminal 10.  | 10 VDC $\pm 0.4$ V<br>Permissible load current 10 mA   |
|                    | 10              |                                  | Change the input specifications of the terminal 2 using <b>Pr.73</b> when connecting it to the terminal 10E.  | 5 VDC $\pm 0.5$ V<br>Permissible load current 10 mA  |
|                    | 2               | Frequency setting (voltage)      | Inputting 0 to 5 VDC (or 0 to 10 V, 0 to 20 mA) provides the maximum output frequency at 5 V (10 V, 20 mA) and makes input and output proportional. Use <b>Pr.73</b> to switch among input 0 to 5 VDC (initial setting), 0 to 10 VDC, and 0 to 20 mA. Set the voltage/current input switch in the ON position to select current input (0 to 20 mA). *1  | When voltage is input:<br>Input resistance 10 k $\Omega$ $\pm 1$ k $\Omega$<br>Maximum permissible voltage 20 VDC<br>When current is input:<br>Input resistance 245 $\Omega$ $\pm 5$ $\Omega$<br>Permissible maximum current 30 mA |
|                    | 4               | Frequency setting (current)      | Inputting 4 to 20 mADC (or 0 to 5 V, 0 to 10 V) provides the maximum output frequency at 20 mA and makes input and output proportional. This input signal is valid only when the AU signal is ON (terminal 2 input is invalid). Use <b>Pr.267</b> to switch among input 4 to 20 mA (initial setting), 0 to 5 VDC, and 0 to 10 VDC. Set the voltage/current input switch in the OFF position to select voltage input (0 to 5 V/0 to 10 V). *1<br>Use <b>Pr.858</b> to switch terminal functions. |   |
|                    | 1               | Frequency setting auxiliary      | Inputting 0 to $\pm 5$ VDC or 0 to $\pm 10$ VDC adds this signal to terminal 2 or 4 frequency setting signal. Use <b>Pr.73</b> to switch between input 0 to $\pm 5$ VDC and 0 to $\pm 10$ VDC (initial setting). Use <b>Pr.868</b> to switch terminal functions.  |  |
|                    | 5               | Frequency setting common         | Common terminal for frequency setting signal (terminal 2, 1 or 4) and analog output terminal AM, CA. Do not earth (ground).   | —  |
| Thermistor         | 10<br>2         | PTC thermistor input             | For receiving PTC thermistor outputs.<br>When PTC thermistor is valid ( <b>Pr.561</b> $\neq$ "9999"), the terminal 2 is not available for frequency setting.  | Applicable PTC thermistor specification<br>Overheat detection resistance:<br>0.5 to 30 k $\Omega$<br>(Set by <b>Pr.561</b> )   |
| Power supply input | +24             | 24 V external power supply input | For connecting 24 V external power supply.<br>If the 24 V external power supply is connected, power is supplied to the control circuit while the main power circuit is OFF.<br>(Refer to <a href="#">page 37</a> .)   | Input voltage 23 to 25.5 VDC<br>Input current 1.4 A or less  |

\*1 Set **Pr.73**, **Pr.267**, and the voltage/current input switch correctly, then input an analog signal in accordance with the setting. Applying a voltage with the voltage/current input switch ON (current input is selected) or a current with the switch OFF (voltage input is selected) could cause component damage of the inverter or analog circuits of output devices. (For the details, refer to the FR-A800 Instruction Manual (Detailed).)

\*2 The sink logic is initially set for the FM-type inverter.

\*3 The source logic is initially set for the CA-type inverter.

## Control circuit

### (2) Output signal

| Type           | Terminal Symbol         | Terminal name                 | Terminal function description   |  | Rated specification   |
|----------------|-------------------------|-------------------------------|---|--|---|
| Relay          | A1, B1, C1              | Relay output 1 (fault output) | 1 changeover contact output that indicates that an inverter's protective function has been activated and the outputs are stopped.<br>Fault: discontinuity across B and C (continuity across A and C),<br>Normal: continuity across Band C (discontinuity across A and C)  |  | Contact capacity 230 VAC 0.3 A (power factor = 0.4)<br>30 VDC 0.3 A   |
|                | A2, B2, C2              | Relay output 2                | 1 changeover contact output   |  |   |
| Open collector | RUN                     | Inverter running              | Switched to LOW when the inverter output frequency is equal to or higher than the starting frequency (initial value 0.5 Hz). Switched to HIGH during stop or DC injection brake operation.  |  | Permissible load 24 VDC (maximum 27 VDC) 0.1 A (A voltage drop is 2.8 V at maximum while the signal is ON.)<br>LOW is when the open collector output transistor is ON (conducted).<br>HIGH is when the transistor is OFF (not conducted). |
|                | SU                      | Up to frequency               | Switched to LOW when the output frequency is within the set frequency range $\pm 10\%$ (initial value). Switched to HIGH during acceleration/deceleration and at a stop.  | Fault code (4 bits) output.<br>(Refer to the FR-A800 Instruction Manual (Detailed).) |   |
|                | OL                      | Overload warning              | Switched to LOW when stall prevention is activated by the stall prevention function. Switched to HIGH when stall prevention is canceled.  |  |   |
|                | IPF                     | Instantaneous power failure   | Switched to LOW when an instantaneous power failure occurs or when the undervoltage protection is activated.  |  |   |
|                | FU                      | Frequency detection           | Switched to LOW when the inverter output frequency is equal to or higher than the preset detection frequency, and to HIGH when it is less than the preset detection frequency.  |  |   |
|                | SE                      | Open collector output common  | Common terminal for terminals RUN, SU, OL, IPF, FU  |  |   |
| Pulse          | FM<br><small>*1</small> | For meter                     | Outputs a selected monitored item (such as output frequency) among several monitored items. The signal is not output during an inverter reset. The output signal is proportional to the magnitude of the corresponding monitoring item.<br>Use <b>Pr.55</b> , <b>Pr.56</b> , and <b>Pr.866</b> to set full scales for the monitored output frequency, output current, and torque. (Refer to the FR-A800 Instruction Manual (Detailed).) | Output item:<br>Output frequency (initial setting)                                   | Permissible load current 2 mA<br>For full scale 1440 pulses/s   |
|                |                         | NPN open collector output     |   | This terminal can be used for open collector outputs by setting <b>Pr.291</b> .      | Maximum output pulse 50k pulses/s<br>Permissible load current 80 mA   |
| Analog         | AM                      | Analog voltage output         |   |  | Output item:<br>Output frequency (initial setting)  |
|                | CA<br><small>*2</small> | Analog current output         | Load impedance 200 $\Omega$ to 450 $\Omega$<br>Output signal 0 to 20 mADC   |  |   |

\*1 Terminal FM is provided in the FM-type inverter.

\*2 Terminal CA is provided in the CA-type inverter.

**(3) Communication**

| Type   | Terminal Symbol  |      | Terminal name                  | Terminal function description  |  |
|--------|------------------|------|--------------------------------|--|--|
| RS-485 | —                |      | PU connector                   | With the PU connector, communication can be made through RS-485. (For connection on a 1:1 basis only) <ul style="list-style-type: none"><li>Conforming standard: EIA-485 (RS-485)</li><li>Transmission format: Multidrop link</li><li>Communication speed: 4800 to 115200 bps</li><li>Wiring length: 500 m</li></ul> |  |
|        | RS-485 terminals | TXD+ | Inverter transmission terminal | The RS-485 terminals enables the communication by RS-485. <ul style="list-style-type: none"><li>Conforming standard: EIA-485 (RS-485)</li><li>Transmission format: Multidrop link</li><li>Communication speed: 300 to 115200 bps</li><li>Overall length: 500 m</li></ul>   |  |
|        |                  | TXD- |                                |  |  |
|        |                  | RXD+ | Inverter reception terminal    |  |  |
|        |                  | RXD- |                                |  |  |
|        |                  | SG   | Earthing (grounding)           |  |  |
| USB    | —                |      | USB A connector                | <ul style="list-style-type: none"><li>Interface: Conforms to USB1.1 (USB2.0 full-speed compatible)</li><li>Transmission speed: 12 Mbps (Refer to <a href="#">page 45.</a>)</li></ul>   |  |
|        |                  |      | USB B connector                |  |  |

**(4) Safety stop signal**

For the safety stop function, refer to [page 39](#).

| Terminal Symbol | Terminal name                                 | Terminal function description  | Rated specification   |
|-----------------|---|--|---|
| S1              | Safety stop input (Channel 1)                 | The terminals S1 and S2 are used for the safety stop input signal for the safety relay module. The terminals S1 and S2 are used at the same time (dual channel).<br>Inverter output is shutoff by shortening/opening between terminals S1 and SIC, or between S2 and SIC.<br>In the initial status, terminals S1 and S2 are shorted with the terminal PC by shorting wires. The terminal SIC is shorted with the terminal SD. Remove the shorting wires and connect the safety relay module when using the safety stop function.                       | Input resistance 4.7 kΩ<br>Input current 4 to 6 mADC (with 24 VDC input)  |
| S2              | Safety stop input (Channel 2)                 |  |   |
| SIC             | Safety stop input terminal common             | Common terminal for terminals S1 and S2.   | —   |
| SO              | Safety monitor output (open collector output) | Indicates the safety stop input signal status.<br>Switched to LOW when the status is other than the internal safety circuit failure. Switched to HIGH during the internal safety circuit failure status.<br>(LOW is when the open collector output transistor is ON (conducted). HIGH is when the transistor is OFF (not conducted).)<br>Refer to the Safety stop function instruction manual (BCN-A23228-001) when the signal is switched to HIGH while both terminals S1 and S2 are open. (Please contact your sales representative for the manual.) | Permissible load<br>D24 VDC (27 VDC at maximum), 0.1 A (A voltage drop is 3.4 V at maximum while the signal is ON.)<br>(A voltage drop is 3.4 V at maximum while the signal is ON.) |
| SOC             | Safety monitor output terminal common         | Common terminal for terminal SO.   | —   |



## 2.6.2 Control logic (sink/source) change

Change the control logic of input signals as necessary.

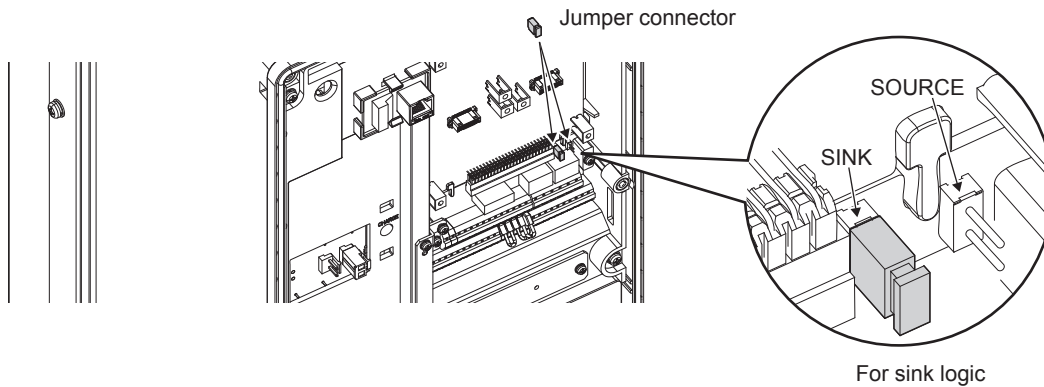
To change the control logic, change the jumper connector position on the control circuit board.

Connect the jumper connector to the connector pin of the desired control logic.

The control logic of input signals is initially set to the sink logic (SINK) for the FM type.

The control logic of input signals is initially set to the source logic (SOURCE) for the CA type.

(The output signals may be used in either the sink or source logic independently of the jumper connector position.)



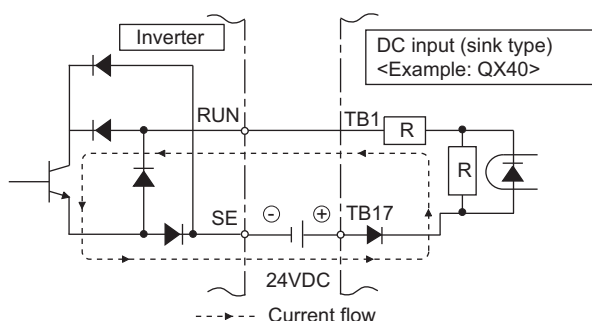
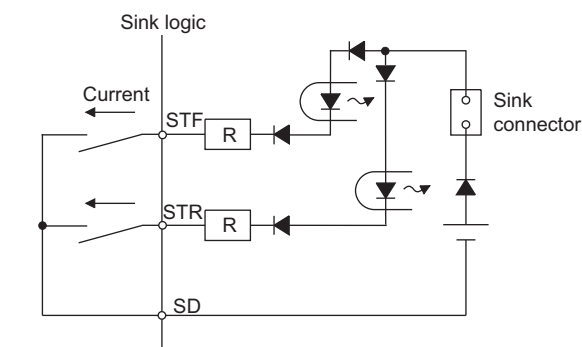
### REMARKS

- Make sure that the jumper connector is installed correctly.
- Never change the control logic while power is ON.

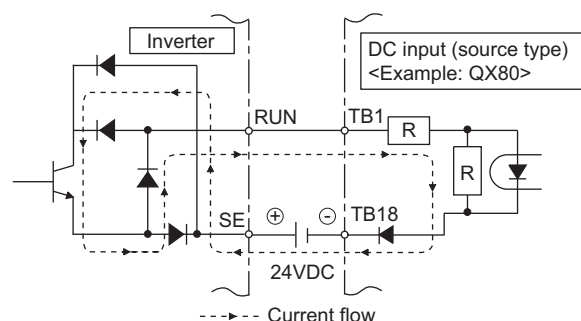
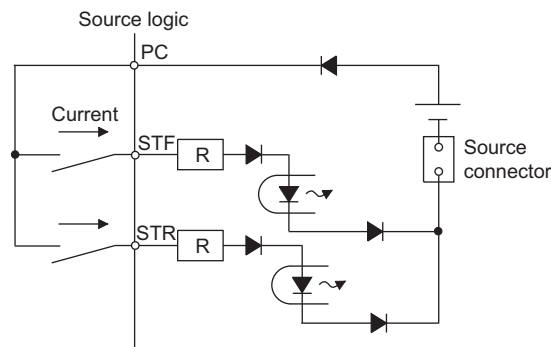
**(1) Sink logic and source logic**

- In the sink logic, a signal switches ON when a current flows from the corresponding signal input terminal. Terminal SD is common to the contact input signals. Terminal SE is common to the open collector output signals.
- In the source logic, a signal switches ON when a current flows into the corresponding signal input terminal. Terminal PC is common to the contact input signals. Terminal SE is common to the open collector output signals.

● Current flow concerning the input/output signal when sink logic is selected



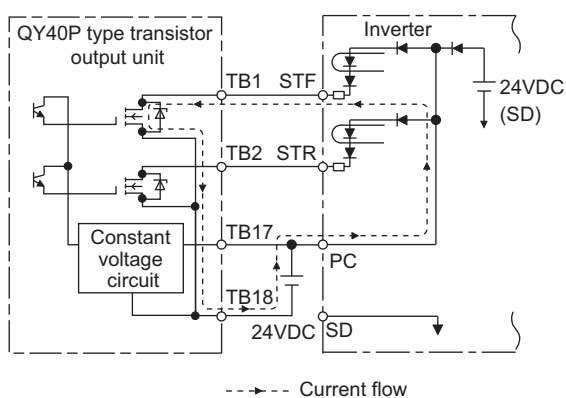
● Current flow concerning the input/output signal when source logic is selected



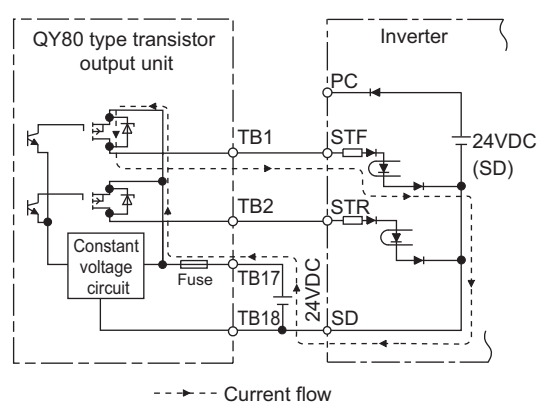
- When using an external power supply for transistor output

**Sink logic**

Use the terminal PC as a common terminal, and perform wiring as shown below. (Do not connect terminal SD of the inverter with the terminal 0 V of the external power supply. When using terminals PC-SD as a 24 VDC power supply, do not install an external power supply in parallel with the inverter. Doing so may cause a malfunction in the inverter due to undesirable currents.)

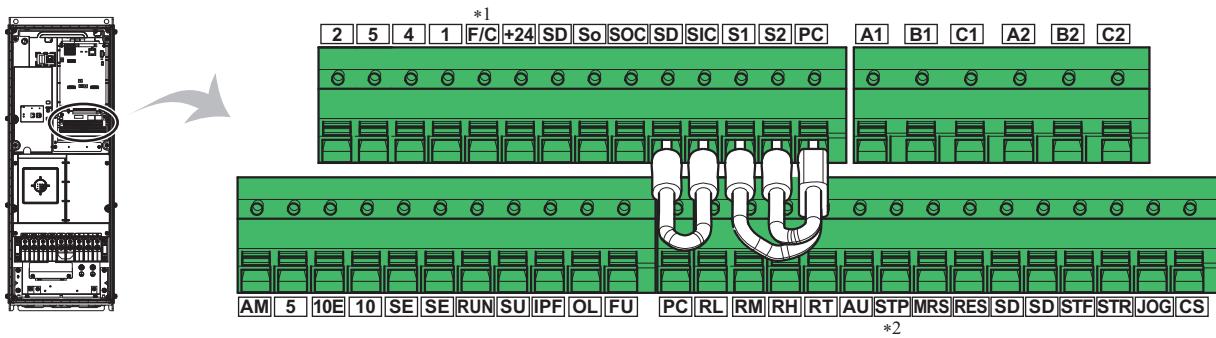
**Source logic**

Use the terminal SD as a common terminal, and perform wiring as shown below. (Do not connect terminal PC of the inverter with the terminal +24 V of the external power supply. When using terminals PC-SD as a 24 VDC power supply, do not install an external power supply in parallel with the inverter. Doing so may cause a malfunction in the inverter due to undesirable currents.)



## 2.6.3 Wiring of control circuit

### (1) Control circuit terminal layout



\*1 The terminal functions as the terminal FM for the FM type, and as the terminal CA for the CA type.

\*2 Represents the terminal STOP.

### (2) Wiring method

#### • Power supply connection

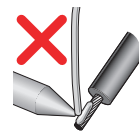
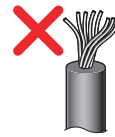
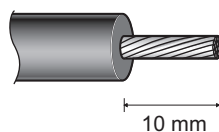
For the control circuit wiring, strip off the sheath of a cable, and use it with a blade terminal. For a single wire, strip off the sheath of the wire and apply directly.

Insert the blade terminal or the single wire into a socket of the terminal.

- 1) Strip off the sheath for the below length. If the length of the sheath peeled is too long, a short circuit may occur with neighboring wires. If the length is too short, wires might come off.

Wire the stripped cable after twisting it to prevent it from becoming loose. In addition, do not solder it.

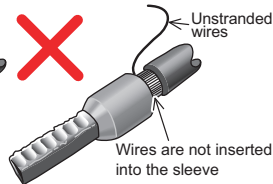
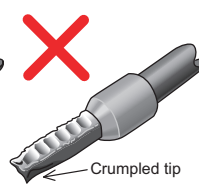
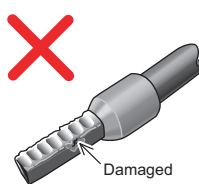
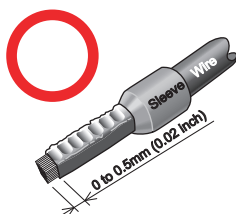
Cable stripping size



- 2) Crimp the blade terminal.

Insert wires to a blade terminal, and check that the wires come out for about 0 to 0.5 mm from a sleeve.

Check the condition of the blade terminal after crimping. Do not use a blade terminal of which the crimping is inappropriate, or the face is damaged.



- Blade terminals commercially available (as of February 2012)

Phoenix Contact Co., Ltd.

| Cable gauge (mm <sup>2</sup> ) | Blade terminal model   |                           |                      | Crimping tool model |
|--------------------------------|------------------------|---------------------------|----------------------|---------------------|
|                                | With insulation sleeve | Without insulation sleeve | For UL wire*1        |                     |
| 0.3                            | AI 0,5-10WH            | -                         | -                    | CRIMPFOX 6          |
| 0.5                            | AI 0,5-10WH            | -                         | AI 0,5-10WH-GB       |                     |
| 0.75                           | AI 0,75-10GY           | A 0,75-10                 | AI 0,75-10GY-GB      |                     |
| 1                              | AI 1-10RD              | A 1-10                    | AI 1-10RD/1000GB     |                     |
| 1.25, 1.5                      | AI 1,5-10BK            | A 1,5-10                  | AI 1,5-10BK/1000GB*2 |                     |
| 0.75 (for two wires)           | AI-TWIN 2 × 0,75-10GY  | -                         | -                    |                     |

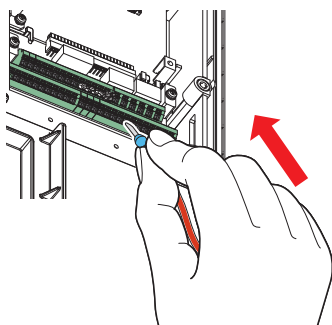
\*1 A blade terminal with an insulation sleeve compatible with the MTW wire which has a thick wire insulation.

\*2 Applicable for the terminal A1, B1, C1, A2, B2, C2.

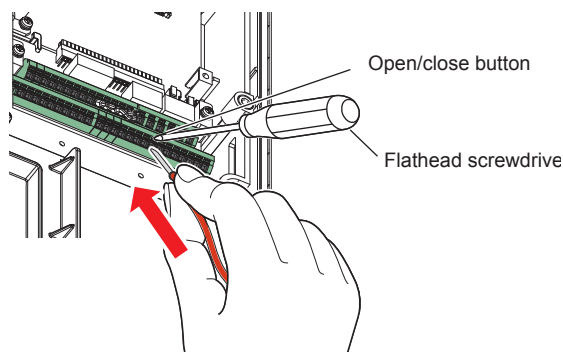
NICHIFU Co., Ltd.

| Cable gauge (mm <sup>2</sup> ) | Blade terminal product number | Insulation product number | Crimping tool product number |
|--------------------------------|-------------------------------|---------------------------|------------------------------|
| 0.3 to 0.75                    | BT 0.75-11                    | VC 0.75                   | NH 69                        |

## 3) Insert the wires into a socket.



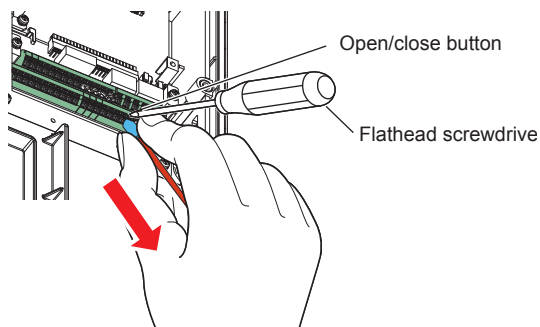
When using a single wire or stranded wires without a blade terminal, push the open/close button all the way down with a flathead screwdriver, and insert the wire.

**REMARKS**

- When using stranded wires without a blade terminal, twist enough to avoid short circuit with a nearby terminals or wires.
- Place the flathead screwdriver vertical to the open/close button. In case the blade tip slips, it may cause an inverter damage or injury.

## ● Wire removal

Pull the wire while pushing the open/close button all the way down firmly with a flathead screwdriver.

**REMARKS**

- Pulling out the wire forcefully without pushing the open/close button all the way down may damage the terminal block.
- Use a small flathead screwdriver (tip thickness: 0.4 mm/tip width: 2.5 mm).

If a flathead screwdriver with a narrow tip is used, terminal block may be damaged.

Commercially available products (as of February 2012)

| Name   | Model               | Manufacturer              |
|--------|---------------------|---------------------------|
| Driver | SZF<br>0- 0,4 × 2,5 | Phoenix Contact Co., Ltd. |

- Place the flathead screwdriver vertical to the open/close button. In case the blade tip slips, it may cause an inverter damage or injury.

## Control circuit

### (3) Common terminals of the control circuit (SD, PC, 5, SE)

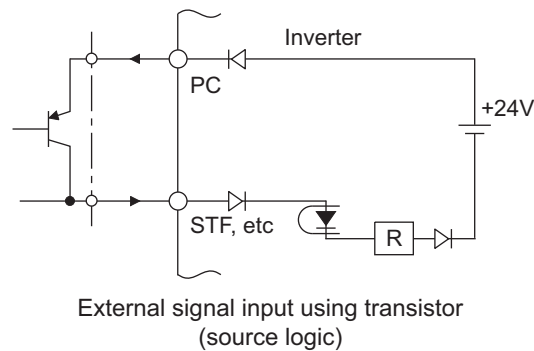
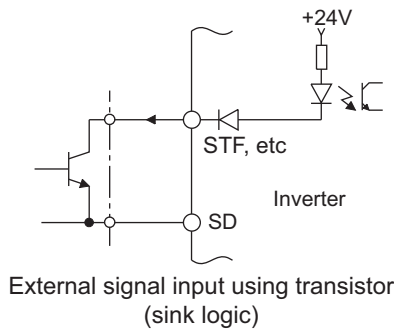
- Terminals SD (sink logic), PC (source logic), 5, and SE are common terminals (0V) for I/O signals. (All common terminals are isolated from each other.) Do not earth (ground) these terminals. Avoid connecting the terminal SD (sink logic) with 5, the terminal PC (source logic) with 5, and the terminal SE with 5.
- In the sink logic, terminal SD is a common terminal for the contact input terminals (STF, STR, STOP, RH, RM, RL, JOG, RT, MRS, RES, AU, CS) and the pulse train output terminal (FM\*1). The open collector circuit is isolated from the internal control circuit by photocoupler.
- In the source logic, terminal PC is a common terminal for the contact input terminals (STF, STR, STOP, RH, RM, RL, JOG, RT, MRS, RES, AU, CS). The open collector circuit is isolated from the internal control circuit by photocoupler.
- Terminal 5 is a common terminal for the frequency setting terminals (2, 1 or 4) and the analog output terminals (AM, CA\*2). It should be protected from external noise using a shielded or twisted cable.
- Terminal SE is a common terminal for the open collector output terminals (RUN, SU, OL, IPF, FU). The contact input circuit is isolated from the internal control circuit by photocoupler.

\*1 Terminal FM is provided in the FM-type inverter.

\*2 Terminal CA is provided in the CA-type inverter.

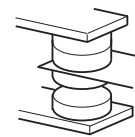
### (4) Signal inputs by contactless switches

The contact input terminals of the inverter (STF, STR, STOP, RH, RM, RL, JOG, RT, MRS, RES, AU, CS) can be controlled using a transistor instead of a contact switch as shown below.

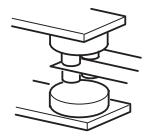


## 2.6.4 Wiring precautions

- It is recommended to use a cable of 0.75 mm<sup>2</sup> for the connection to the control circuit terminals.
- The wiring length should be 30 m (200 m for the terminal FM) at the maximum.
- Use two or more parallel micro-signal contacts or twin contacts to prevent contact faults when using contact inputs since the control circuit input signals are micro-currents.
- To suppress EMI, use shielded or twisted cables for the control circuit terminals and run them away from the main and power circuits (including the 200 V relay sequence circuit). For the cables connected to the control circuit terminals, connect their shields to the common terminal of the connected control circuit terminal. When connecting an external power supply to the terminal PC, however, connect the shield of the power supply cable to the negative side of the external power supply. Do not directly earth (ground) the shield to the enclosure, etc.
- Do not apply a voltage to the contact input terminals (STF, etc.) of the control circuit.
- Always apply a voltage to the fault output terminals (A1, B1, C1, A2, B2, C2) via a relay coil, lamp, etc.



Micro signal contacts



Twin contacts

## 2.6.5 When supplying 24 V external power to the control circuit

Connect the 24 V external power supply across terminals +24 and SD. The 24 V external power supply enables I/O terminal ON/OFF operation, operation panel displays, control functions, and communication during communication operation even at power-OFF of inverter's main circuit power supply. When the main circuit power supply is turned ON, the power supply source changes from the 24 V external power supply to the main circuit power supply.

### (1) Specification of the applicable 24 V external power supply

| Item          | Rated specification |
|---------------|---------------------|
| Input voltage | 23 to 25.5 VDC      |
| Input current | 1.4 A or less       |

Commercially available products (as of October 2013)

| Model  | Manufacturer      |
|--|-------------------|
| S8JX-N05024C *1<br>Specifications: Capacity 50 W, output voltage (DC) 24 V, output current 2.1 A<br>Installation method: Front installation with cover<br><br>Or<br><br>S8VS-06024 *1<br>Specifications: Capacity 60 W, output voltage (DC) 24 V, output current 2.5 A<br>Installation method: DIN rail installation | OMRON Corporation |

\*1 For the latest information about OMRON power supply, contact OMRON corporation.

### (2) Starting and stopping the 24 V external power supply operation

- Supplying 24 V external power while the main circuit power is OFF starts the 24 V external power supply operation. Likewise, turning OFF the main circuit power while supplying 24 V external power starts the 24 V external power supply operation.
- Turning ON the main circuit power stops the 24 V external power supply operation and enables the normal operation.

#### REMARKS

- When the 24 V external power is supplied while the main circuit power supply is OFF, the inverter operation is disabled.
- In the initial setting, when the main power supply is turned ON during the 24 V external power supply operation, a reset is performed in the inverter, then the power supply changes to the main circuit power supply. (The reset can be disabled using **Pr.30**. (For the details of **Pr.30**, refer to the Instruction Manual (Detailed) of the FR-A800 series.))

### (3) Confirming the 24 V external power supply input

- During the 24 V external power supply operation, "EV" flickers on the operation panel.



- During the 24 V external power supply operation, the 24 V external power supply operation signal (EV) is output. To use the EV signal, set "68 (positive logic) or 168 (negative logic)" in one of **Pr.190 to Pr.196 (output terminal function selection)** to assign function to an output terminal.

### (4) Operation while the 24 V external power is supplied

- Faults history and parameters can be read and parameters can be written (when the parameter write from the operation panel is enabled) using the operation panel keys.
- The safety stop function is invalid during the 24 V external power supply operation.
- During the 24 V external power supply operation, monitored items and signals related to inputs to main circuit power supply, such as output current, converter output voltage, and IPF signal, are invalid.
- The faults, which have occurred when the main circuit power supply is ON, continue to be output after the power supply is changed to the 24 V external power supply. Perform the inverter reset or turn OFF then ON the power to reset the faults.
- The retry function is invalid for all faults during the 24 V external power supply.
- If the power supply changes from the main circuit power supply to the 24 V external power supply while measuring the main circuit capacitor's life, the measurement completes after the power supply changes back to the main circuit power supply (**Pr.259** = "3").
- The output data is retained when "1 or 11" is set in **Pr.495 Remote output selection**.

#### REMARKS

- Inrush current equal to or higher than the 24 V external power supply may flow at power-ON. Confirm that the power supply and other devices are not affected by the inrush current and the voltage drop caused by it. Depending on the power supply, the inrush current protection may be activated to disable the power supply. Select the power supply and capacity carefully.
- When the wiring length between the external power supply and the inverter is long, the voltage often drops. Select the appropriate wiring size and length to keep the voltage in the rated input voltage range.
- In a serial connection of several inverters, the current increases when it flows through the inverter wiring near the power supply. The increase of the current causes voltage to drop further. When connecting different inverters to different power supplies, use the inverters after confirming that the input voltage of each inverter is within the rated input voltage range. Depending on the power supply, the over current protection may be activated to disable the power supply. Select the power supply and capacity carefully.
- "E.SAF or E.P24" may appear when the start-up time of the 24 V power supply is too long (less than 1.5 V/s) in the 24 V external power supply operation.
- "E.P24" may appear when the 24 V external power supply input voltage is low. Check the external power supply input.
- Do not touch the control circuit terminal block (circuit board) during the 24 V power supply operation (when conducted). Otherwise you may get an electric shock or burn.

## 2.6.6 Safety stop function

### (1) Function description

The terminals related to the safety stop function are shown below.

| Terminal symbol | Terminal function description   |  |
|-----------------|---|--|
| S1 *1           | For input of the safety stop channel 1.   | Between S1 and SIC, S2 and SIC<br>Open: In safety stop mode<br>Short: Other than the safety stop mode. |
| S2 *1           | For input of the safety stop channel 2.   |  |
| SIC *1          | Common terminal for S1 and S2.  |  |
| SO              | Outputs when an alarm or failure is detected.<br>The signal is output when no internal safety circuit failure*2 exists. | OFF: Internal safety circuit failure*2<br>ON: No internal safety circuit failure*2                     |
| SOC             | Open collector output (terminal SO) common  |  |

\*1 In the initial status, terminals S1 and PC, S2 and PC, and SIC and SD are respectively shorted with shorting wires. To use the safety stop function, remove all the shortening wires, and then connect to the safety relay module as shown in the following connection diagram.

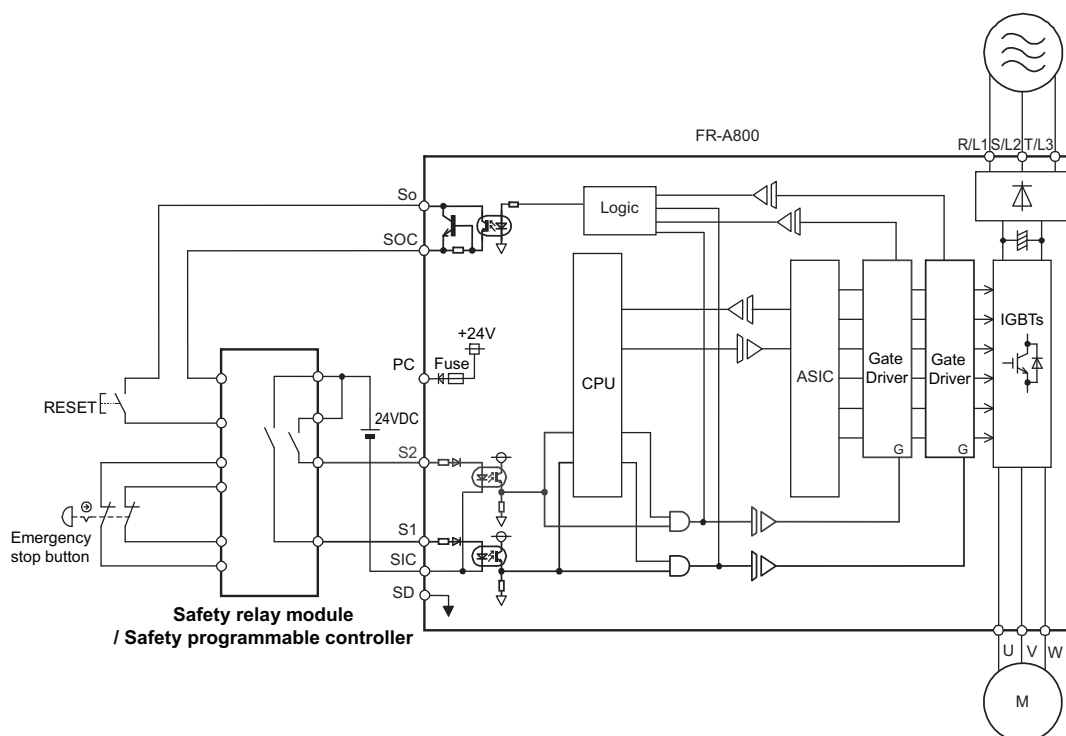
\*2 At an internal safety circuit failure, the operation panel displays one of the faults shown on the next page.

#### REMARKS

- Use the terminal SO to output a fault and to prevent restarting of the inverter. The signal cannot be used as safety stop input terminal to other devices.

### (2) Connection diagram

To prevent automatic restart after a fault occurrence, connect the reset button of a safety relay module or a safety programmable controller across the terminals SO and SOC. The reset button acts as the feedback input for the safety relay module or the safety programmable controller.





## Control circuit

### (3) Safety stop function operation

| Input power | Input signal |        | Internal safety circuit failure *1 | Output signal | Inverter running status     |
|-------------|--------------|--------|------------------------------------|---------------|-----------------------------|
|             | S1-SIC       | S2-SIC |                                    | SO *3         |                             |
| OFF         | -            | -      | -                                  | OFF           | Output shutoff (Safe state) |
| ON          | Short        | Short  | Without                            | ON            | Drive enabled               |
|             |              |        | With                               | OFF           | Output shutoff (Safe state) |
|             | Open         | Open   | Without *2                         | ON            | Output shutoff (Safe state) |
|             |              |        | With                               | OFF           | Output shutoff (Safe state) |
|             | Short        | Open   | N/A                                | OFF           | Output shutoff (Safe state) |
|             | Open         | Short  | N/A                                | OFF           | Output shutoff (Safe state) |

N/A denotes a condition where circuit fault does not apply.

\*1 At an internal safety circuit failure, the operation panel displays one of the faults shown in the following table.

\*2 SA is displayed when both of the S1 and S2 signals are in open status and no internal safety circuit failure exists.

\*3 ON: Transistor used for an open collector output is conducted.

OFF: Transistor used for an open collector output is not conducted.

### (4) Internal safety circuit failure

At an internal safety circuit failure, the terminal SO turns OFF.



The following faults can cause the internal safety circuit failure (terminal SO - OFF).

| Fault record                                | Operation panel indication | Fault record                     | Operation panel indication |
|---|----------------------------|----------------------------------|----------------------------|
| Option fault                                | E.OPT                      | Safety circuit fault             | E.SAF                      |
| Communication option fault                  | E.OP1                      | Overspeed occurrence             | E.OS                       |
| Parameter storage device fault              | E.PE                       | Speed deviation excess detection | E.OSD                      |
| Retry count excess                          | E.RET                      | Signal loss detection            | E.ECT                      |
| Parameter storage device fault              | E.PE2                      | Excessive position fault         | E.OD                       |
| Operation panel power supply short circuit  | E.CTE                      | Brake sequence fault             | E.MB1 to E.MB7             |
| RS-485 terminals power supply short circuit |                            | Encoder phase fault              | E.EP                       |
| 24 VDC power fault                          | E.P24                      | CPU fault                        | E.CPU                      |
|   |                            |                                  | E.5 to E.7                 |
|   |                            | Internal circuit fault           | E.13                       |

For more details, refer to the Safety stop function instruction manual (BCN-A23228-001). (Find a PDF copy of this manual in the CD-ROM enclosed with the product.)

## 2.7 Operation panel (FR-DU08-01)

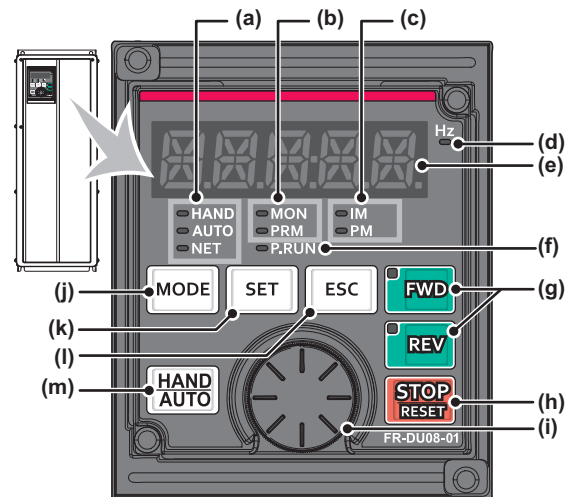
### 2.7.1 Differences with the FR-DU08

| Item                           | FR-DU08   | FR-DU08-01   |
|--------------------------------|---|--|
| Applicable model               | FR-A800   | FR-A806  |
| Protective structure           | IP40 (except for the PU connector)  | IP55 (except for the PU connector)   |
| Outline dimension (W×H×D [mm]) | 72×78.5×17  | 80×96×19   |
| Number of fixing screws        | 2   | 4  |
| Operation mode indicator       | PU/EXT  | HAND/AUTO  |
| Operation key                  | PU/EXT key<br> | HAND/AUTO key<br> |
| Installation on the enclosure  | Available   | Not available  |

## 2.7.2 Components of the operation panel (FR-DU08-01)

The operation panel (FR-DU08-01) is an IP55 compatible model dedicated to the FR-A806 series.

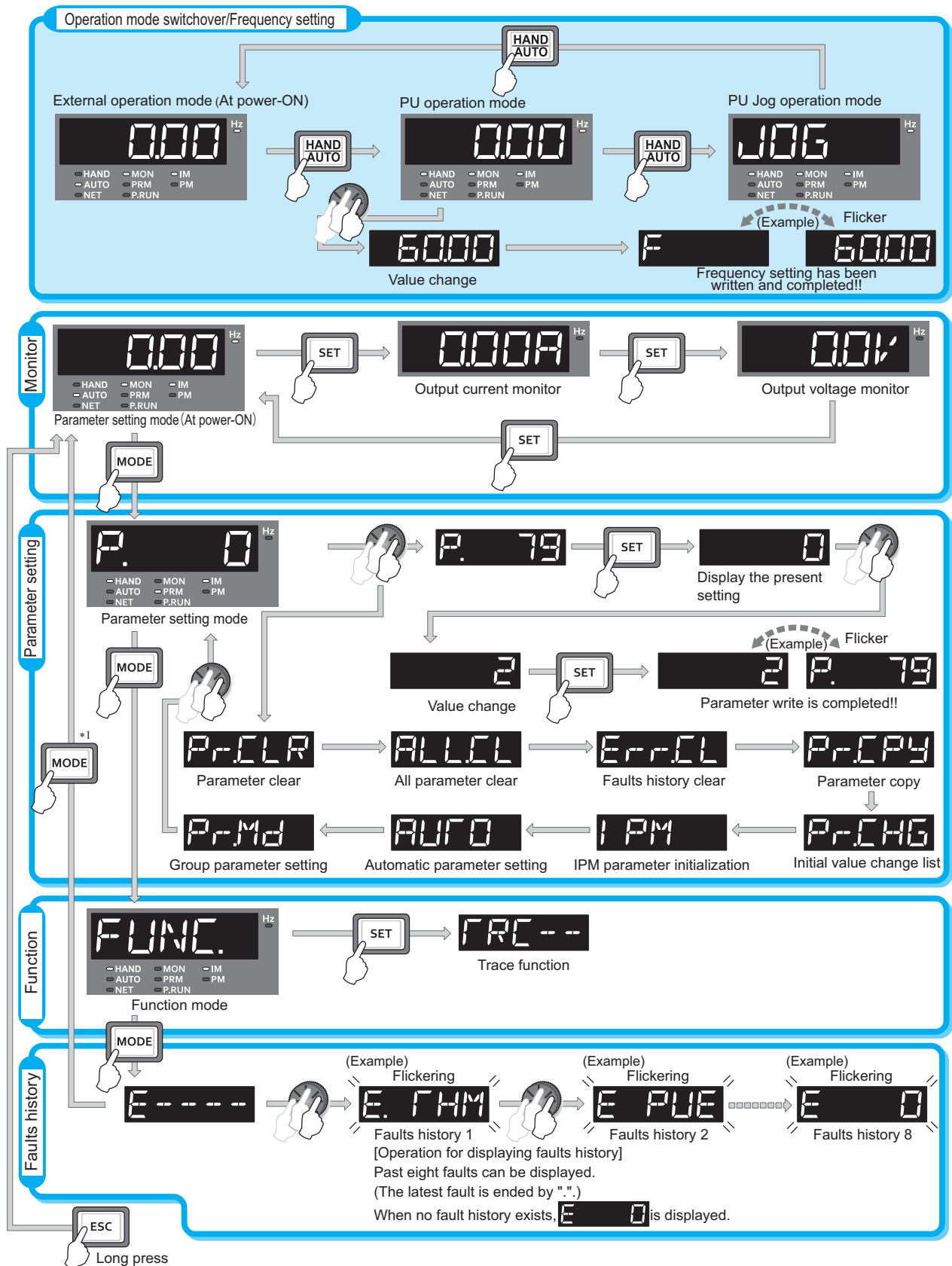
(It cannot be installed to the standard model of FR-A800 series.)



| No. | Component | Name                             | Description  |
|-----|-----------|----------------------------------|--|
| (a) |           | Operation mode indicator         | HAND: Lit to indicate the PU operation mode.<br>AUTO: Lit to indicate the External operation mode. (Lit at power-ON in the initial setting.)<br>NET: Lit to indicate the Network operation mode.<br>HAND and AUTO: Lit to indicate the External/PU combined operation mode 1 or 2.   |
| (b) |           | Operation panel status indicator | MON: Lit to indicate the monitoring mode. The indicator quickly flickers twice to indicate activation of the protective function.<br>PRM: Lit to indicate the parameter setting mode.  |
| (c) |           | Control motor indicator          | IM: Lit to indicate the induction motor control.<br>PM: Lit to indicate the PM sensorless vector control.<br>The indicator flickers when test operation is selected.   |
| (d) |           | Frequency unit indicator         | Lit to indicate frequency. (Flickers when the set frequency is displayed in the monitor.)  |
| (e) |           | Monitor (5-digit LED)            | Shows the frequency, parameter number, etc.<br>(Using Pr.52, Pr.774 to Pr.776, the monitored item can be changed.)   |
| (f) |           | PLC function indicator           | Lit to indicate that the sequence program can be executed.   |
| (g) |           | FWD key, REV key                 | FWD key: Starts forward rotation. The LED is lit during forward operation.<br>REV key: Starts reverse rotation. The LED is lit during reverse operation.<br>The LED flickers under the following conditions.<br>• When the frequency command is not given even if the forward/reverse command is given.<br>• When the frequency command is the starting frequency or lower.<br>• When the MRS signal is being input. |
| (h) |           | STOP/RESET key                   | Stops the operation commands.<br>Resets the inverter when the protection function is activated.  |
| (i) |           | Setting dial                     | The setting dial of the Mitsubishi inverters. The setting dial is used to change the frequency and parameter settings.<br>Press the setting dial to perform the following operations:<br>• To display a set frequency in the monitoring mode (the setting can be changed using Pr.992.)<br>• To display the present setting during calibration<br>• To display a fault history number in the faults history mode     |
| (j) |           | MODE key                         | Switches to different modes.<br><br>Switches to the easy setting mode by pressing simultaneously with .<br>Holding this key for 2 seconds locks the operation. The key lock is invalid when Pr.161="0 (initial setting)". (Refer to FR-A800 the Instruction Manual (Detailed).)  |
| (k) |           | SET key                          | Enters each setting.<br>If pressed during operation, the monitored item  changes.<br>(Using Pr.52 and Pr.774-Pr.776, the monitored item can be changed.)   |
| (l) |           | ESC key                          | Goes back to the previous display.<br>Holding this key for a longer time changes the mode back to the monitor mode.  |
| (m) |           | HAND/AUTO key                    | Switches between the PU mode and the External operation mode.<br><br>Switches to the easy setting mode by pressing simultaneously with .<br>Cancels the PU stop also.  |

## 2.7.3 Basic operation of the operation panel

For the details of each function, refer to the FR-A800 Instruction Manual (Detailed).

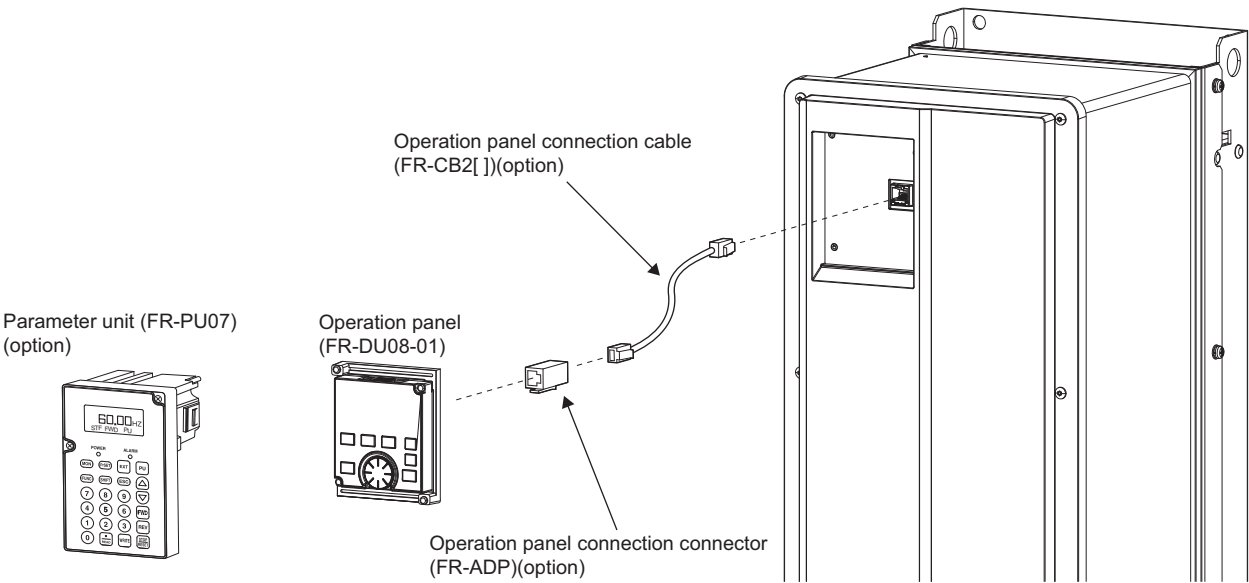


# 2.8 Communication connectors and terminals

## 2.8.1 PU connector

### (1) Mounting the operation panel (FR-DU08-01) or parameter unit (FR-PU07)

- With a connection cable, the operation panel (FR-DU08-01) or the parameter unit (FR-PU07) can be connected to the inverter.  
Use the option FR-CB2[ ], or connectors and cables available on the market.  
(To mount the operation panel (FR-DU08-01), the optional connector (FR-ADP) is required.)  
Securely insert one end of the connection cable until the stoppers are fixed.
- If the operation panel is removed from the inverter, the inverter does not conform to IP55.



#### REMARKS

- Refer to the following table when fabricating the cable on the user side. Keep the total cable length within 20 m.
- Commercially available products (as of February 2012)

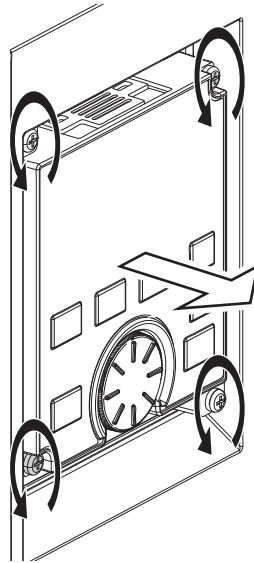
| Name                | Model                                | Manufacturer                      |
|---------------------|--------------------------------------|-----------------------------------|
| Communication cable | SGLPEV-T (Cat5e/300 m)<br>24AWG × 4P | Mitsubishi Cable Industries, Ltd. |
| RJ-45 connector     | 5-554720-3                           | Tyco Electronics                  |

### (2) Communication operation

- Using the PU connector enables communication operation from a personal computer, etc. When the PU connector is connected with a personal, FA or other computer by a communication cable, a user program can run to monitor the inverter or read and write parameters.  
Communication can be performed with the Mitsubishi inverter protocol (computer link operation).  
For the details, refer to the FR-A800 Instruction Manual (Detailed).
- If the operation panel is removed from the inverter, the inverter does not conform to IP55.

### (3) Removal and reinstallation of the operation panel

- Loosen the four fixing screws on the operation panel and pull out the operation panel. (These screws cannot be removed.)

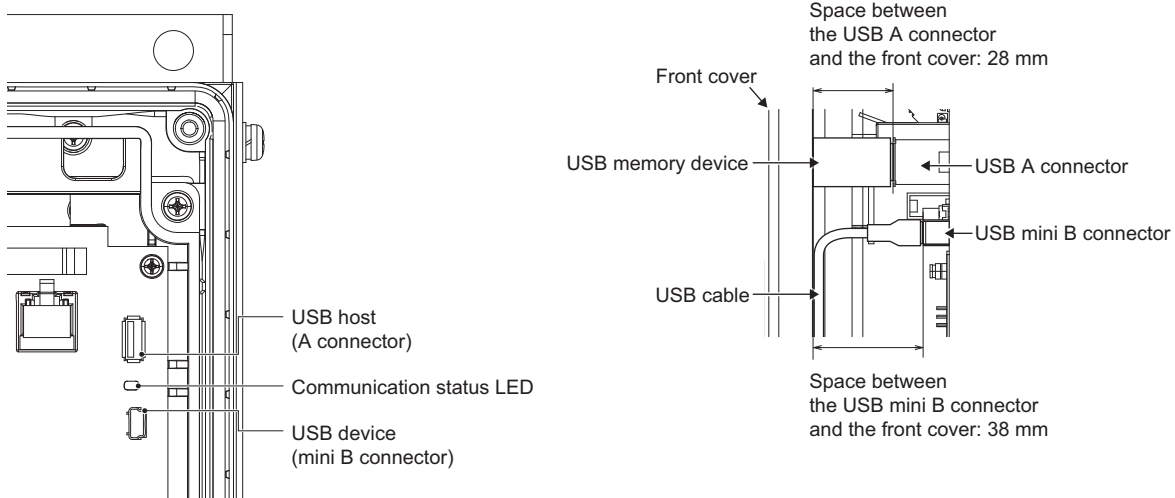


- To reinstall the operation panel, align its connector on the back with the PU connector of the inverter, and insert the operation panel. After confirming that the operation panel is fit securely, tighten the screws in the diagonal order. (Tightening torque: 0.39 to 0.49 N·m)

## 2.8.2 USB connector

### (1) Connection to the USB connectors

- Before removing a front cover, check to make sure that the indication of the inverter operation panel is OFF, wait for at least 10 minutes after the power supply has been switched OFF, and check that there is no residual voltage using a tester or the like.
- Connect a USB memory device to the USB A connector, and a USB cable to the USB mini B connector. Refer to the following figure for the clearance required for the USB memory device or the USB cable. They must fit in the space between each connector and the front cover.



### (2) USB host communication

|                              |                            |  |
|------------------------------|----------------------------|--|
| <b>Interface</b>             |                            | Conforms to USB1.1   |
| <b>Transmission speed</b>    |                            | 12 Mbps  |
| <b>Wiring length</b>         |                            | Maximum 5 m  |
| <b>Connector</b>             |                            | USB A connector (receptacle)                                   |
| <b>Compatible USB memory</b> | <b>Format</b>              | FAT32  |
|                              | <b>Capacity</b>            | 1 GB or more (used in the recorder mode of the trace function) |
|                              | <b>Encryption function</b> | Not available  |

- Different inverter data can be saved in a USB memory device.

The USB host communication enables the following functions.

| Function               | Description   |
|------------------------|---|
| Parameter copy         | <ul style="list-style-type: none"> <li>• Copies the parameter setting from the inverter to the USB memory device. The maximum of 99 parameter settings can be saved in a USB memory device.</li> <li>• The parameter setting data copied in the USB memory device can be copied to other inverters. This function is useful in backing up the parameter setting or for sharing the parameter setting among multiple inverters.</li> <li>• The parameter setting file can be copied onto a personal computer from the USB memory device and edited using FR Configurator 2.</li> </ul> |
| Trace                  | <ul style="list-style-type: none"> <li>• The monitored data and output status of the signals can be saved in a USB memory device.</li> <li>• The saved data can be imported to FR Configurator 2 to diagnose the operating status of the inverter.</li> </ul>   |
| PLC function data copy | <ul style="list-style-type: none"> <li>• This function copies the PLC function project data to a USB memory device when the PLC function is used.</li> <li>• The PLC function project data copied in the USB memory device can be copied to other inverters.</li> <li>• This function is useful in backing up the parameter setting and for allowing multiple inverters to operate by the same sequence programs.</li> </ul>  |

- When the inverter recognizes the USB memory device without any problem, **USB--A** is briefly displayed on the operation panel.
- When the USB memory device is removed, **USB--** is briefly displayed on the operation panel.
- The operating status of the USB host can be checked on the LED display of the inverter.

| LED display status | Operating status  |
|--------------------|---|
| OFF                | No USB connection.  |
| ON                 | The communication is established between the inverter and the USB device.       |
| Flickering rapidly | The USB memory device is being accessed. (Do not remove the USB memory device.) |
| Flickering slowly  | Error in the USB connection.  |

- When a device such as a USB battery charger is connected to the USB connector and an excessive current (500 mA or more) flows, USB host error **UF** (UF warning) is displayed on the operation panel.
- When the UF warning appears, the USB error can be canceled by removing the USB device and setting **Pr.1049 = "1"**. (The UF warning can also be canceled by resetting the inverter power or resetting with the RES signal.)

#### REMARKS

- Do not connect devices other than a USB memory device to the inverter.
- If a USB device is connected to the inverter via a USB hub, the inverter cannot recognize the USB memory device properly.
- For the details of the usage of the USB connector, refer to the FR-A800 Instruction Manual (Detailed).

### (3) USB device communication

The inverter can be connected to a personal computer with a USB (Ver. 1.1) cable.  
Parameter setting and monitoring can be performed by FR Configurator 2.

|                           |                                   |
|---------------------------|-----------------------------------|
| <b>Interface</b>          | Conforms to USB1.1                |
| <b>Transmission speed</b> | 12 Mbps                           |
| <b>Wiring length</b>      | Maximum 5 m                       |
| <b>Connector</b>          | USB mini B connector (receptacle) |
| <b>Power supply</b>       | Self-powered                      |

#### REMARKS

- For the details of FR Configurator 2, refer to the Instruction Manual of FR Configurator 2.

## WARNING

**⚠ While power is ON or when the inverter is running, do not open the front cover. Otherwise you may get an electric shock.**

## 2.8.3 RS-485 terminal block

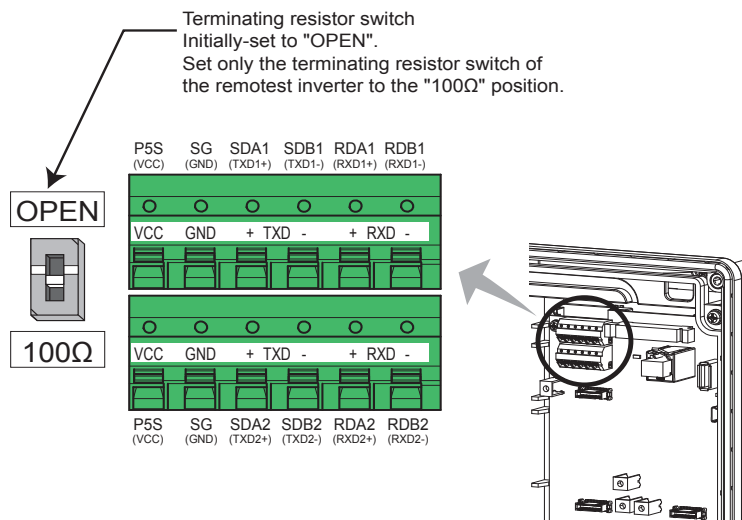
### (1) Communication operation

|                            |                              |
|----------------------------|------------------------------|
| <b>Conforming standard</b> | EIA-485 (RS-485)             |
| <b>Transmission format</b> | Multidrop link               |
| <b>Communication speed</b> | maximum 115200 bps           |
| <b>Overall length</b>      | 500 m                        |
| <b>Connection cable</b>    | Twisted pair cable (4 pairs) |

The RS-485 terminals enable communication operation from a personal computer, etc. When the PU connector is connected with a personal, FA or other computer by a communication cable, a user program can run to monitor the inverter or read and write parameters.

Communication can be performed with the Mitsubishi inverter protocol (computer link operation) and Modbus-RTU protocol.

For the details, refer to the FR-A800 Instruction Manual (Detailed).



#### REMARKS

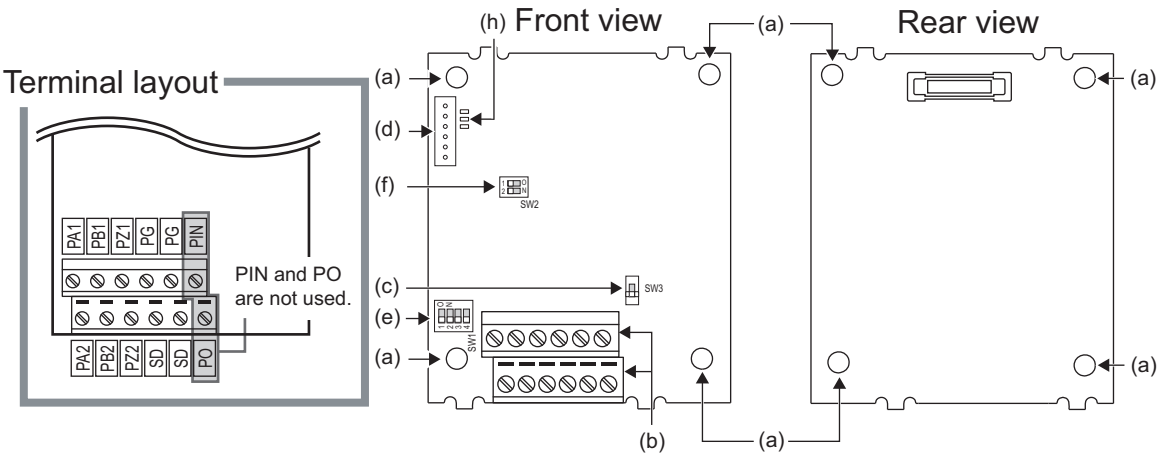
- To avoid malfunction, keep the RS-485 terminal wires away from the control circuit board.
- When is used with a plug-in option, lead the wires on the left side of the plug-in option for wiring of the RS-485 terminals.




## 2.9 Connection of motor with encoder (vector control)

Using an encoder-equipped motor together with the plug-in option FR-A8AP enables speed, torque, and positioning control operations under orientation control, encoder feedback control, and full-scale vector control.

(1) Appearance and parts name of FR-A8AP



| Symbol | Name  | Description   | Refer to page |
|--------|---|---|---------------|
| a      | Mounting hole                               | Used for installation to the inverter.  | —             |
| b      | Terminal block                              | Connected with the encoder.   | 51            |
| c      | Encoder type selection switch (SW3)         | Switches the encoder type (differential line driver/complementary).   | 49            |
| d      | CON2 connector                              | Not used.   | —             |
| e      | Terminating resistor selection switch (SW1) | Switches ON or OFF the internal terminating resistor.   | 49            |
| f      | Switch for manufacturer setting (SW2)       | Do not change from the initially-set status. (Switches 1 and 2 are OFF  .) | —             |
| g      | Connector                                   | Connected to the option connector of the inverter.  | 9             |
| h      | LED for manufacturer check                  | Not used.   | —             |

(2) Terminals of the FR-A8AP

| Terminal symbol | Terminal name                                       | Description  |
|-----------------|---|--|
| PA1             | Encoder A-phase signal input terminal               | A-, B- and Z-phase signals are input from the encoder.   |
| PA2             | Encoder A-phase inverse signal input terminal       |  |
| PB1             | Encoder B-phase signal input terminal               |  |
| PB2             | Encoder B-phase inverse signal input terminal       |  |
| PZ1             | Encoder Z-phase signal input terminal               |  |
| PZ2             | Encoder Z-phase inverse signal input terminal       |  |
| PG              | Encoder power supply (positive side) input terminal | Input terminal for the encoder power supply.<br>Connect the external power supply (5 V, 12 V, 15 V, 24 V) and the encoder power cable. When the encoder output is the differential line driver type, only 5 V can be input. Make the voltage of the external power supply same as the encoder output voltage. (Check the encoder specification.) |
| SD              | Encoder power supply ground terminal                |  |
| PIN             | Not used.   |  |
| PO              |   |  |

### REMARKS

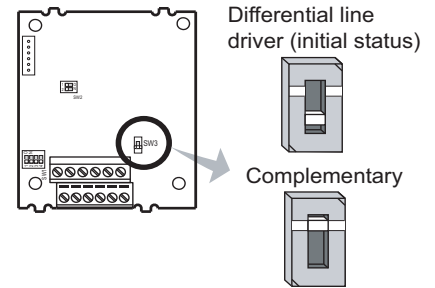
- When the encoder's output voltage differs from its input power supply voltage, the signal loss detection (E.ECT) may occur.
- Incorrect wiring or faulty setting to the encoder will cause a fault such as an overcurrent (E.OC[ ]) and an inverter overload (E.THT). Correctly perform wiring and setting to the encoder.

## (3) Switches of the FR-A8AP

### Encoder type selection switch (SW3)

Selects either the differential line driver or complementary setting.

It is initially set to the differential line driver. Switch its position according to the output circuit.



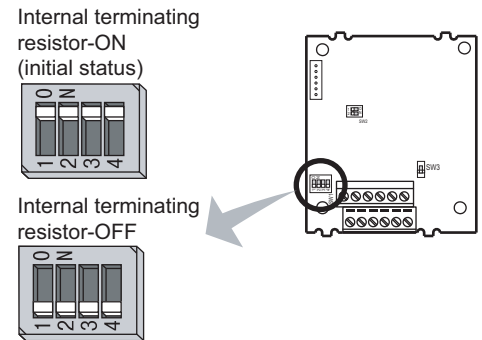
### Terminating resistor selection switch (SW1)

Selects ON/OFF of the internal terminating resistor.

Set the switch to ON (initial status) when an encoder output type is differential line driver, and set to OFF when complementary.

ON: with internal terminating resistor (initial status)

OFF: without internal terminating resistor



## REMARKS

- Set all switches to the same setting (ON/OFF).
- Set the switch "OFF" when sharing an encoder with another unit (NC (computerized numerical controller), etc.) having a terminating resistor under the differential line driver setting.

### Motor and switch setting

| Motor   |         | Encoder type selection switch (SW1) | Terminating resistor selection switch (SW2) | Power supply specification*2 |
|---|---------|-------------------------------------|---|------------------------------|
| Mitsubishi standard motor with encoder        | SF-JR   | Differential                        | ON  | 5 V                          |
|   | SF-HR   | Differential                        | ON  | 5 V                          |
|   | Other   | *1                                  | *1  | *1                           |
| Mitsubishi constant-torque motor with encoder | SF-JRCA | Differential                        | ON  | 5 V                          |
|   | SF-HRCA | Differential                        | ON  | 5 V                          |
|   | Other   | *1                                  | *1  | *1                           |
| Vector control dedicated motor                | SF-V5RU | Complementary                       | OFF   | 12 V                         |
| Other manufacturer's motor with encoder       |         | *1                                  | *1  | *1                           |

\*1 Set according to the motor (encoder).

\*2 Prepare an encoder's power supply (5 V/12 V/15 V/24 V) according to the encoder's output voltage. When the encoder output is the differential line driver type, only 5 V can be input.

## REMARKS

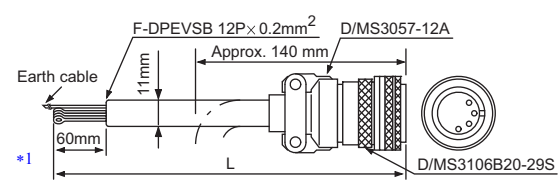
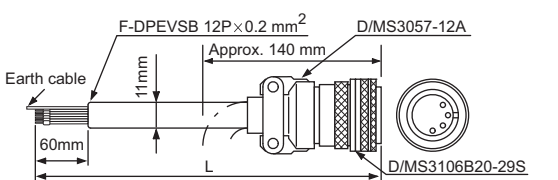
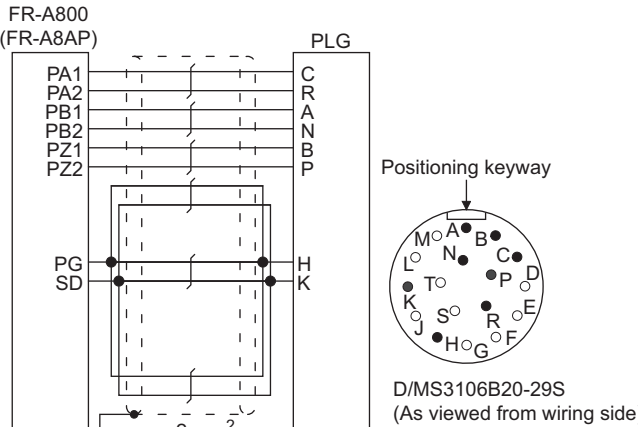
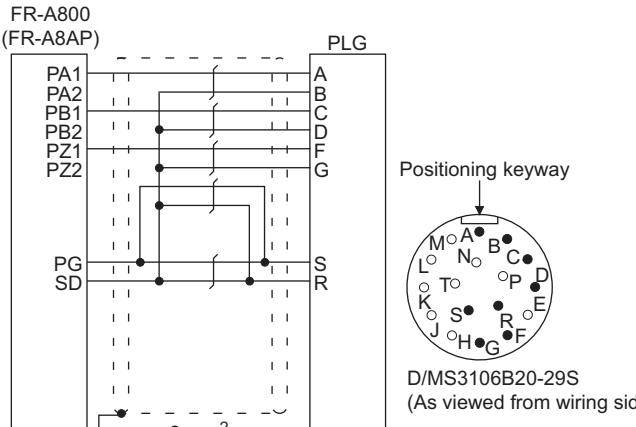
- The SW2 switch is for manufacturer setting. Do not change the setting.

### Encoder specification

| Item                 | Encoder for SF-JR                                     | Encoder for SF-V5RU  |
|----------------------|---|--|
| Resolution           | 1024 pulses/rev                                       | 2048 pulses/rev  |
| Power supply voltage | 5 VDC $\pm 10\%$                                      | 12 VDC $\pm 10\%$  |
| Current consumption  | 150 mA  | 150 mA   |
| Output signal form   | A, B phases (90° phase shift)<br>Z phase: 1 pulse/rev | A, B phases (90° phase shift)<br>Z phase: 1 pulse/rev                  |
| Output circuit       | Differential line driver 74LS113 equivalent           | Complementary  |
| Output voltage       | H level: 2.4 V or more<br>L level: 0.5 V or less      | H level: (Power supply for encoder-3V) or more<br>L level: 3 V or less |

## Connection of motor with encoder (vector control)

### (4) Encoder cable

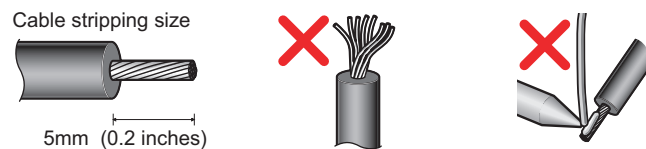
| SF-JR/HR/JRCA/HRCA with encoder  | SF-V5RU, SF-THY   |              |          |   |           |    |           |    |  |       |              |           |   |            |    |            |    |
|--|---|--------------|----------|---|-----------|----|-----------|----|--|-------|--------------|-----------|---|------------|----|------------|----|
|  <table border="1" style="margin-top: 10px; width: 100%; border-collapse: collapse;"> <thead> <tr style="background-color: #cccccc;"> <th>Model</th> <th>Length L (m)</th> </tr> </thead> <tbody> <tr> <td>FR-JCBL5</td> <td>5</td> </tr> <tr> <td>FR-JCBL15</td> <td>15</td> </tr> <tr> <td>FR-JCBL30</td> <td>30</td> </tr> </tbody> </table> | Model   | Length L (m) | FR-JCBL5 | 5 | FR-JCBL15 | 15 | FR-JCBL30 | 30 |  <table border="1" style="margin-top: 10px; width: 100%; border-collapse: collapse;"> <thead> <tr style="background-color: #cccccc;"> <th>Model</th> <th>Length L (m)</th> </tr> </thead> <tbody> <tr> <td>FR-V7CBL5</td> <td>5</td> </tr> <tr> <td>FR-V7CBL15</td> <td>15</td> </tr> <tr> <td>FR-V7CBL30</td> <td>30</td> </tr> </tbody> </table> | Model | Length L (m) | FR-V7CBL5 | 5 | FR-V7CBL15 | 15 | FR-V7CBL30 | 30 |
| Model  | Length L (m)  |              |          |   |           |    |           |    |  |       |              |           |   |            |    |            |    |
| FR-JCBL5   | 5   |              |          |   |           |    |           |    |  |       |              |           |   |            |    |            |    |
| FR-JCBL15  | 15  |              |          |   |           |    |           |    |  |       |              |           |   |            |    |            |    |
| FR-JCBL30  | 30  |              |          |   |           |    |           |    |  |       |              |           |   |            |    |            |    |
| Model  | Length L (m)  |              |          |   |           |    |           |    |  |       |              |           |   |            |    |            |    |
| FR-V7CBL5  | 5   |              |          |   |           |    |           |    |  |       |              |           |   |            |    |            |    |
| FR-V7CBL15   | 15  |              |          |   |           |    |           |    |  |       |              |           |   |            |    |            |    |
| FR-V7CBL30   | 30  |              |          |   |           |    |           |    |  |       |              |           |   |            |    |            |    |
|    |  |              |          |   |           |    |           |    |  |       |              |           |   |            |    |            |    |

\*1 As the terminal block of the FR-A8AP is an insertion type, cables need to be treated. (Refer to the following description.)

- When using an encoder cable (FR-JCBL, FR-V5CBL, etc.) dedicated to the conventional motor, cut the crimping terminal of the encoder cable and strip its sheath to make its cable wires loose.

Also, treat the shielding wires of the shielded twisted pair cable to ensure that they will not contact conductive areas.

Wire the stripped cable after twisting it to prevent it from becoming loose. In addition, do not solder it.



#### REMARKS

- Information on blade terminals

Commercially available products (as of February 2012)

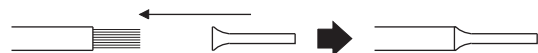
Phoenix Contact Co., Ltd.

| Terminal screw size | Cable gauge (mm <sup>2</sup> ) | Blade terminal model   |                           | Crimping tool name |
|---------------------|--------------------------------|------------------------|---------------------------|--------------------|
|                     |                                | With insulation sleeve | Without insulation sleeve |                    |
| M2                  | 0.3, 0.5                       | AI 0,5-6WH             | A 0,5-6                   | CRIMPFOX 6         |

NICHIFU Co.,Ltd.

| Terminal screw size | Cable gauge (mm <sup>2</sup> ) | Blade terminal product number | Insulation product number | Crimping tool product number |
|---------------------|--------------------------------|-------------------------------|---------------------------|------------------------------|
| M2                  | 0.3 to 0.75                    | BT 0.75-7                     | VC 0.75                   | NH 69                        |

- When using a blade terminal (without insulation sleeve), take caution that the twisted wires do not come out.

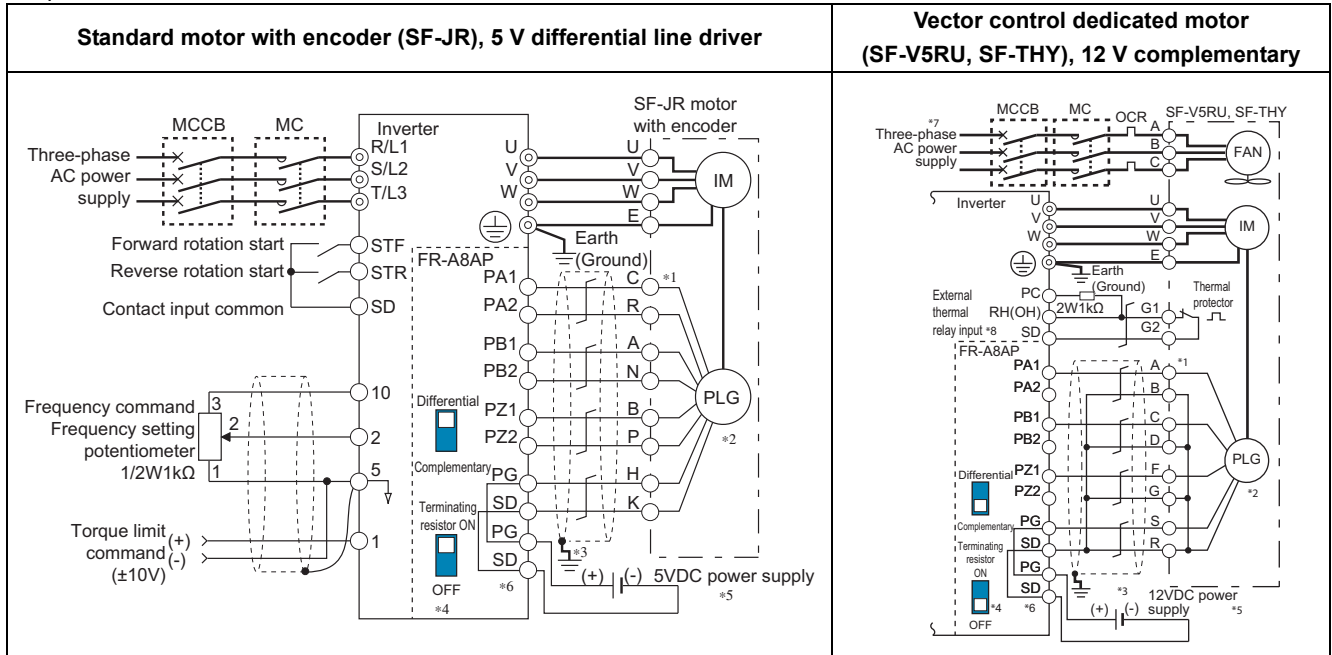


## • Connection terminal compatibility table

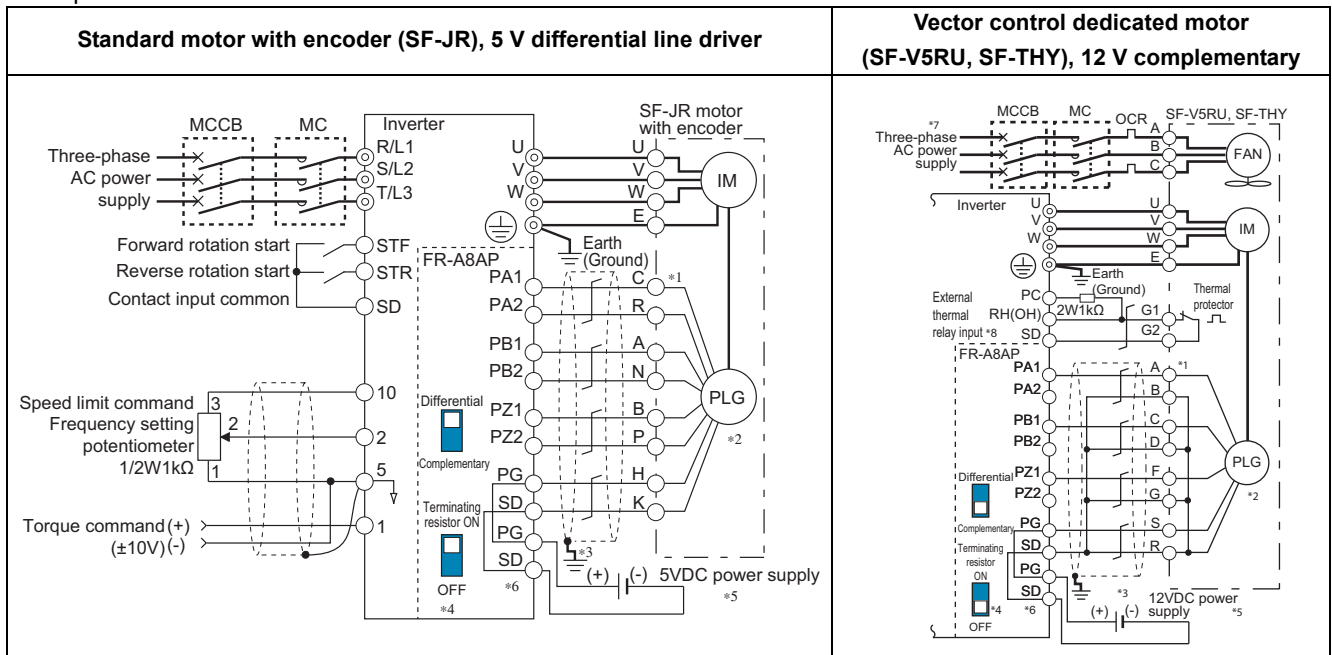
| Motor            |     | SF-V5RU, SF-THY                  | SF-JR/HR/JRCA/HRCA (with encoder) |
|------------------|-----|----------------------------------|-----------------------------------|
| Encoder cable    |     | FR-V7CBL                         | FR-JCBL                           |
| FR-A8AP terminal | PA1 | PA                               | PA                                |
|                  | PA2 | Do not connect anything to this. | PAR                               |
|                  | PB1 | PB                               | PB                                |
|                  | PB2 | Do not connect anything to this. | PBR                               |
|                  | PZ1 | PZ                               | PZ                                |
|                  | PZ2 | Do not connect anything to this. | PZR                               |
|                  | PG  | PG                               | 5E                                |
|                  | SD  | SD                               | AG2                               |

## (5) Wiring example

### • Speed control

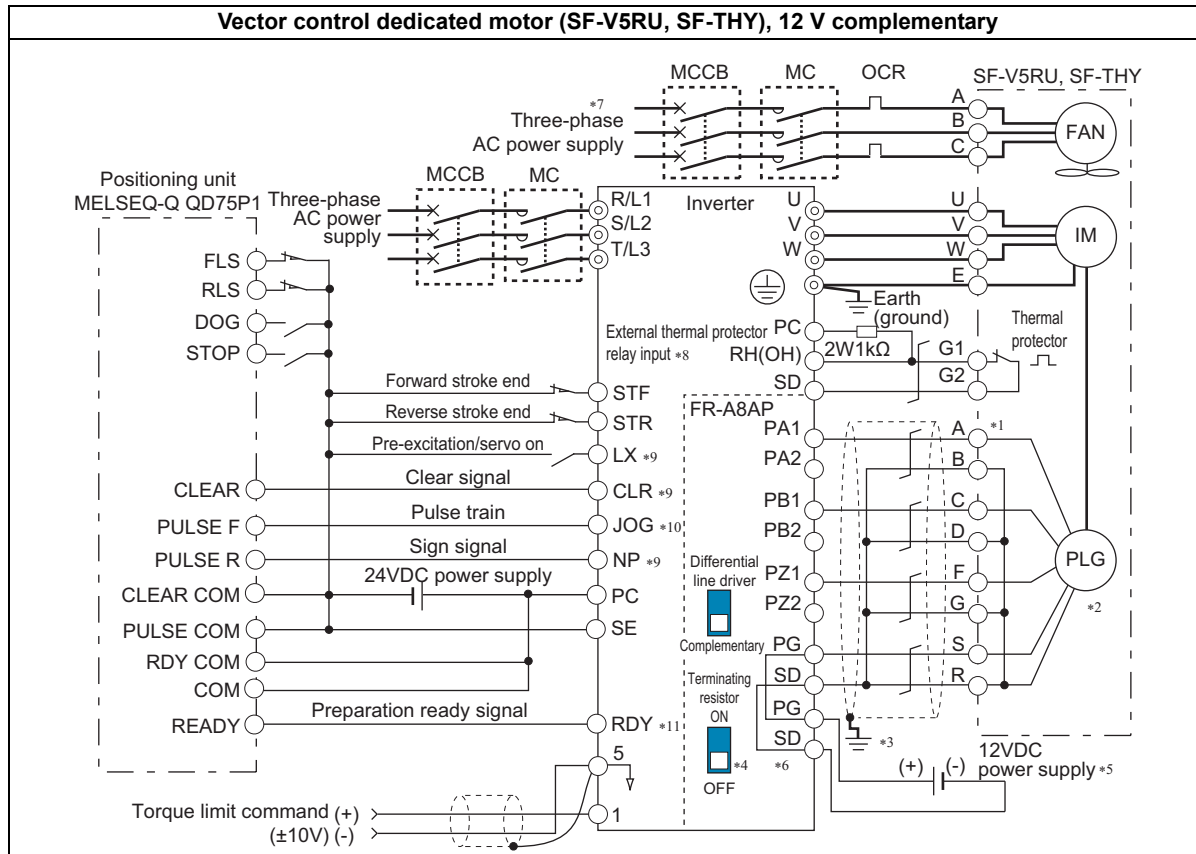


### • Torque control

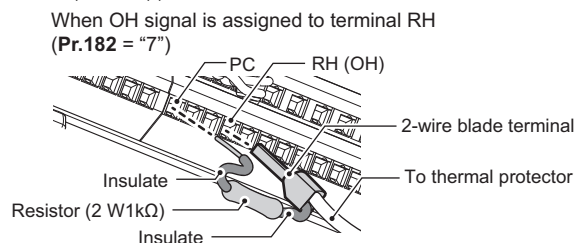


## Connection of motor with encoder (vector control)

### • Position control



- \*1 The pin number differs according to the encoder used.  
Speed, control, torque control, and position control by pulse train input are available with or without the Z-phase being connected.
- \*2 Connect the encoder so that there is no looseness between the motor and motor shaft. Speed ratio must be 1:1.
- \*3 Earth (ground) the shield of the encoder cable to the enclosure using a tool such as a P-clip. (Refer to [page 53](#).)
- \*4 For the complementary, set the terminating resistor selection switch to OFF position. (Refer to [page 49](#).)
- \*5 A separate power supply of 5 V/12 V/15 V/24 V is necessary according to the encoder power specification.  
When the encoder output is the differential line driver type, only 5 V can be input.  
Make the voltage of the external power supply the same as the encoder output voltage, and connect the external power supply across PG and SD.
- \*6 For terminal compatibility of the FR-JCBL, FR-V7CBL, and FR-A8AP, refer to [page 51](#).
- \*7 For the fan of the 7.5 kW or lower dedicated motor, the power supply is single phase. (200 V/50 Hz, 200 to 230 V/60 Hz)
- \*8 Connect the recommended 2W1kΩ resistor between the terminal PC and OH. (Recommended product: MOS2C102J 2W1kΩ by KOA Corporation)  
Insert the input line and the resistor to a 2-wire blade terminal, and connect the blade terminal to the terminal OH. (For the recommended 2-wire blade terminals, refer to [page 34](#).)  
Insulate the lead wire of the resistor, for example by applying a contraction tube, and shape the wires so that the resistor and its lead wire will not touch other cables. Caulk the lead wire securely together with the thermal protector input line using a 2-wire blade terminal. (Do not subject the lead wire's bottom area to an excessive pressure.)  
To use a terminal as the terminal OH, assign the OH (external thermal O/L relay input) signal to an input terminal. (Set "7" in any of **Pr.178 to Pr.189**. For details, refer to the FR-A800 Instruction Manual (Detailed).)

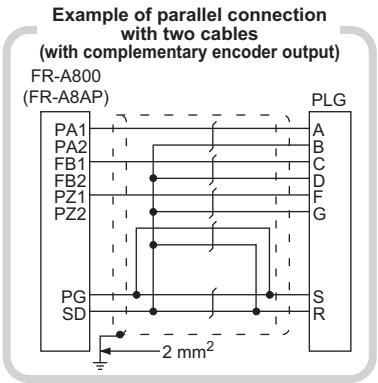


- \*9 Assign the function using **Pr.178 to Pr.184, Pr.187 to Pr.189 (input terminal function selection)**.
- \*10 When position control is selected, terminal JOG function is invalid and simple position pulse train input terminal becomes valid.
- \*11 Assign the function using **Pr.190 to Pr.194 (output terminal function selection)**.

(6) Instructions for encoder cable wiring

- Use shielded twisted pair cables (0.2 mm<sup>2</sup> or larger) to connect the FR-A8AP. For the wiring to the terminals PG and SD, use several cables in parallel or use a thick cable, according to the wiring length.

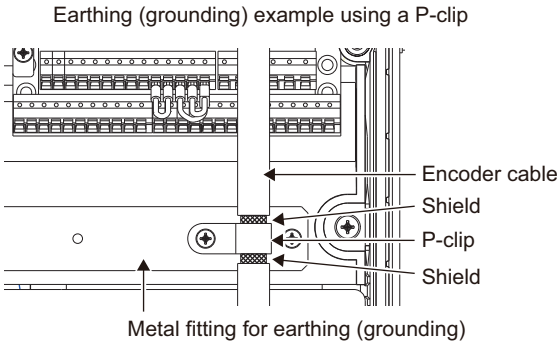
To protect the cables from noise, run them away from any source of noise (such as the main circuit and power supply voltage).



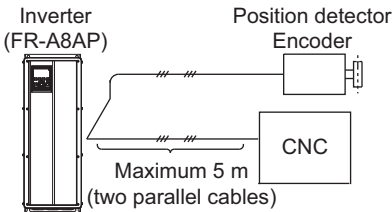
| Wiring length   | Parallel connection              | Larger-size cable              |
|-----------------|----------------------------------|--------------------------------|
| Within 10 m     | At least two cables in parallel  | 0.4 mm <sup>2</sup> or larger  |
| Within 20 m     | At least four cables in parallel | 0.75 mm <sup>2</sup> or larger |
| Within 100 m *1 | At least six cables in parallel  | 1.25 mm <sup>2</sup> or larger |

\*1 When differential line driver is set and a wiring length is 30 m or more.  
The wiring length can be extended to 100 m by increasing the 5 V power supply (approximately to 5.5 V) while using six or more 0.2 mm<sup>2</sup> gauge cables in parallel or a 1.25 mm<sup>2</sup> or larger gauge cable. The voltage applied must be within power supply specifications of encoder.

- To reduce noise of the encoder cable, earth (ground) the encoder's shielded cable to the metal fitting for earthing (grounding) with a P-clip or U-clip made of metal. Refer to the following figure.



- When one encoder is shared between FR-A8AP and CNC (computerized numerical controller), its output signal should be connected as shown below. In this case, the wiring length between FR-A8AP and CNC should be as short as possible, within 5 m.





REMARKS

- For the details of the optional encoder dedicated cable (FR-JCBL/FR-V7CBL), refer to [page 50](#).
- The FR-V7CBL is provided with a P-clip for earthing (grounding) shielded cables.

## Connection of motor with encoder (vector control)

### (7) Parameter for the encoder (Pr.359, Pr.369)

| Pr.         | Name                       | Initial value | Setting range | Description  |
|-------------|----------------------------|---------------|---------------|--|
| 359<br>C141 | Encoder rotation direction | 1             | 0             | Set when using a motor for which forward rotation (encoder) is clockwise (CW) viewed from the shaft                        |
|             |                            |               | 100           |  Set for the operation at 120 Hz or less. |
|             |                            |               | 1             | Set when using a motor for which forward rotation (encoder) is counterclockwise (CCW) viewed from the shaft                |
|             |                            |               | 101           |  Set for the operation at 120 Hz or less. |
| 369<br>C140 | Number of encoder pulses   | 1024          | 0 to 4096     | Set the number of encoder pulses output.<br>Set the number of pulses before it is multiplied by 4.                         |

The above parameters can be set when the FR-A8AP (option) is mounted.

### (8) Parameter settings for the motor under vector control

- Values in   indicate initial values.

| Motor name                                 |  | Pr.9<br>Electronic thermal O/L relay | Pr.71<br>Applied motor | Pr.80<br>Motor capacity | Pr.81<br>Number of motor poles | Pr.359<br>Encoder rotation direction | Pr.369<br>Number of encoder pulses |
|--|--|--------------------------------------|------------------------|-------------------------|--------------------------------|--------------------------------------|------------------------------------|
| Mitsubishi standard motor                  | SF-JR                                  | Rated motor current                  | 0                      | Motor capacity          | Number of motor poles          | 1                                    | 1024                               |
|  | SF-HR                                  | Rated motor current                  | 40                     | Motor capacity          | Number of motor poles          | 1                                    | 1024                               |
|  | Others                                 | Rated motor current                  | 0(3) *1                | Motor capacity          | Number of motor poles          | *2                                   | *2                                 |
| Mitsubishi constant-torque motor           | SF-JRCA 4P                             | Rated motor current                  | 1                      | Motor capacity          | 4                              | 1                                    | 1024                               |
|  | SF-HRCA                                | Rated motor current                  | 50                     | Motor capacity          | Number of motor poles          | 1                                    | 1024                               |
|  | Others                                 | Rated motor current                  | 1(13) *1               | Motor capacity          | Number of motor poles          | *2                                   | *2                                 |
| Vector control dedicated motor             | SF-V5RU (1500 r/min series)            | 0 *3                                 | 30                     | Motor capacity          | 4                              | 1                                    | 2048                               |
|  | SF-V5RU (except for 1500 r/min series) | 0 *3                                 | 1(13) *1               | Motor capacity          | 4                              | 1                                    | 2048                               |
|  | SF-THY                                 | 0 *3                                 | 30(33) *1              | Motor capacity          | 4                              | 1                                    | 2048                               |
| Other manufacturer's standard motor        | —                                      | Rated motor current                  | 0(3) *1                | Motor capacity          | Number of motor poles          | *2                                   | *2                                 |
| Other manufacturer's constant-torque motor | —                                      | Rated motor current                  | 1(13) *1               | Motor capacity          | Number of motor poles          | *2                                   | *2                                 |

\*1 Offline auto tuning is required (Refer to the FR-A800 Instruction Manual (Detailed).)

\*2 Set this parameter according to the motor.

\*3 Use the thermal protector input provided with the motor.

- When using the inverter with the SF-V5RU (1500 r/min series), refer to the table below to set **Pr.83 Rated motor voltage** and **Pr.84 Rated motor frequency**.

| Motor capacity | SF-V5RU   |            |
|----------------|-----------|------------|
|                | 400 V     |            |
|                | Pr.83 (V) | Pr.84 (Hz) |
| 5.5 kW         | 322       | 51         |
| 7.5 kW         | 331       | 51         |
| 11 kW          | 320       | 51         |
| 15 kW          | 330       | 51         |

- When using the inverter with the SF-V5RU1, SF-V5RU3, or SF-V5RU4, refer to the table below to set **Pr.83 Rated motor voltage** and **Pr.84 Rated motor frequency**.

| Motor model                                    | Pr.83 setting | Pr.84 setting |
|--|---------------|---------------|
|  | 400 V class   |               |
| SF-V5RU1                                       | 320 V         | 33.33 Hz      |
| SF-V5RU3                                       | 320 V         |               |
| SF-V5RU4-7.5kW                                 | 300 V         | 16.67 Hz      |
| SF-V5RU4 and motors other than described above | 320 V         |               |

- (9) Combination with the vector control dedicated motor

When using the inverter with a vector control dedicated motor, refer to the table below.

- Combination with the SF-V5RU

| Voltage        | 400 V class        |             |                          |
|----------------|--------------------|-------------|--------------------------|
| Rated speed    | 1500 r/min         |             |                          |
| Base frequency | 50 Hz              |             |                          |
| Maximum speed  | 3000 r/min         |             |                          |
| Motor capacity | Motor frame number | Motor model | Inverter model FR-A846-□ |
| 5.5 kW         | 132S               | SF-V5RUH5K  | 00250(7.5K)              |
| 7.5 kW         | 132M               | SF-V5RUH7K  | 00310(11K)               |
| 11 kW          | 160M               | SF-V5RUH11K | 00380(15K)               |
| 15 kW          | 160L               | SF-V5RUH15K | 00470(18.5K)             |

### REMARKS

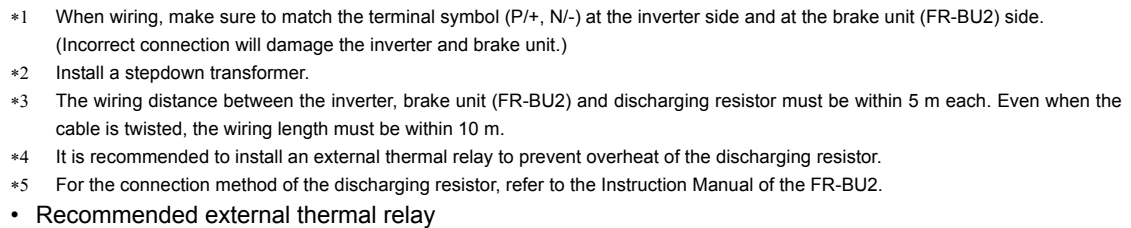
- The SF-V5RU1 (speed ratio 1:1), SF-V5RU3 (speed ratio 1:3), and SF-V5RU (speed ratio 1:4) are to be manufactured after an order.



Incorrect connection will cause inverter damage or accident. Connect and operate the option unit carefully in accordance with the corresponding option unit manual.

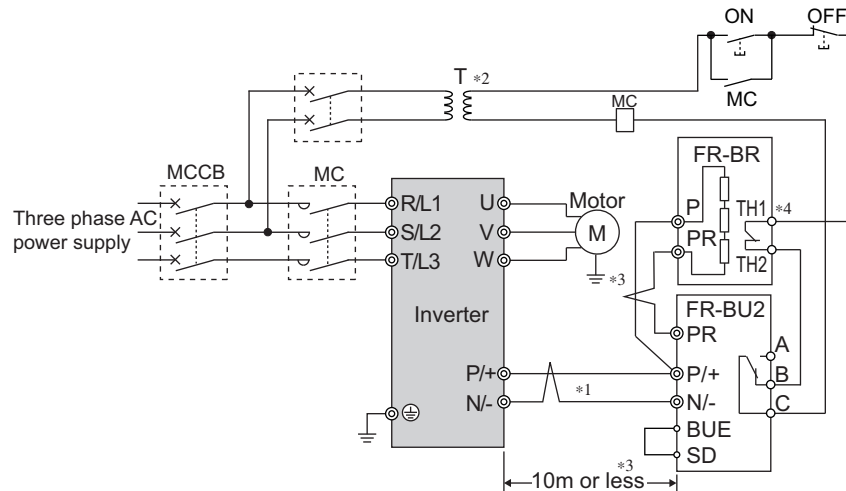
### 2.10.1 Connection of the brake unit (FR-BU2)

### (1) Connection example with the GRZG type discharging resistor



- Set "1" in **Pr.0 Brake mode selection** of the FR-BU2 to use a GRZG type discharging resistor.
- Do not remove the jumper across terminals P/+ and P1.

## (2) Connection example with the FR-BR-(H) resistor unit



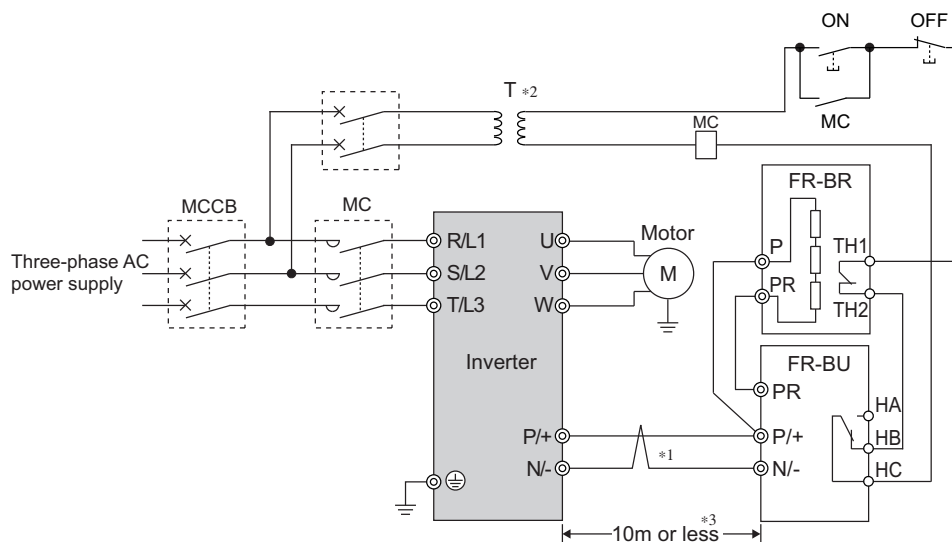
- \*1 When wiring, make sure to match the terminal symbol (P/+, N/-) at the inverter side and at the brake unit (FR-BU2) side. (Incorrect connection will damage the inverter and brake unit.)
- \*2 Install a stepdown transformer.
- \*3 The wiring distance between the inverter, brake unit (FR-BU2) and resistor unit (FR-BR) must be within 5 m each. Even when the cable is twisted, the wiring length must be within 10 m.
- \*4 The contact between TH1 and TH2 is closed in the normal status and is open at a fault.

### REMARKS

- Do not remove the jumper across terminals P/+ and P1.

## 2.10.2 Connection of the brake unit (FR-BU)

Connect the brake unit (FR-BU2(H)) as shown below to improve the braking capability during deceleration.



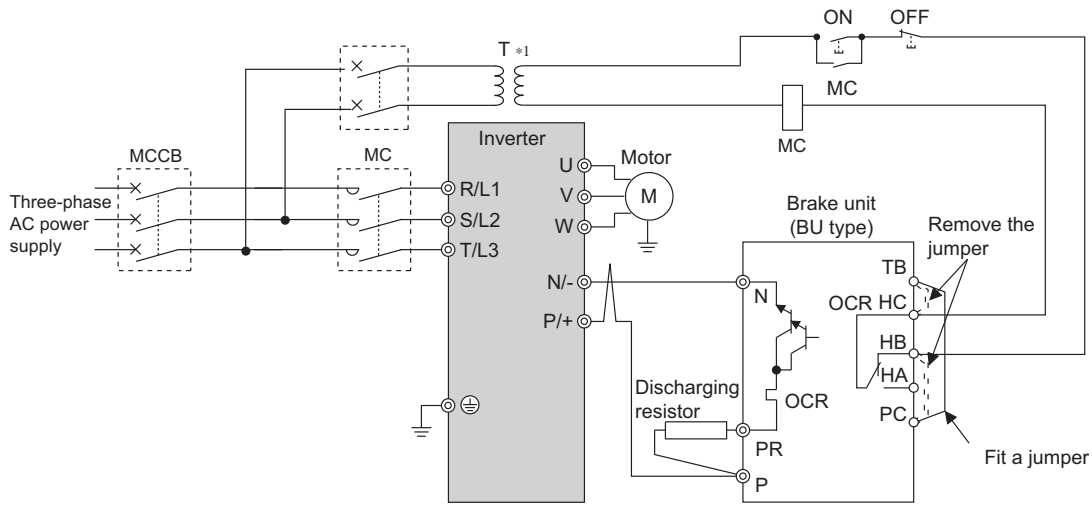
- \*1 When wiring, make sure to match the terminal symbol (P/+, N/-) at the inverter side and at the brake unit (FR-BU(H)) side. (Incorrect connection will damage the inverter.)
- \*2 Install a stepdown transformer.
- \*3 The wiring distance between the inverter, brake unit (FR-BU) and resistor unit (FR-BR) must be within 5 m each. Even when the cable is twisted, the wiring length must be within 10 m.

### REMARKS

- If the transistors in the brake unit should becomes faulty, the resistor will overheat. Install a magnetic contactor on the inverter's input side and configure a circuit that shut off the current in case of a fault.
- Do not remove the jumper across terminals P/+ and P1.

## 2.10.3 Connection of the brake unit (BU type)

Connect the brake unit (BU type) correctly as shown below. Incorrect connection will damage the inverter. Remove the jumpers across terminals HB and PC and terminals TB and HC of the brake unit and fit one across terminals PC and TB.



\*1 Install a stepdown transformer.

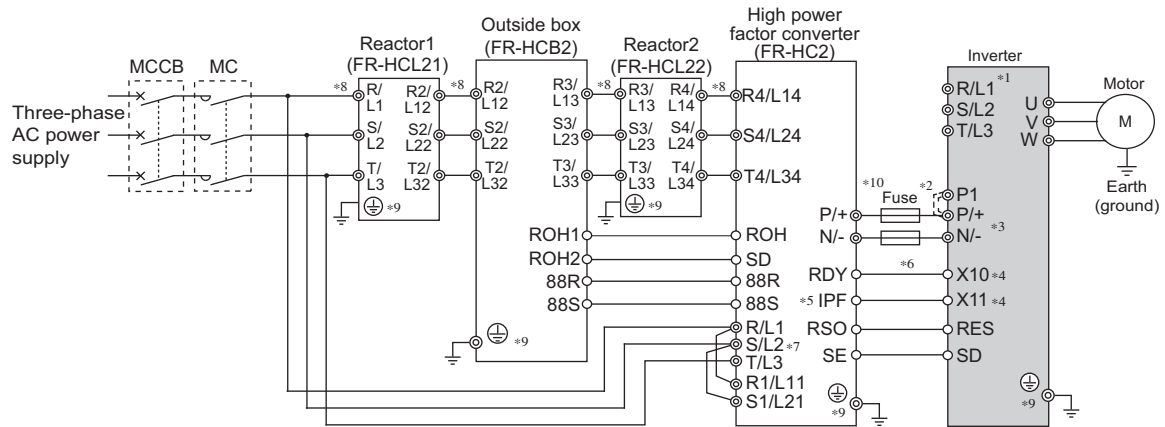
### REMARKS

- The wiring distance between the inverter, brake unit and discharging resistor must be within 2 m each. Even when the cable is twisted, the wiring length must be within 5 m.
- If the transistors in the brake unit should becomes faulty, the resistor will overheat and result in a fire. Install a magnetic contactor on the inverter's input side and configure a circuit that shut off the current in case of a fault.
- Remove the jumper across terminals P/+ and P1.

## 2.10.4 Connection of the high power factor converter (FR-HC2)

When connecting the high power factor converter (FR-HC2) to suppress power harmonics, perform wiring securely as shown below. Incorrect connection will damage the high power factor converter and the inverter.

After making sure that the wiring is correct, set "rated motor voltage" in **Pr.19 Base frequency voltage** (under V/F control) or **Pr.83 Rated motor voltage** (under other than V/F control) and "2" in **Pr.30 Regenerative function selection**.



- \*1 Do not connect anything to power input terminals (R/L1, S/L2, T/L3). Incorrect connection will damage the inverter. (E.OPT (option fault) will occur.)
- \*2 Remove the jumper across terminals P/+ and P1.
- \*3 Do not install an MCCB across the terminals P/+ and N/- (across terminals P and P/+ or across N and N/-). Connecting the opposite polarity of terminals N/- and P/+ will damage the inverter.
- \*4 Use **Pr.178 to Pr.189 (input terminal function selection)** to assign the terminals used for the X10 (X11) signal.  
For RS-485 or any other communication where the start command is only transmitted once, use the X11 signal to save the operation mode at the time of an instantaneous power failure.
- \*5 Assign the IPF signal to an FR-HC2 terminal. (Refer to the Instruction Manual of FR-HC2.)
- \*6 Always connect the FR-HC2 terminal RDY to a terminal where the X10 signal or MRS signal is assigned in the inverter. Always connect the FR-HC2 terminal SE to the inverter terminal SD. Not connecting these terminals may damage the FR-HC2.
- \*7 Always connect the R/L1, S/L2, and T/L3 terminals of FR-HC2 to the power supply. Operating the inverter without connecting them will damage the FR-HC2.
- \*8 Do not install an MCCB or MC between the reactor 1 terminals (R/L1, S/L2, T/L3) and the FR-HC2 terminals (R4/L14, S4/L24, T4/L34). It will not operate properly.
- \*9 Securely perform grounding (earthing) by using the grounding (earthing) terminal.
- \*10 Installation of a fuse is recommended. (Refer to the Instruction Manual of FR-HC2.)

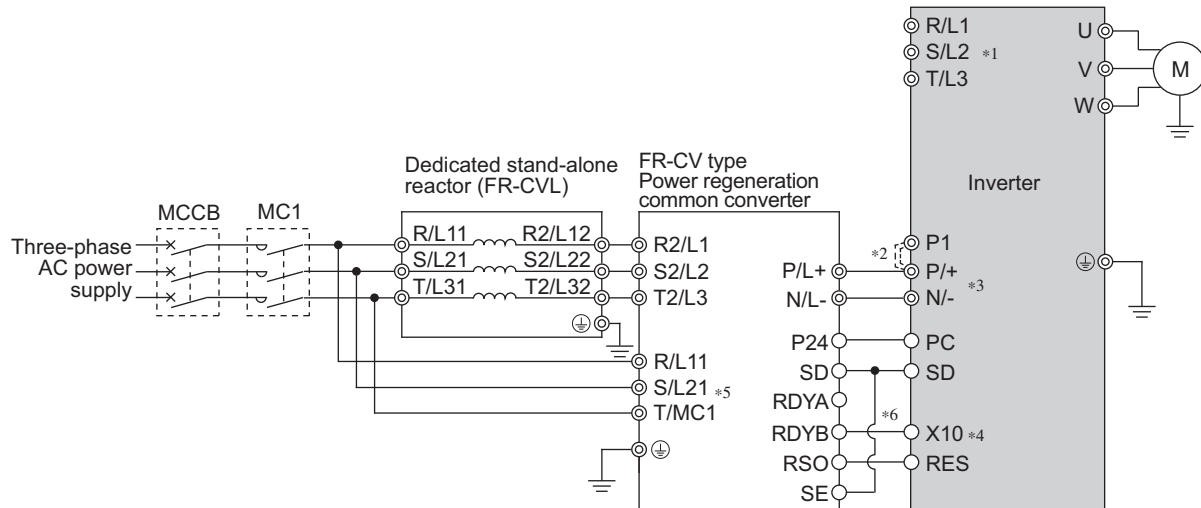
### REMARKS

- The voltage phases of terminals R/L1, S/L2, and T/L3 and the voltage phases of terminals R4/L14, S4/L24, and T4/L34 must be matched.
- The control logic (sink logic/source logic) of the high power factor converter and the inverter must be matched. (Refer to [page 32.](#))
- For the parameter details, refer to the FR-A800 Instruction Manual (Detailed).

## 2.10.5 Connection of the power regeneration common converter (FR-CV)

When connecting the power regeneration common converter (FR-CV), connect the inverter terminals (P/+, N/-) and the power regeneration common converter (FR-CV) terminals as shown below so that their symbols match with each other.

After making sure that the wiring is correct, set "2" in **Pr.30 Regenerative function selection**.



- \*1 Do not connect anything to power input terminals (R/L1, S/L2, T/L3). Incorrect connection will damage the inverter. (E.OPT (option fault) will occur.
- \*2 Remove the jumper across terminals P/+ and P1.
- \*3 Do not insert an MCCB between terminals P/+ and N/- (between terminals P/L+ and P/+ or between N/L- and N/-). Connecting the opposite polarity of terminals N/- and P/+ will damage the inverter.
- \*4 Use **Pr.178 to Pr.189 (input terminal function selection)** to assign the terminals used for the X10 signal.
- \*5 Be sure to connect the power supply and terminals R/L11, S/L21, and T/MC1. Operating the inverter without connecting them will damage the power regeneration common converter.
- \*6 Always connect terminal RDYB of the FR-CV to the inverter terminal where the X10 signal or the MRS signal is assigned to. Always connect terminal SE of the FR-CV to the inverter terminal SD. Not connecting these terminals may damage the FR-CV.

### REMARKS

- The voltage phases of terminals R/L11, S/L21, and T/MC1 and the voltage phases of terminals R2/L1, S2/L2, and T2/L3 must be matched.
- Use the sink logic (initial setting for the FM type) when the FR-CV is connected. It cannot be connected when the source logic is selected.
- For the parameter details, refer to the FR-A800 Instruction Manual (Detailed).

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# **3 PRECAUTIONS FOR USE OF THE INVERTER**

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This chapter explains the precautions for use of this product.  
Always read the instructions before using the equipment.

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|            |  |           |
|------------|--|-----------|
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## 3.1 Electro-magnetic interference (EMI) and leakage currents

### 3.1.1 Leakage currents and countermeasures

Capacitances exist between the inverter I/O cables, other cables and earth and in the motor, through which a leakage current flows. Since its value depends on the static capacitances, carrier frequency, etc., low acoustic noise operation at the increased carrier frequency of the inverter will increase the leakage current. Therefore, take the following countermeasures. Select the earth leakage current breaker according to its rated sensitivity current, independently of the carrier frequency setting.

#### (1) To-earth (ground) leakage currents

Leakage currents may flow not only into the inverter's own line but also into the other lines through the earthing (grounding) cable, etc. These leakage currents may operate earth leakage circuit breakers and earth leakage relays unnecessarily.

##### • Suppression technique

- If the carrier frequency setting is high, decrease the **Pr.72 PWM frequency selection** setting.  
Note that motor noise increases. Selecting **Pr.240 Soft-PWM operation selection** makes the sound inoffensive.
- By using earth leakage circuit breakers designed for harmonic and surge suppression in the inverter's own line and other line, operation can be performed with the carrier frequency kept high (with low noise).

##### • To-earth (ground) leakage currents

- Take caution as long wiring will increase the leakage current. Decreasing the carrier frequency of the inverter reduces the leakage current.
- Increasing the motor capacity increases the leakage current.

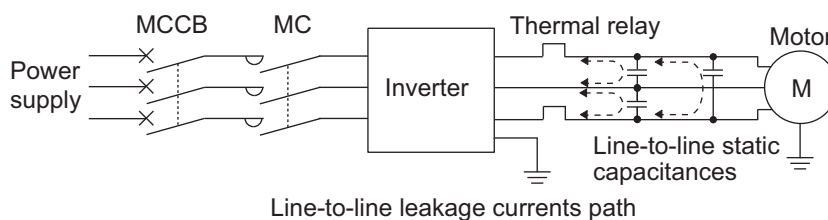
#### (2) Line-to-line leakage currents

Harmonics of leakage currents flowing in static capacitances between the inverter output cables may operate the external thermal relay unnecessarily. When the wiring length is long (50 m or more) for small-capacity models (FR-A846-00250(7.5K)), the external thermal relay is likely to operate unnecessarily because the ratio of the leakage current to the rated motor current increases.

##### • Line-to-line leakage current example

| Motor capacity (kW) | Rated motor current (A) | Leakage current (mA) |                     |
|---------------------|-------------------------|----------------------|---------------------|
|                     |                         | Wiring length 50 m   | Wiring length 100 m |
| 0.4                 | 1.8                     | 620                  | 1000                |
| 0.75                | 3.2                     | 680                  | 1060                |
| 1.5                 | 5.8                     | 740                  | 1120                |
| 2.2                 | 8.1                     | 800                  | 1180                |
| 3.7                 | 12.8                    | 880                  | 1260                |
| 5.5                 | 19.4                    | 980                  | 1360                |
| 7.5                 | 25.6                    | 1070                 | 1450                |

- Motor: SF-JR 4P
- Carrier frequency: 14.5 kHz
- Cable: 2 mm<sup>2</sup>, 4 cores
- Cabtyre cable



##### • Countermeasures

- Use **Pr.9 Electronic thermal O/L relay**.
- If the carrier frequency setting is high, decrease the **Pr.72 PWM frequency selection** setting.  
Note that motor noise increases. Selecting **Pr.240 Soft-PWM operation selection** makes the sound inoffensive.  
To ensure that the motor is protected against line-to-line leakage currents, it is recommended to use a temperature sensor to directly detect motor temperature.

##### • Installation and selection of the molded case circuit breaker

Install a molded case circuit breaker (MCCB) on the power receiving side to protect the wiring at the inverter input side. Select an MCCB according to the inverter input side power factor, which depends on the power supply voltage, output frequency and load. Especially for a completely electromagnetic MCCB, a slightly large capacity must be selected since its operation characteristic varies with harmonic currents. (Check it in the data of the corresponding breaker.) As an earth leakage current breaker, use the Mitsubishi earth leakage current breaker designed for harmonics and surge suppression.

## (3) Selecting the rated sensitivity current for the earth leakage circuit breaker

When using an earth leakage circuit breaker with the inverter circuit, select its rated sensitivity current as follows, independently of the PWM carrier frequency.

- Breaker designed for harmonic and surge suppression  
Rated sensitivity current  
 $I_{\Delta n} \geq 10 \times (I_{g1} + I_{gn} + I_{gi} + I_{g2} + I_{gm})$
- Standard breaker  
Rated sensitivity current  
 $I_{\Delta n} \geq 10 \times \{I_{g1} + I_{gn} + I_{gi} + 3 \times (I_{g2} + I_{gm})\}$

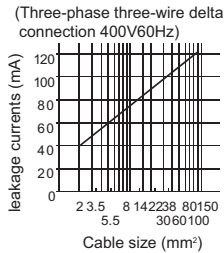
$I_{g1}$ ,  $I_{g2}$ : Leakage currents in wire path during commercial power supply operation

$I_{gn}$ : Leakage current of inverter input side noise filter

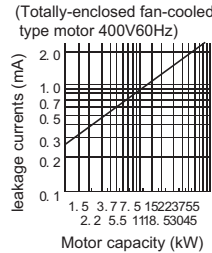
$I_{gm}$ : Leakage current of motor during commercial power supply operation

$I_{gi}$ : Leakage current of inverter unit

Example of leakage current per 1km during the commercial power supply operation when the CV cable is routed in metal conduit

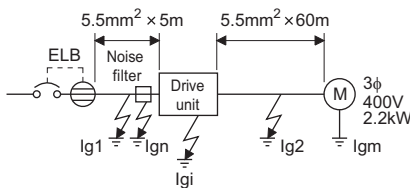


Leakage current example of three-phase induction motor during the commercial power supply operation



For "Δ" connection, the amount of leakage current is approx. 1/3 of the above value.

<Example>



| Item  | Breaker designed for harmonic and surge suppression  | Standard breaker |
|---|--|------------------|
| Leakage current $I_{g1}$ (mA)                           | $\frac{1}{3} \times 66 \times \frac{5 \text{ m}}{1000 \text{ m}} = 0.11$                         |                  |
| Leakage current $I_{gn}$ (mA)                           | 0 (without noise filter)   |                  |
| Leakage current $I_{gi}$ (mA)                           | 1 (without EMC filter)<br>For the leakage current of the inverter, refer to the following table. |                  |
| Leakage current $I_{g2}$ (mA)                           | $\frac{1}{3} \times 66 \times \frac{60 \text{ m}}{1000 \text{ m}} = 1.32$                        |                  |
| Motor leakage current $I_{gm}$ (mA)                     | 0.36   |                  |
| Total leakage current (mA)                              | 2.79   | 6.15             |
| Rated sensitivity current (mA) ( $\geq I_g \times 10$ ) | 30   | 100              |

### • Inverter leakage current (with and without EMC filter)

Input power conditions

(400 V class: 440 V/60 Hz, power supply unbalance within 3%)

|                            | Voltage (V) | EMC filter (C3) |          | EMC filter (C2) |          |
|----------------------------|-------------|-----------------|----------|-----------------|----------|
|                            |             | ON (mA)         | OFF (mA) | ON (mA)         | OFF (mA) |
| Phase earthing (grounding) | 400         | 35              | 2        | 200             | 1        |
| Earthed-neutral system     | 400         | 2               | 1        | 1               | 1        |

### REMARKS

- Install the earth leakage circuit breaker (ELB) on the input side of the inverter.
- In the Δ connection earthed-neutral system, the sensitivity current is blunt against a ground fault in the inverter output side. Earthing (Grounding) must conform to the requirements of national and local safety regulations and electrical codes. (NEC section 250, IEC 536 class 1 and other applicable standards)
- When the breaker is installed on the output side of the inverter, it may be unnecessarily operated by harmonics even if the effective value is within the rating.  
In this case, do not install the breaker since the eddy current and hysteresis loss will increase, leading to temperature rise.
- The following models are standard breakers: BV-C1, BC-V, NVB, NV-L, NV-G2N, NV-G3NA, NV-2F, earth leakage relay (except NV-ZHA), and NV with AA neutral wire open-phase protection. The other models are designed for harmonic and surge suppression: NV-C/ NV-S/MN series, NV30-FA, NV50-FA, BV-C2, earth leakage alarm breaker (NF-Z), NV-ZHA, and NV-H.



### 3.1.2 Countermeasures against inverter-generated EMI

Some electromagnetic noises enter the inverter to malfunction it, and others are radiated by the inverter to malfunction peripheral devices. Though the inverter is designed to have high immunity performance, it handles low-level signals, so it requires the following basic techniques. Also, since the inverter chops outputs at high carrier frequency, that could generate electromagnetic noises. If these electromagnetic noises cause peripheral devices to malfunction, EMI countermeasures should be taken to suppress noises. These techniques differ slightly depending on EMI paths.

#### 1) Basic techniques

- Do not run the power cables (I/O cables) and signal cables of the inverter in parallel with each other and do not bundle them.
- Use shielded twisted pair cables for the detector connecting and control signal cables and connect the sheathes of the shielded cables to terminal SD.
- Ground (Earth) the inverter, motor, etc. at one point.

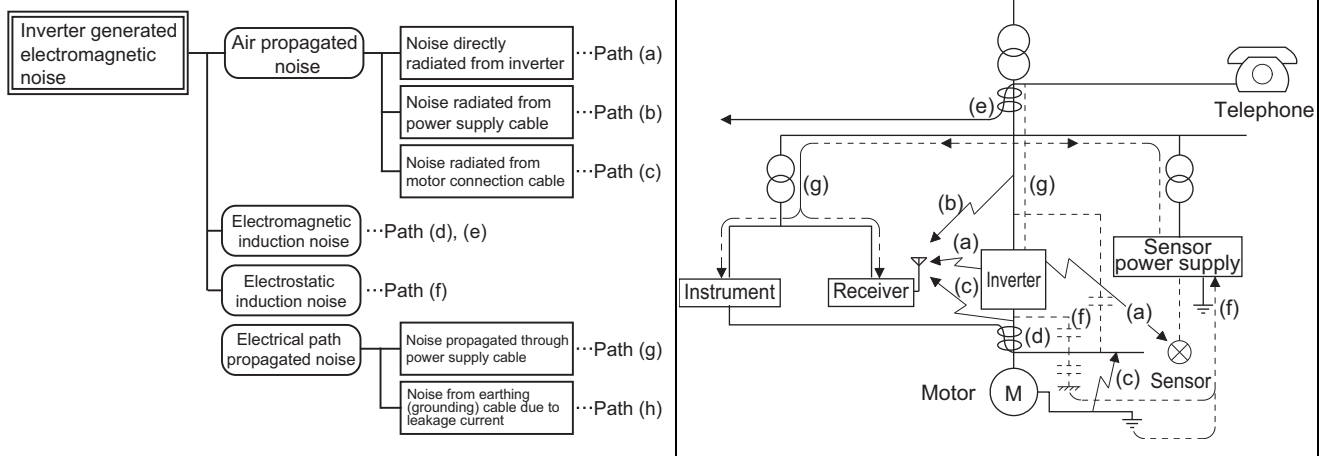
#### 2) Techniques to reduce electromagnetic noises that enter and cause a malfunction of the inverter (EMI countermeasures)

When devices that generate many electromagnetic noises (which use magnetic contactors, electromagnetic brakes, many relays, for example) are installed near the inverter and the inverter may malfunction due to electromagnetic noises, the following countermeasures must be taken:

- Provide surge suppressors for devices that generate many electromagnetic noises to suppress electromagnetic noises.
- Install data line filters ([page 65](#)) to signal cables.
- Ground (Earth) the shields of the detector connection and control signal cables with cable clamp metal.

#### 3) Techniques to reduce electromagnetic noises that are radiated by the inverter to malfunction peripheral devices (EMI countermeasures)

Inverter-generated noises are largely classified into those radiated by the cables connected to the inverter and inverter main circuits (I/O), those electromagnetically and electrostatically induced to the signal cables of the peripheral devices close to the main circuit power supply, and those transmitted through the power supply cables.



| Noise propagation path | Countermeasure  |
|------------------------|---|
| (a)(b)(c)              | <p>When devices that handle low-level signals and are liable to malfunction due to electromagnetic noises, e.g. instruments, receivers and sensors, are near the inverter or when the signal cables are run near the inverter, the devices may malfunction due to by air-propagated electromagnetic noises. The following countermeasures must be taken:</p> <ol style="list-style-type: none"> <li>(1) Install easily affected devices as far away as possible from the inverter.</li> <li>(2) Run easily affected signal cables as far away as possible from the inverter and its I/O cables.</li> <li>(3) Do not run the signal cables and power cables (inverter I/O cables) in parallel with each other and do not bundle them.</li> <li>(4) Set the EMC filter ON/OFF connector of the inverter to the ON position. (Refer to <a href="#">page 66</a>.)</li> <li>(5) Inserting a line noise filter into the output suppresses the radiated noise from the cables.</li> <li>(6) Use shielded cables as signal cables and power cables and run them in individual metal conduits to produce further effects.</li> </ol> |
| (d)(e)(f)              | <p>When the signal cables are run in parallel with or bundled with the power cables, magnetic and static induction noises may be propagated to the signal cables to cause malfunction of the devices and the following countermeasures must be taken:</p> <ol style="list-style-type: none"> <li>(1) Install easily affected devices as far away as possible from the inverter.</li> <li>(2) Run easily affected signal cables as far away as possible from the inverter and its I/O cables.</li> <li>(3) Do not run the signal cables and power cables (inverter I/O cables) in parallel with each other and do not bundle them.</li> <li>(4) Use shielded cables as signal cables and power cables and run them in individual metal conduits to produce further effects.</li> </ol>   |
| (g)                    | <p>When the power supplies of the peripheral devices are connected to the power supply of the inverter in the same line, inverter-generated noises may flow back through the power supply cables to cause malfunction of the devices and the following countermeasures must be taken:</p> <ol style="list-style-type: none"> <li>(1) Set the EMC filter ON/OFF connector of the inverter to the ON position. (Refer to <a href="#">page 66</a>.)</li> <li>(2) Install the line noise filter (FR-BLF, FR-BSF01) to the power cables (output cables) of the inverter.</li> </ol>  |
| (h)                    | <p>When a closed loop circuit is formed by connecting the peripheral device wiring to the inverter, leakage currents may flow through the earthing (grounding) cable of the inverter to malfunction the device. In that case, disconnecting the earthing (grounding) cable from the device may stop the malfunction of the device.</p>  |

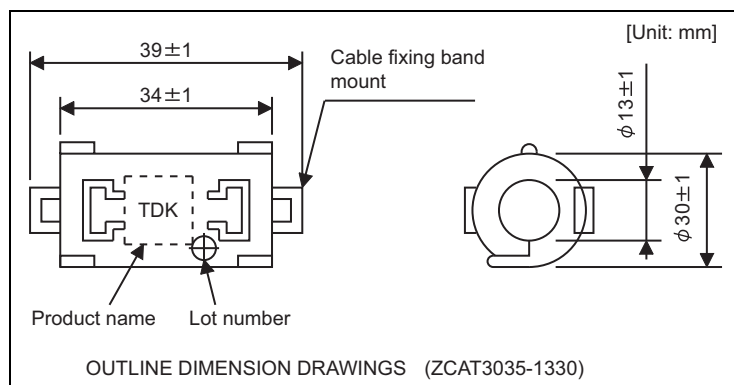
## • Data line filter

Data line filter is effective as an EMI countermeasure. Provide a data line filter for the detector cable, etc.

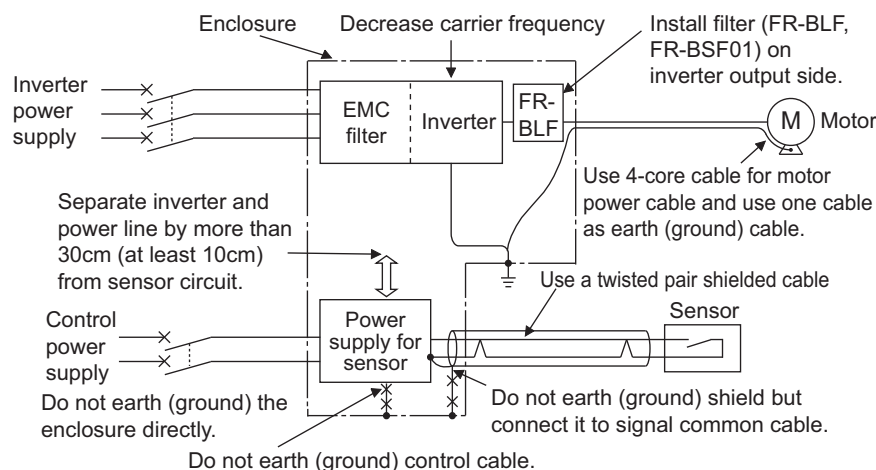
<Example> Data line filter : ZCAT3035-1330 (by TDK)  
: ESD-SR-250 (by NEC TOKIN)  
Impedance (ZCAT3035-1330)

| Impedance (Ω) |                |
|---------------|----------------|
| 10 to 100 MHz | 100 to 500 MHz |
| 80            | 150            |

The impedance values above are reference values, and not guaranteed values.



## • EMI countermeasure example



## REMARKS

- For compliance with the EU EMC Directive, refer to [page 105](#).

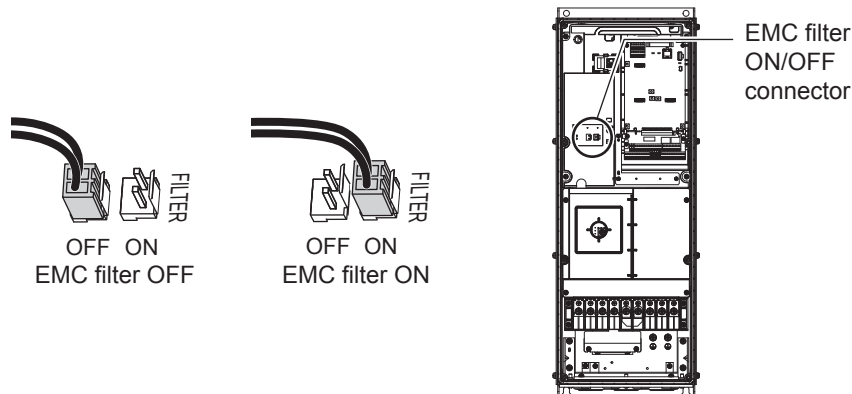
### 3.1.3 Built-in EMC filter

This inverter is equipped with a built-in EMC filter (capacitive filter) and a common mode choke.

Those filters are effective in reducing air-propagated noise on the input side of the inverter.

To enable the EMC filter, fit the EMC filter ON/OFF connector to the ON position. The FM type is initially set to "disabled" (OFF), and the CA type to "enabled" (ON).

The input side common mode choke, which is built in the inverter, is always enabled regardless of the EMC filter ON/OFF connector setting.



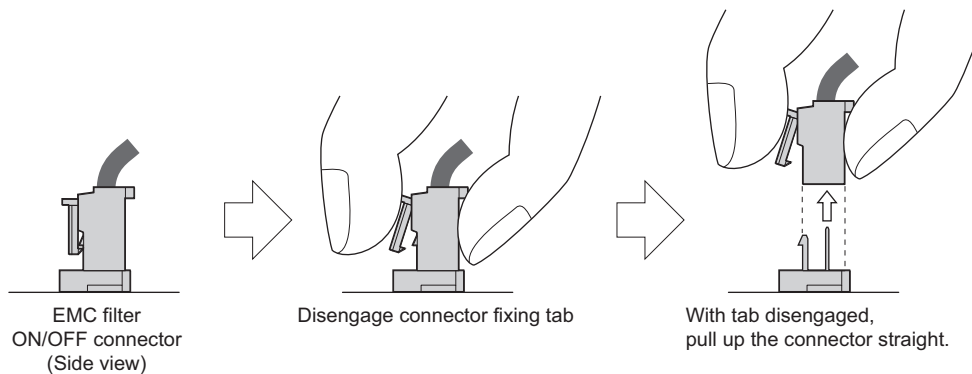
- Switching ON/OFF the filter

(1) Before removing a front cover, check to make sure that the indication of the inverter operation panel is OFF, wait for at least 10 minutes after the power supply has been switched OFF, and check that there is no residual voltage using a tester or the like.

(2) When disconnecting the connector, push the fixing tab and pull the connector straight without pulling the cable or forcibly pulling the connector with the tab fixed.

When installing the connector, also engage the fixing tab securely.


(If it is difficult to disconnect the connector, use a pair of needle-nose pliers, etc.)



#### REMARKS

- Fit the connector to either ON or OFF position.
- Enabling (turning ON) the EMC filter increases leakage current. (Refer to [page 63](#).)

## WARNING

 While power is ON or when the inverter is running, do not open the front cover. Otherwise you may get an electric shock.

## 3.2 Power supply harmonics

### 3.2.1 Power supply harmonics

The inverter may generate power supply harmonics from its converter circuit to affect the power generator, power factor correction capacitor etc. Power supply harmonics are different from noise and leakage currents in source, frequency band and transmission path. Take the following countermeasure suppression techniques.

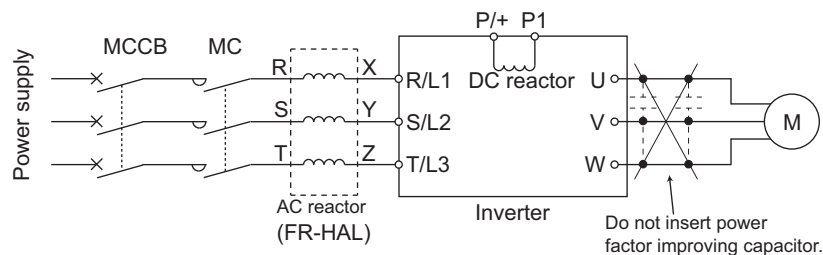
- The differences between harmonics and noises

| Item                        | Harmonics  | Noise   |
|-----------------------------|--|---|
| Frequency                   | Normally 40th to 50th degrees or less (3 kHz or less). | High frequency (several 10 kHz to 1 GHz order).                                       |
| Location                    | To-electric channel, power impedance.                  | To-space, distance, wiring path   |
| Quantitative understanding  | Theoretical calculation possible.                      | Random occurrence, quantitative grasping difficult.                                   |
| Generated amount            | Nearly proportional to the load capacity.              | Changes with the current variation ratio. (Gets larger as switching speed increases.) |
| Affected equipment immunity | Specified by standards per equipment.                  | Different depending on maker's equipment specifications.                              |
| Countermeasure              | Provide an AC reactor.                                 | Increase distance.  |

#### • Countermeasures

The harmonic current generated from the inverter to the input side differs according to various conditions such as the wiring impedance, whether a reactor is used or not, and output frequency and output current on the load side.

For the output frequency and output current, we understand that this should be calculated in the conditions under the rated load at the maximum operating frequency.



#### REMARKS

- The power factor improving capacitor and surge suppressor on the inverter output side may be overheated or damaged by the harmonic components of the inverter output. Also, since an excessive current flows in the inverter to activate overcurrent protection, do not provide a capacitor and surge suppressor on the inverter output side when the motor is driven by the inverter. For power factor improvement, install a reactor on the inverter input side.

## 3.2.2 Harmonic suppression guidelines in Japan

Harmonic currents flow from the inverter to a power receiving point via a power transformer. The Harmonic Suppression Guidelines was established to protect other consumers from these outgoing harmonic currents.

The three-phase 200 V input specifications 3.7 kW or lower were previously covered by "the Harmonic Suppression Guidelines for Household Appliances and General-purpose Products" and other models were covered by "the Harmonic Suppression Guidelines for Consumers Who Receive High Voltage or Special High Voltage". However, the transistorized inverter has been excluded from the target products covered by "the Harmonic Suppression Guidelines for Household Appliances and General-purpose Products" in January 2004 and "the Harmonic Suppression Guideline for Household Appliances and General-purpose Products" was repealed on September 6, 2004.

All capacity and all models of general-purpose inverter used by specific consumers are now covered by "the Harmonic Suppression Guidelines for Consumers Who Receive High Voltage or Special High Voltage" (hereinafter referred to as "the Specific Consumer Guidelines").

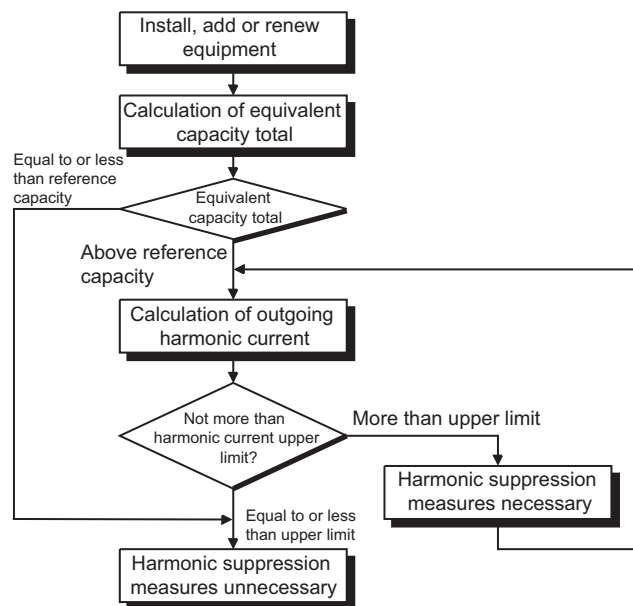
"Specific Consumer Guidelines"

This guideline sets forth the maximum harmonic currents outgoing from a high-voltage or especially high-voltage receiving consumer who will install, add or renew harmonic generating equipment. If any of the maximum values is exceeded, this guideline requires that consumer to take certain suppression measures.

**Table 1 Maximum Values of Outgoing Harmonic Currents per 1kW Contract Power**

| Received power voltage | 5th | 7th  | 11th | 13th | 17th | 19th | 23rd | Over 23rd |
|------------------------|-----|------|------|------|------|------|------|-----------|
| 6.6 kV                 | 3.5 | 2.5  | 1.6  | 1.3  | 1.0  | 0.9  | 0.76 | 0.70      |
| 22 kV                  | 1.8 | 1.3  | 0.82 | 0.69 | 0.53 | 0.47 | 0.39 | 0.36      |
| 33 kV                  | 1.2 | 0.86 | 0.55 | 0.46 | 0.35 | 0.32 | 0.26 | 0.24      |

### (1) Application of the specific consumer guidelines



**Table 2 Conversion factors for FR-A806 series**

| Classification | Circuit type                                |  | Conversion coefficient Ki |
|----------------|---|--|---------------------------|
| 3              | Three-phase bridge<br>(Capacitor smoothing) | With reactor (DC side) *1                  | K33 = 1.8                 |
|                |   | With reactors (AC, DC sides) *1            | K34 = 1.4                 |
| 5              | Self-excitation three-phase bridge          | When a high power factor converter is used | K5 = 0                    |

**Table 3 Equivalent Capacity Limits**

| Received power voltage | Reference capacity |
|------------------------|--------------------|
| 6.6 kV                 | 50 kVA             |
| 22/33 kV               | 300 kVA            |
| 66 kV or more          | 2000 kVA           |

**Table 4 Harmonic content (Values of the fundamental current is 100%)**

| Reactor                | 5th | 7th | 11th | 13th | 17th | 19th | 23rd | 25th |
|------------------------|-----|-----|------|------|------|------|------|------|
| Used (DC side) *1      | 30  | 13  | 8.4  | 5.0  | 4.7  | 3.2  | 3.0  | 2.2  |
| Used (AC, DC sides) *1 | 28  | 9.1 | 7.2  | 4.1  | 3.2  | 2.4  | 1.6  | 1.4  |

\*1 A DC reactor is built in the FR-A806.

- Calculation of equivalent capacity P0 of harmonic generating equipment

"Equivalent capacity" is the capacity of a 6-pulse converter converted from the capacity of consumer's harmonic generating equipment and is calculated by the following equation: If the sum of equivalent capacities is higher than the limit in Table 3, harmonics must be calculated with the following procedure:

$$P0 = \sum (Ki \times Pi) \text{ [kVA]}$$

Ki: Conversion coefficient (Refer to Table 2)

Pi: Rated capacity of harmonic generating equipment \* [kVA]

i: Number indicating the conversion circuit type

\* Rated capacity: Determined by the capacity of the applied motor and found in Table 5. The rated capacity used here is used to calculate the generated harmonic amount and is different from the power supply capacity required for actual inverter drive.

- Calculation of outgoing harmonic current

Outgoing harmonic current = fundamental wave current (value converted from received power voltage) × operation ratio × harmonic content

• Operation ratio: Operation ratio = actual load factor × operation time ratio during 30 minutes

• Harmonic content: Found in Table 4.

Table 5 Rated capacities and outgoing harmonic currents of inverter-driven motors

| Applicable motor (kW) | Rated current (A) | Fundamental wave current converted from 6.6 kV (mA) | Rated capacity (kVA) | Outgoing harmonic current converted from 6.6 kV (mA)<br>(With a DC reactor, 100% operation ratio) |       |       |       |       |       |       |       |
|-----------------------|-------------------|---|----------------------|---|-------|-------|-------|-------|-------|-------|-------|
|                       | 400 V             |   |                      | 5th   | 7th   | 11th  | 13th  | 17th  | 19th  | 23rd  | 25th  |
| 0.4                   | 0.81              | 49  | 0.57                 | 14.7  | 6.37  | 4.116 | 2.45  | 2.303 | 1.568 | 1.47  | 1.078 |
| 0.75                  | 1.37              | 83  | 0.97                 | 24.9  | 10.79 | 6.972 | 4.15  | 3.901 | 2.656 | 2.49  | 1.826 |
| 1.5                   | 2.75              | 167   | 1.95                 | 50.1  | 21.71 | 14.03 | 8.35  | 7.849 | 5.344 | 5.01  | 3.674 |
| 2.2                   | 3.96              | 240   | 2.81                 | 72  | 31.20 | 20.16 | 12    | 11.28 | 7.68  | 7.2   | 5.28  |
| 3.7                   | 6.50              | 394   | 4.61                 | 118.2   | 51.22 | 33.10 | 19.7  | 18.52 | 12.61 | 11.82 | 8.67  |
| 5.5                   | 9.55              | 579   | 6.77                 | 173.7   | 75.27 | 48.64 | 28.95 | 27.21 | 18.53 | 17.37 | 12.74 |
| 7.5                   | 12.8              | 776   | 9.07                 | 232.8   | 100.9 | 65.18 | 38.8  | 36.47 | 24.83 | 23.28 | 17.07 |
| 11                    | 18.5              | 1121  | 13.1                 | 336.3   | 145.7 | 94.16 | 56.05 | 52.69 | 35.87 | 33.63 | 24.66 |
| 15                    | 24.9              | 1509  | 17.6                 | 452.7   | 196.2 | 126.8 | 75.45 | 70.92 | 48.29 | 45.27 | 33.2  |
| 18.5                  | 30.7              | 1860  | 21.8                 | 558   | 241.8 | 156.2 | 93    | 87.42 | 59.52 | 55.8  | 40.92 |
| 22                    | 36.6              | 2220  | 25.9                 | 666   | 288.6 | 186.5 | 111   | 104.3 | 71.04 | 66.6  | 48.84 |
| 30                    | 49.0              | 2970  | 34.7                 | 891   | 386.1 | 249.5 | 148.5 | 139.6 | 95.04 | 89.1  | 65.34 |
| 37                    | 60.4              | 3660  | 42.8                 | 1098  | 475.8 | 307.4 | 183   | 172   | 117.1 | 109.8 | 80.52 |
| 45                    | 73.5              | 4450  | 52.1                 | 1335  | 578.5 | 373.8 | 222.5 | 209.2 | 142.4 | 133.5 | 97.9  |
| 55                    | 89.9              | 5450  | 63.7                 | 1635  | 708.5 | 457.8 | 272.5 | 256.2 | 174.4 | 163.5 | 119.9 |
| 75                    | 123               | 7455  | 87.2                 | 2237  | 969.2 | 626.2 | 372.8 | 350.4 | 238.6 | 223.7 | 164   |
| 90                    | 147               | 8909  | 104                  | 2673  | 1158  | 748.4 | 445.5 | 418.7 | 285.1 | 267.3 | 196   |
| 110                   | 179               | 10848   | 127                  | 3254  | 1410  | 911.2 | 542.5 | 509.9 | 347.1 | 325.4 | 238.7 |
| 132                   | 216               | 13091   | 153                  | 3927  | 1702  | 1100  | 654.6 | 615.3 | 418.9 | 392.7 | 288   |
| 160                   | 258               | 15636   | 183                  | 4691  | 2033  | 1313  | 781.8 | 734.9 | 500.4 | 469.1 | 344   |
| 220                   | 355               | 21515   | 252                  | 6455  | 2797  | 1807  | 1076  | 1011  | 688.5 | 645.5 | 473.3 |
| 250                   | 403               | 24424   | 286                  | 7327  | 3175  | 2052  | 1221  | 1148  | 781.6 | 732.7 | 537.3 |
| 280                   | 450               | 27273   | 319                  | 8182  | 3545  | 2291  | 1364  | 1282  | 872.7 | 818.2 | 600   |
| 315                   | 506               | 30667   | 359                  | 9200  | 3987  | 2576  | 1533  | 1441  | 981.3 | 920   | 674.7 |
| 355                   | 571               | 34606   | 405                  | 10382   | 4499  | 2907  | 1730  | 1627  | 1107  | 1038  | 761.3 |
| 400                   | 643               | 38970   | 456                  | 11691   | 5066  | 3273  | 1949  | 1832  | 1247  | 1169  | 857.3 |
| 450                   | 723               | 43818   | 512                  | 13145   | 5696  | 3681  | 2191  | 2059  | 1402  | 1315  | 964   |
| 500                   | 804               | 48727   | 570                  | 14618   | 6335  | 4093  | 2436  | 2290  | 1559  | 1462  | 1072  |
| 560                   | 900               | 54545   | 638                  | 16363   | 7091  | 4582  | 2727  | 2564  | 1745  | 1636  | 1200  |

## Installation of a reactor

- Determining if a countermeasure is required

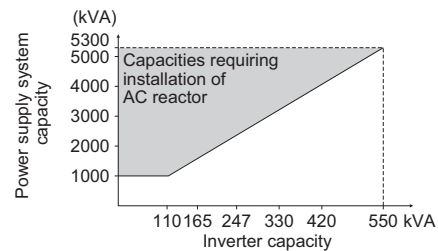
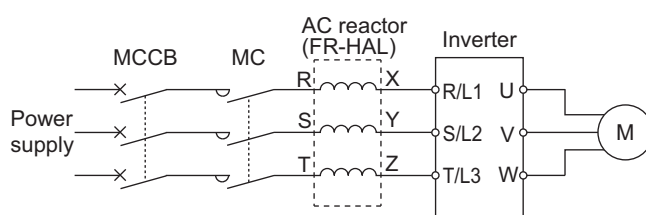
A countermeasure for harmonics is required if the following condition is satisfied: outgoing harmonic current > maximum value per 1 kW contract power × contract power

- Harmonic suppression techniques

| No. | Item   | Description  |
|-----|--|--|
| 1   | Reactor installation (FR-HAL)                    | Because a DC reactor is built in on the DC side of this product, outgoing harmonic current can be suppressed. By installing an AC reactor (FR-HAL) on the AC side of the inverter, the outgoing harmonic current suppression performance can be improved.  |
| 2   | Installation of power factor improving capacitor | When used with a reactor connected in series, the power factor improving correction capacitor can absorb harmonic currents.  |
| 3   | Transformer multi-phase operation                | Use two transformers with a phase angle difference of 30° as in $\Delta$ - $\Delta$ and $\Delta$ - $\Delta$ combinations to provide an effect corresponding to 12 pulses, reducing low-degree harmonic currents.   |
| 4   | Passive filter (AC filter)                       | A capacitor and a reactor are used together to reduce impedances at specific frequencies. Harmonic currents are expected to be absorbed greatly by using this technique.   |
| 5   | Active filter                                    | This filter detects the current in a circuit generating a harmonic current and generates a harmonic current equivalent to a difference between that current and a fundamental wave current to suppress the harmonic current at the detection point. Harmonic currents are expected to be absorbed greatly by using this technique. |

## 3.3 Installation of a reactor

When the inverter is connected near a large-capacity power transformer (1000 kVA or more) or when a power factor correction capacitor is to be switched over, an excessive peak current may flow in the power input circuit, damaging the converter circuit. To prevent this, always install an optional AC reactor (FR-HAL).







## 3.5 Countermeasures against deterioration of the 400 V class motor insulation

In the PWM type inverter, a surge voltage attributable to wiring constants is generated at the motor terminals. Especially in a 400 V class motor, the surge voltage may deteriorate the insulation. When the 400 V class motor is driven by the inverter, consider the following countermeasures:

### (1) Countermeasures for induction motors

It is recommended to take one of the following countermeasures:

- Rectifying the motor insulation and limiting the PWM carrier frequency according to the wiring length  
For the 400 V class motor, use an insulation-enhanced motor.  
Specifically,  
-Order a "400 V class inverter-driven insulation-enhanced motor".  
-For the dedicated motor such as the constant-torque motor and low-vibration motor, use an "inverter-driven dedicated motor".  
-Set **Pr.72 PWM frequency selection** as indicated below according to the wiring length.

|                                      | Wiring length          |                    |                    |
|--------------------------------------|------------------------|--------------------|--------------------|
|                                      | 50 m or shorter        | 50 m to 100 m      | Longer than 100 m  |
| <b>Pr.72 PWM frequency selection</b> | 15 (14.5 kHz) or lower | 9 (9 kHz) or lower | 4 (4 kHz) or lower |

- Suppressing the surge voltage on the inverter side  
-Connect the surge voltage suppression filter (FR-ASF-H/FR-BMF-H) to the output side.

### (2) Countermeasures for PM motors

- When the wiring length exceeds 50 m, set "9" (6 kHz) or less in **Pr.72 PWM frequency selection**.

#### REMARKS

- For the details of **Pr.72 PWM frequency selection**, refer to the FR-A800 Instruction Manual (Detailed).
- For the details of the surge voltage suppression filter (FR-ASF-H/FR-BMF-H), refer to the Instruction Manual of each option.
- A surge voltage suppression filter (FR-ASF-H/FR-BMF-H) can be used under V/F control and Advanced magnetic flux vector control.
- The carrier frequency is limited during PM sensorless vector control. (Refer to the FR-A800 Instruction Manual (Detailed).)

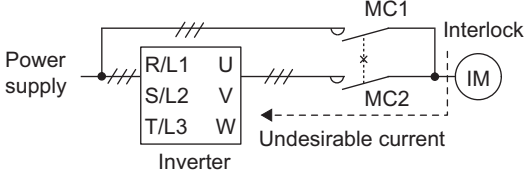
## 3.6 Checklist before starting operation

The FR-A800 series inverter is a highly reliable product, but incorrect peripheral circuit making or operation/handling method may shorten the product life or damage the product.

Before starting operation, always recheck the following points.

| Checkpoint  | Countermeasure   | Refer to page | Check by user |
|---|--|---------------|---------------|
| Crimping terminals are insulated.   | Use crimping terminals with insulation sleeves to wire the power supply and the motor.   | -             |               |
| The wiring between the power supply (R/L1, S/L2, T/L3) and the motor (U, V, W) is correct.  | Application of power to the output terminals (U, V, W) of the inverter will damage the inverter. Never perform such wiring.  | 23            |               |
| No wire offcuts are left from the time of wiring.   | Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean.<br>When drilling mounting holes in a wall etc., take caution not to allow chips and other foreign matters to enter the inverter.  | -             |               |
| The main circuit cable gauge is correctly selected.   | Use an appropriate cable gauge to suppress a voltage drop to 2% or less.<br>If the wiring distance is long between the inverter and motor, a voltage drop in the main circuit will cause the motor torque to decrease especially during the output of a low frequency.   | 25            |               |
| The total wiring length within the specified length.  | Keep the total wiring length within the specified length.<br>In long distance wiring, charging currents due to stray capacitance in the wiring may degrade the fast-response current limit operation or cause the equipment on the inverter's output side to malfunction. Pay attention to the total wiring length.  | 25            |               |
| Countermeasures are taken against EMI.  | The input/output (main circuit) of the inverter includes high frequency components, which may interfere with the communication devices (such as AM radios) used near the inverter. In such case, activate the EMC filter (turn ON the EMC filter ON/OFF connector) to minimize interference.   | 66            |               |
| On the inverter's output side, none of the power factor correction capacitor, surge suppressor, or radio noise filter is installed.               | Such installation will cause the inverter to trip or the capacitor and surge suppressor to be damaged. If any of the above devices is connected, immediately remove it.  | -             |               |
| When performing an inspection or rewiring on the product energized once, the operator has waited long enough after shutting off the power supply. | For a short time after the power-OFF, a high voltage remains in the smoothing capacitor, and it is dangerous.<br>Before performing an inspection or rewiring, wait 10 minutes or longer after the power supply turns OFF, then confirm that the voltage across the main circuit terminals P/+ and N/- of the inverter is 30 VDC or less using a tester, etc.   | -             |               |
| The inverter's output side has no short circuit or ground fault occurring.  | A short circuit or ground fault on the inverter's output side may damage the inverter module.<br>Fully check the insulation resistance of the circuit prior to inverter operation since repeated short circuits caused by peripheral circuit inadequacy or a ground fault caused by wiring inadequacy or reduced motor insulation resistance may damage the inverter module.<br>Fully check the to-earth (ground) insulation and phase-to-phase insulation of the inverter's output side before power-ON. Especially for an old motor or use in hostile atmosphere, make sure to check the motor insulation resistance, etc. | -             |               |
| The circuit is not configured to use the inverter's input-side magnetic contactor to start/stop the inverter frequently.                          | Since repeated inrush currents at power ON will shorten the life of the converter circuit, frequent starts and stops of the magnetic contactor must be avoided. Turn ON/OFF the inverter's start signals (STF, STR) to run/stop the inverter.  | 71            |               |
| The voltage applied to the inverter I/O signal circuits is within the specifications.   | Application of a voltage higher than the permissible voltage to the inverter I/O signal circuits or opposite polarity may damage the I/O devices. Especially check the wiring to prevent the speed setting potentiometer from being connected incorrectly to short circuit the terminals 10E and 5.  | 28            |               |

## Checklist before starting operation

| Checkpoint  | Countermeasure   | Refer to page | Check by user |
|---|--|---------------|---------------|
| When using the electronic bypass operation, electrical and mechanical interlocks are provided between the electronic bypass contactors MC1 and MC2. | <p>When using a switching circuit as shown below, chattering due to mis-configured sequence or arc generated at switching may allow undesirable current to flow in and damage the inverter. Mis-wiring may also damage the inverter.<br/>(The commercial power supply operation is not available with vector control dedicated motors (SF-V5RU, SF-THY) nor with PM motors.)</p>  <p>When switching to the commercial power supply operation while a failure such as an output short circuit is occurring between the magnetic contactor MC2 and the motor, the damage may further spread.</p>                                     | -             |               |
| A countermeasure is provided for power restoration after a power failure.   | If the machine must not be restarted when power is restored after a power failure, provide an MC in the inverter's input side and also make up a sequence which will not switch ON the start signal. If the start signal (start switch) remains ON after a power failure, the inverter will automatically restart as soon as the power is restored.  | -             |               |
| When using the vector control, an encoder is properly installed.  | The encoder must be directly connected to a motor shaft without any backlash. (Real sensorless vector control, PM sensorless vector control do not require an encoder.)  | 48            |               |
| A magnetic contactor (MC) is installed on the inverter's input side.  | <p>On the inverter's input side, connect an MC for the following purposes:</p> <ul style="list-style-type: none"> <li>To disconnect the inverter from the power supply at activation of a protective function or at malfunctioning of the driving system (emergency stop, etc.).</li> <li>To prevent any accident due to an automatic restart at power restoration after an inverter stop made by a power failure.</li> <li>To separate the inverter from the power supply to ensure safe maintenance and inspection work.</li> </ul> <p>If using an MC for emergency stop during motor driving, select an MC regarding the drive unit input side current as JEM1038-AC-3 class rated current.</p>                   | 71            |               |
| The magnetic contactor on the inverter's output side is properly handled.   | Switch the magnetic contactor between the inverter and motor only when both the inverter and motor are at a stop.  | 71            |               |
| When using a PM motor, a low-voltage manual contactor is installed on the inverter's output side.   | <p>When a failure occurs between the MC2 and motor, make sure to provide a protection circuit, such as using the OH signal input.</p> <p>In an application, such as fan and blower, where the motor is driven by the load, a low-voltage manual contactor must be connected at the inverter's output side, and wiring and inspection must be performed while the contactor is open. Otherwise you may get an electric shock.</p>   | 71            |               |
| An EMI countermeasure is provided for the frequency setting signals.  | <p>If electromagnetic noise generated from the inverter causes frequency setting signal to fluctuate and the motor rotation speed to be unstable when changing the motor speed with analog signals, the following countermeasures are effective:</p> <ul style="list-style-type: none"> <li>Do not run the signal cables and power cables (inverter I/O cables) in parallel with each other and do not bundle them.</li> <li>Run signal cables as far away as possible from power cables (inverter I/O cables).</li> <li>Use shielded cables.</li> <li>Install a ferrite core on the signal cable (Example: ZCAT3035-1330 by TDK).</li> </ul>  | 64            |               |
| A countermeasure is provided for an overload operation.   | When performing frequent starts/stops by the inverter, rise/fall in the temperature of the transistor element of the inverter will repeat due to a repeated flow of large current, shortening the life from thermal fatigue. Since thermal fatigue is related to the amount of current, the life can be increased by reducing current at locked condition, starting current, etc. Reducing current may extend the service life but may also cause torque shortage, which leads to a start failure. Adding a margin to the current can eliminate such a condition. For an induction motor, use an inverter of a higher capacity (up to two ranks). For a PM motor, use an inverter and PM motor of higher capacities. | -             |               |
| The specifications and rating match the system requirements.  | Make sure that the specifications and rating match the system requirements.  | 98            |               |

## 3.7 Failsafe system which uses the inverter

When a fault is detected by the protective function, the protective function activates and outputs a fault signal. However, a fault signal may not be output at an inverter's fault occurrence when the detection circuit or output circuit fails, etc. Although Mitsubishi assures the best quality products, provide an interlock which uses inverter status output signals to prevent accidents such as damage to the machine when the inverter fails for some reason. Also at the same time consider the system configuration where a failsafe from outside the inverter, without using the inverter, is enabled even if the inverter fails.

### (1) Interlock method which uses the inverter status output signals

By combining the inverter output signals to provide an interlock as shown below, an inverter failure can be detected.

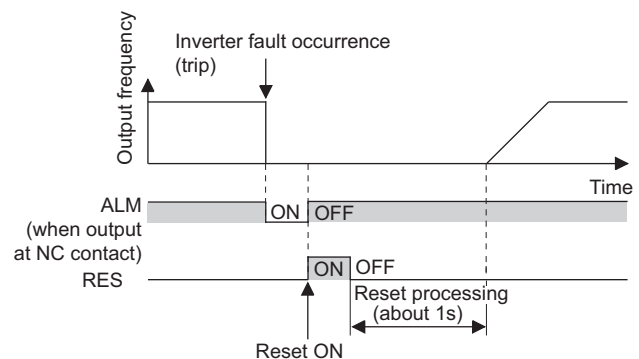
| No. | Interlock method                       | Check method   | Used signals  |
|-----|--|--|---|
| a   | Inverter protective function operation | Operation check of an alarm contact.<br>Circuit error detection by negative logic. | Fault output signal (ALM signal)  |
| b   | Inverter operating status              | Operation ready signal check.  | Operation ready signal (RY signal)  |
| c   | Inverter running status                | Logic check of the start signal and running signal.                                | Start signal (STF signal, STR signal)<br>Running signal (RUN signal)                  |
| d   | Inverter running status                | Logic check of the start signal and output current.                                | Start signal (STF signal, STR signal)<br>Output current detection signal (Y12 signal) |

#### (a) Checking by the output of the inverter fault signal

When the inverter's protective function activates and the inverter trips, the fault output signal (ALM signal) is output. (ALM signal is assigned to terminal A1B1C1 in the initial setting).

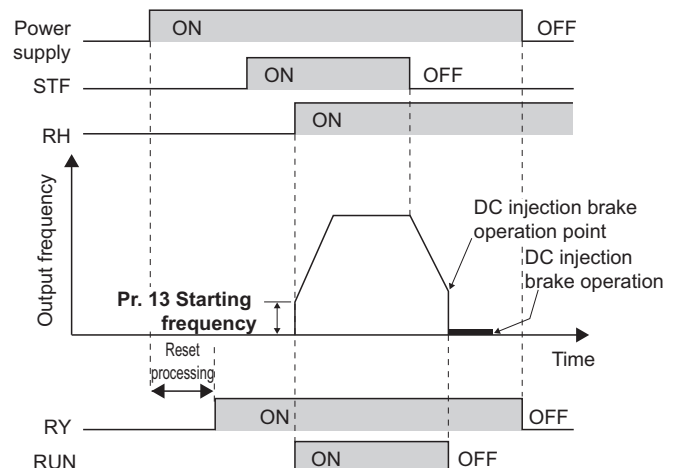
With this signal, check that the inverter operates properly.

In addition, negative logic can be set. (ON when the inverter is normal, OFF when the fault occurs.)



#### (b) Checking the inverter operating status by the inverter operation ready completion signal

Operation ready signal (RY signal) is output when the inverter power is ON and the inverter becomes operative. Check if the RY signal is output after powering ON the inverter.



#### (c) Checking the inverter operating status by the start signal input to the inverter and inverter running signal

The inverter running signal (RUN signal) is output when the inverter is running. (RUN signal is assigned to terminal RUN in the initial setting.) Check if RUN signal is being output while inputting a start signal to the inverter. (STF signal is a forward rotation signal, and STR is a reverse rotation signal.) Even after the start signal is turned OFF, the RUN signal is kept output until the inverter makes the motor to decelerate and to stop. For the logic check, configure a sequence considering the inverter's deceleration time.

## Failsafe system which uses the inverter

- (d) Checking the motor operating status by the start signal input to the inverter and inverter output current detection signal
- The output current detection signal (Y12 signal) is output when the inverter operates and currents flow in the motor. Check if Y12 signal is being output while inputting a start signal to the inverter. (STF signal is a forward rotation signal, and STR is a reverse rotation signal.) The Y12 signal is initially set to be output at 150% rated inverter current. Adjust the level to around 20% using no load current of the motor as reference with **Pr.150 Output current detection level**. Like the inverter running signal (RUN signal), even after the start signal is turned OFF, the RUN signal is kept output until the inverter makes the motor to decelerate and to stop. For the logic check, configure a sequence considering the inverter's deceleration time.

| Output signal | Pr.190 to Pr.196 setting |                |
|---------------|--------------------------|----------------|
|               | Positive logic           | Negative logic |
| ALM           | 99                       | 199            |
| RY            | 11                       | 111            |
| RUN           | 0                        | 100            |
| Y12           | 12                       | 112            |

- When using various signals, assign the functions to **Pr.190 and Pr.196 (output terminal function selection)** referring to the table on the left.

### REMARKS

- Changing the terminal assignment using **Pr.190 and Pr.196 (output terminal function selection)** may affect the other functions. Set parameters after confirming the function of each terminal.
- For the details of the parameters and signals, refer to the FR-A800 Instruction Manual (Detailed).

### (2) Backup method outside the inverter

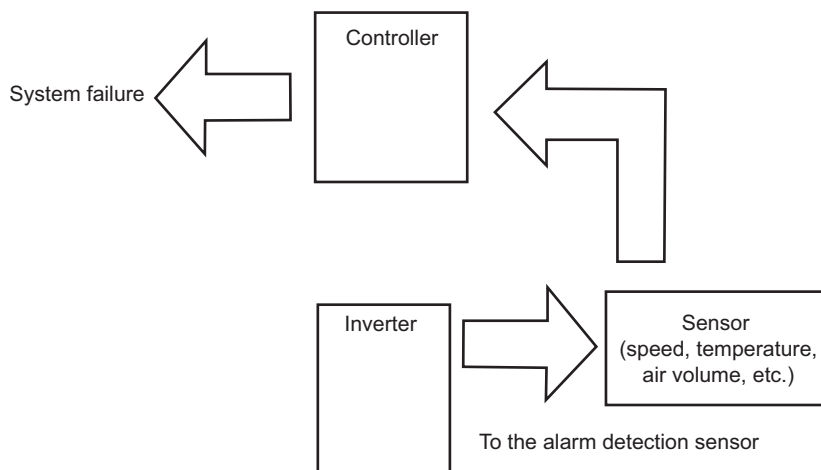
Even if the interlock is provided by the inverter status signal, enough failsafe is not ensured depending on the failure status of the inverter itself. For example, if an inverter CPU fails in a system interlocked with the inverter's fault, start, and RUN signals, no fault signal will be output and the RUN signal will be kept ON because the inverter CPU is down. Provide a speed detector to detect the motor speed and current detector to detect the motor current and consider the backup system such as performing a check as below according to the level of importance of the system.

#### (a) Start signal and actual operation check

Check the motor running and motor current while the start signal is input to the inverter by comparing the start signal to the inverter and detected speed of the speed detector or detected current of the current detector. Note that the current is flowing through the motor while the motor coasts to stop, even after the inverter's start signal is turned OFF. For the logic check, configure a sequence considering the inverter's deceleration time. In addition, it is recommended to check the three-phase current when using the current detector.

#### (b) Command speed and actual operation check

Check for a gap between the actual speed and commanded speed by comparing the inverter's speed command and the speed detected by the speed detector.



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# **PROTECTIVE FUNCTIONS**

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This chapter explains the "PROTECTIVE FUNCTIONS" that operates in this product.

Always read the instructions before using the equipment.

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|            |  |           |
|------------|--|-----------|
| <b>4.1</b> | <b>Inverter fault and alarm indications .....</b>          | <b>78</b> |
| <b>4.2</b> | <b>Reset method for the protective functions.....</b>      | <b>78</b> |
| <b>4.3</b> | <b>Faults history and the list of fault displays .....</b> | <b>79</b> |

## 4.1 Inverter fault and alarm indications

- When the inverter detects a fault, depending on the nature of the fault, the operation panel displays an error message or warning, or a protective function activates to trip the inverter.
- When any fault occurs, take an appropriate corrective action, then reset the inverter, and resume the operation.  
Restarting the operation without a reset may break or damage the inverter.
- When a protective function activates, note the following points.

| Item                      | Description   |
|---------------------------|---|
| Fault output signal       | Opening the magnetic contactor (MC) provided on the input side of the inverter at a fault occurrence shuts off the control power to the inverter, therefore, the fault output will not be retained. |
| Fault or alarm indication | When a protective function activates, the operation panel displays a fault indication.  |
| Operation restart method  | While a protective function is activated, the inverter output is kept shutoff. Reset the inverter to restart the operation.   |

- Inverter fault or alarm indications are categorized as below.

| Displayed item | Description  |
|----------------|--|
| Error message  | A message regarding an operational fault and setting fault by the operation panel (FR-DU08-01) and parameter unit (FR-PU07). The inverter does not trip. |
| Warning        | The inverter does not trip even when a warning. However, failure to take appropriate measures will lead to a fault.                                      |
| Alarm          | The inverter does not trip. An Alarm (LF) signal can be output with a parameter setting.   |
| Fault          | A protective function activates to trip the inverter and output a Fault (ALM) signal.  |


### REMARKS

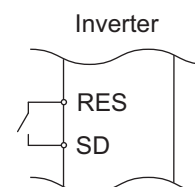
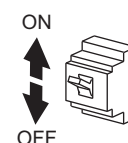
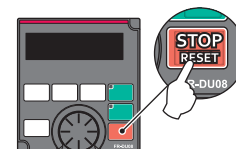
- For the details of fault displays and other malfunctions, also refer to the FR-A800 Instruction Manual (Detailed).
- Past eight faults can be displayed using the setting dial. (Refer to [page 43](#))

## 4.2 Reset method for the protective functions

Reset the inverter by performing any of the following operations. Note that the accumulated heat value of the electronic thermal relay function and the number of retries are cleared (erased) by resetting the inverter.

The inverter recovers about 1 s after the reset is released.

- On the operation panel, press  to reset the inverter.  
(This may only be performed when a fault occurs.)
- Switch the power OFF once, then switch it ON again.
- Turn ON the reset signal (RES) for 0.1 s or more. (If the RES signal is kept ON, "Err" appears (flickers) to indicate that the inverter is in a reset status.)



### REMARKS

- OFF status of the start signal must be confirmed before resetting the inverter fault. Resetting an inverter fault with the start signal ON restarts the motor suddenly.

## 4.3 Faults history and the list of fault displays

For details, refer to the FR-A800 Instruction Manual (Detailed).

| Operation panel indication |                                   |                                | Name   |
|----------------------------|-----------------------------------|--------------------------------|--|
| Error message              | E-----                            | E----                          | Faults history   |
|                            | HOLD                              | HOLD                           | Operation panel lock                                       |
|                            | LOCd                              | LOCD                           | Password locked  |
|                            | Er 1to<br>Er 4<br>Er 8            | Er1 to<br>Er4<br>Er8           | Parameter write error                                      |
|                            | rE 1to<br>rE 4<br>rE 6 to<br>rE 8 | rE1 to<br>rE4<br>rE6 to<br>rE8 | Copy operation error                                       |
|                            | Err.                              | Err.                           | Error  |
|                            | Warning                           | OL                             | OL   |
| oL                         |                                   | oL                             | Stall prevention (overvoltage)                             |
| TH                         |                                   | TH                             | Electronic thermal relay function pre-alarm                |
| PS                         |                                   | PS                             | PU stop  |
| MT 1to<br>MT 3             |                                   | MT1 to<br>MT3                  | Maintenance signal output                                  |
| SL                         |                                   | SL                             | Speed limit indication                                     |
| SA                         |                                   | SA                             | Safety stop  |
| UF                         |                                   | UF                             | USB host error   |
| EV                         |                                   | EV                             | 24 V external power supply operation                       |
| HP 1                       |                                   | HP1                            | Home position return setting error                         |
| HP2                        |                                   | HP2                            | Home position return uncompleted                           |
| HP3                        |                                   | HP3                            | Home position return parameter setting error               |
| Alarm                      |                                   | FN                             | FN   |
|                            | FN2                               | FN2                            | Internal-circulation fan alarm                             |
| Fault                      | E. OC 1                           | E.OC1                          | Overcurrent trip during acceleration                       |
|                            | E. OC2                            | E.OC2                          | Overcurrent trip during constant speed                     |
|                            | E. OC3                            | E.OC3                          | Overcurrent trip during deceleration or stop               |
|                            | E. OV 1                           | E.OV1                          | Regenerative overvoltage trip during acceleration          |
|                            | E. OV2                            | E.OV2                          | Regenerative overvoltage trip during constant speed        |
|                            | E. OV3                            | E.OV3                          | Regenerative overvoltage trip during deceleration or stop  |
|                            | E. THF                            | E.THT                          | Inverter overload trip (electronic thermal relay function) |
|                            | E. THM                            | E.THM                          | Motor overload trip (electronic thermal relay function)    |
|                            | E. FIN                            | E.FIN                          | Heatsink overheat  |
|                            | E. IPF                            | E.IPF                          | Instantaneous power failure                                |
|                            | E. UVF                            | E.UVT                          | Undervoltage   |
|                            | E. ILF                            | E.ILF                          | Input phase loss   |
|                            | E. OLF                            | E.OLT                          | Stall prevention stop                                      |

| Operation panel indication |                          | Name  |
|----------------------------|--------------------------|---|
| E. GF                      | E.GF                     | Output side earth (ground) fault overcurrent  |
| E. SOT                     | E. SOT                   | Loss of synchronism detection   |
| E. LF                      | E.LF                     | Output phase loss   |
| E. OHT                     | E.OHT                    | External thermal relay operation  |
| E. PTC                     | E.PTC                    | PTC thermistor operation  |
| E. OPT                     | E.OPT                    | Option fault  |
| E. OP 1                    | E.OP1                    | Communication option fault  |
| E. 1 to<br>E. 3            | E. 1 to<br>E. 3          | Option fault  |
| E. PE                      | E.PE                     | Parameter storage device fault  |
| E. PUE                     | E.PUE                    | PU disconnection  |
| E. RET                     | E.RET                    | Retry count excess  |
| E. PE2                     | E.PE2                    | Parameter storage device fault  |
| E. 5 to<br>E. 7<br>E. CPU  | E. 5 to<br>E. 7<br>E.CPU | CPU fault   |
| E. CTE                     | E.CTE                    | Operation panel power supply short circuit<br>RS-485 terminals power supply short circuit |
| E. P24                     | E.P24                    | 24 VDC power fault  |
| E. CDO                     | E.CDO                    | Abnormal output current detection   |
| E. IOH                     | E.IOH                    | Inrush current limit circuit fault  |
| E. SER                     | E.SER                    | Communication fault (inverter)  |
| E. AIE                     | E.AIE                    | Analog input fault  |
| E. OS                      | E.OS                     | Overspeed occurrence  |
| E. OSD                     | E.OSD                    | Speed deviation excess detection  |
| E. ECT                     | E.ECT                    | Signal loss detection   |
| E. OD                      | E.OD                     | Excessive position fault  |
| E. Mb 1 to<br>E. Mb 7      | E.MB1 to<br>E.MB7        | Brake sequence fault  |
| E. EP                      | E.EP                     | Encoder phase fault   |
| E. BE                      | E.BE                     | Brake transistor alarm detection  |
| E. USB                     | E.USB                    | USB communication fault   |
| E. 11                      | E.11                     | Opposite rotation deceleration fault  |
| E. 13<br>E. PBT            | E.13<br>E.PBT            | Internal circuit fault  |
| E. SAF                     | E.SAF                    | Safety circuit fault  |
| E. IAH                     | E.IAH                    | Abnormal internal temperature   |
| E. LCI                     | E.LCI                    | 4 mA input fault  |
| E. PCH                     | E.PCH                    | Pre-charge fault  |
| E. PID                     | E.PID                    | PID signal fault  |
| E. 16 to<br>E. 20          | E.16 to<br>E.20          | User definition error by the PLC function   |



# MEMO

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# **5 PRECAUTIONS FOR MAINTENANCE AND INSPECTION**

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This chapter explains the "PRECAUTIONS FOR MAINTENANCE AND INSPECTION" for this product.

Always read the instructions before using the equipment.

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|            |   |           |
|------------|---|-----------|
| <b>5.1</b> | <b>Inspection item.....</b>   | <b>82</b> |
| <b>5.2</b> | <b>Measurement of main circuit voltages, currents and powers...</b> | <b>92</b> |

Inspection item

The inverter is a static unit mainly consisting of semiconductor devices. Daily inspection must be performed to prevent any fault from occurring due to the adverse effects of the operating environment, such as temperature, humidity, dust, dirt and vibration, changes in the parts with time, service life, and other factors.

•Precautions for maintenance and inspection

When accessing the inverter for inspection, wait for at least 10 minutes after the power supply has been switched OFF, and then make sure that the voltage across the main circuit terminals P/+ and N/- of the inverter is not more than 30 VDC using a tester, etc.

5.1 Inspection item

5.1.1 Daily inspection

Basically, check for the following faults during operation.

- Motor operation fault
- Improper installation environment
- Cooling system fault
- Abnormal vibration, abnormal noise
- Abnormal overheat, discoloration

5.1.2 Periodic inspection

Check the areas inaccessible during operation and requiring periodic inspection.

Consult us for periodic inspection.

- Check for cooling system fault ..... Clean the air filter, etc.
- Check the tightening and retighten ..... The screws and bolts may become loose due to vibration, temperature changes, etc. Check and tighten them.  
Tighten them according to the specified tightening torque. (Refer to [page 25.](#))
- Check the conductors and insulating materials for corrosion and damage
- Measure the insulation resistance
- Check and change the cooling fan, internal fan and relay
- Check for dew condensation ..... A sudden temperature change may cause water droplets (dew condensation) to form inside the inverter. Using the inverter with dew condensed inside may cause a failure.
- Check for ingress of water or dust..... If the waterproof or dustproof performance is impaired, water or dust may get into the inverter. Using the inverter with water or dust remaining inside may cause a failure.
- Inspection and replacement of the packing ..... Changes such as in temperature may cause aging degradation of the packing rubber material, which may impair the waterproof and dustproof performances.

REMARKS

- When using the safety stop function, periodic inspection is required to confirm that safety function of the safety system operates correctly.  
For more details, refer to the Safety stop function instruction manual (BCN-A23228-001).

## 5.1.3 Daily and periodic inspection

| Area of inspection                  | Inspection item                           | Description   | Inspection interval |                  | Corrective action at fault occurrence  | Check by the user |
|-------------------------------------|---|---|---------------------|------------------|--|-------------------|
|                                     |   |   | Daily               | Periodic *3      |  |                   |
| General                             | Surrounding environment                   | Check the surrounding air temperature, humidity, dirt, corrosive gas, oil mist, etc.  | ○                   |                  | Improve the environment.   |                   |
|                                     | Overall unit                              | Check for unusual vibration and noise.  | ○                   |                  | Check fault location and retighten.  |                   |
|                                     |   | Check for dirt, oil, and other foreign material. *1   | ○                   |                  | Clean.   |                   |
|                                     | Power supply voltage                      | Check that the main circuit voltages and control voltages are normal.*2   | ○                   |                  | Inspect the power supply.  |                   |
| Main circuit                        | General                                   | (1) Check with megger (across main circuit terminals and earth (ground) terminal).<br>(2) Check for loose screws and bolts.<br>(3) Check for overheat traces on the parts.<br>(4) Check for stain.                |                     | ○<br>○<br>○<br>○ | Contact the manufacturer.<br>Retighten.<br>Contact the manufacturer.<br>Clean. |                   |
|                                     | Conductors, cables                        | (1) Check conductors for distortion.<br>(2) Check cable sheaths for breakage and deterioration (crack, discoloration, etc.).  |                     | ○<br>○           | Contact the manufacturer.<br>Contact the manufacturer.                         |                   |
|                                     | Transformer/reactor                       | Check for unusual odor and abnormal increase of whining sound.  | ○                   |                  | Stop the equipment and contact the manufacturer.                               |                   |
|                                     | Terminal block                            | Check for a damage.   |                     | ○                | Stop the equipment and contact the manufacturer.                               |                   |
|                                     | Smoothing aluminum electrolytic capacitor | (1) Check for liquid leakage.<br>(2) Check for safety valve projection and bulge.<br>(3) Visual check and judge by the life check of the main circuit capacitor. (Refer to <a href="#">page 86.</a> )             |                     | ○<br>○<br>○      | Contact the manufacturer.<br>Contact the manufacturer.                         |                   |
|                                     | Relay/contactors                          | Check that the operation is normal and no chattering sound is heard.  |                     | ○                | Contact the manufacturer.  |                   |
|                                     | Resistor                                  | (1) Check for crack in resistor insulation.<br>(2) Check for a break in the cable.  |                     | ○<br>○           | Contact the manufacturer.<br>Contact the manufacturer.                         |                   |
| Control circuit, protective circuit | Operation check                           | (1) Check that the output voltages across phases are balanced while operating the inverter alone.<br>(2) Check that no fault is found in protective and display circuits in a sequence protective operation test. |                     | ○<br>○           | Contact the manufacturer.<br>Contact the manufacturer.                         |                   |
|                                     | Components check                          | Overall   |                     | ○<br>○           | Stop the equipment and contact the manufacturer.<br>Contact the manufacturer.  |                   |
|                                     |   | Aluminum electrolytic capacitor   |                     | ○<br>○           | Contact the manufacturer.  |                   |

## Inspection item

| Area of inspection                            | Inspection item              | Description  | Inspection interval |             | Corrective action at fault occurrence  | Check by the user |
|---|------------------------------|--|---------------------|-------------|--|-------------------|
|   |                              |  | Daily               | Periodic *3 |  |                   |
| Cooling system                                | Cooling fan                  | (1) Check for unusual vibration and noise.   | ○                   |             | Replace the fan.   |                   |
|   | Internal fan                 | (2) Check for loose screws and bolts.<br>(3) Check for stain.  |                     | ○<br>○      | Check fault location and retighten.<br>Clean.  |                   |
|   | Heatsink                     | (1) Check for clogging.<br>(2) Check for stain.  |                     | ○<br>○      | Clean.<br>Clean.   |                   |
| Display                                       | Indication                   | (1) Check that display is normal.<br>(2) Check for stain.  | ○                   | ○           | Contact the manufacturer.<br>Clean.  |                   |
|   | Meter                        | Check that reading is normal.  | ○                   |             | Stop the equipment and contact the manufacturer.   |                   |
| Load motor                                    | Operation check              | Check for vibration and abnormal increase in operation noise.  | ○                   |             | Stop the equipment and contact the manufacturer.   |                   |
| Waterproof performance, dustproof performance | Operation panel              | (1) Check that it is installed.<br>(2) Check for deformation or fracture.<br>(3) Check for loose fixing screws.    | ○                   | ○<br>○      | Install it securely. (Refer to <a href="#">page 45</a> )<br>Stop the equipment and contact the manufacturer.<br>Retighten.     |                   |
|   | Front cover and wiring cover | (1) Check that it is installed.<br>(2) Check for deformation or fracture.<br>(3) Check for loose fixing screws.    | ○                   | ○<br>○      | Install it securely. (Refer to <a href="#">page 15, 24</a> )<br>Stop the equipment and contact the manufacturer.<br>Retighten. |                   |
|   | Packing                      | (1) Check for stain.<br>(2) Check for damage.<br>(3) Check for degradation (crack, discoloration, or deformation). |                     | ○<br>○<br>○ | Clean.<br>Stop the equipment and contact the manufacturer.<br>Stop the equipment and contact the manufacturer.                 |                   |
|   | Inside the inverter          | (1) Check for dew condensation.<br>(2) Check for ingress of water or dust.   |                     | ○<br>○      | Wipe off the dew.<br>Stop the equipment and contact the manufacturer.  |                   |

\*1 Oil component of the heat dissipation grease used inside the inverter may leak out. The oil component, however, is not flammable, corrosive, nor conductive and is not harmful to humans. Wipe off such oil component.

\*2 It is recommended to install a voltage monitoring device for checking the voltage of the power supplied to the inverter.

\*3 One to two years of periodic inspection cycle is recommended. However, it differs according to the installation environment. Consult us for periodic inspection.

### REMARKS

- Continuous use of a leaked, deformed, or degraded smoothing aluminum electrolytic capacitor (as shown in the table above) may lead to a burst, breakage or fire. Replace such a capacitor without delay.

## 5.1.4 Checking the inverter and converter modules

### (1) Preparation

- Disconnect the external power supply cables (R/L1, S/L2, T/L3) and motor cables (U, V, W).
- Prepare a tester. (For the resistance measurement, use the 100  $\Omega$  range.)

### (2) Checking method

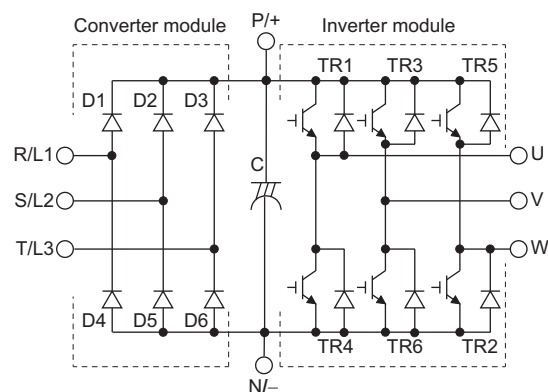
Change the polarity of the tester alternately at the inverter terminals R/L1, S/L2, T/L3, U, V, W, P/+, and N/- and check the electric continuity.

#### REMARKS

- Before measurement, check that the smoothing capacitor is discharged.
- At the time of electric discontinuity, the measured value is almost  $\infty$ . When there is an instantaneous electric continuity, due to the smoothing capacitor, the tester may not indicate  $\infty$ . At the time of electric continuity, the measured value is several  $\Omega$  to several tens of  $\Omega$ . If all measured values are almost the same, although these values are not constant depending on the module type and tester type, the modules are without fault.

### (3) Module device numbers and terminals to be checked

|                  |     | Tester polarity |           | Result        |     |      | Tester polarity |               | Result |
|------------------|-----|-----------------|-----------|---------------|-----|------|-----------------|---------------|--------|
|                  |     | $\oplus$        | $\ominus$ |               |     |      | $\oplus$        | $\ominus$     |        |
| Converter module | D1  | R/L1            | P/+       | Discontinuity | D4  | R/L1 | N/-             | Continuity    |        |
|                  |     | P/+             | R/L1      | Continuity    |     | N/-  | R/L1            | Discontinuity |        |
|                  | D2  | S/L2            | P/+       | Discontinuity | D5  | S/L2 | N/-             | Continuity    |        |
|                  |     | P/+             | S/L2      | Continuity    |     | N/-  | S/L2            | Discontinuity |        |
|                  | D3  | T/L3            | P/+       | Discontinuity | D6  | T/L3 | N/-             | Continuity    |        |
|                  |     | P/+             | T/L3      | Continuity    |     | N/-  | T/L3            | Discontinuity |        |
| Inverter module  | TR1 | U               | P/+       | Discontinuity | TR4 | U    | N/-             | Continuity    |        |
|                  |     | P/+             | U         | Continuity    |     | N/-  | U               | Discontinuity |        |
|                  | TR3 | V               | P/+       | Discontinuity | TR6 | V    | N/-             | Continuity    |        |
|                  |     | P/+             | V         | Continuity    |     | N/-  | V               | Discontinuity |        |
|                  | TR5 | W               | P/+       | Discontinuity | TR2 | W    | N/-             | Continuity    |        |
|                  |     | P/+             | W         | Continuity    |     | N/-  | W               | Discontinuity |        |



(Assumes the use of an analog meter.)

## 5.1.5 Cleaning

Always run the inverter in a clean status.

When cleaning the inverter, gently wipe dirty areas with a soft cloth immersed in neutral detergent or ethanol.

#### REMARKS

- Do not use solvent, such as acetone, benzene, toluene and alcohol, as these will cause the inverter surface paint to peel off.
- The display, etc. of the operation panel (FR-DU08-01) and parameter unit (FR-PU07) are vulnerable to detergent and alcohol. Therefore, avoid using them for cleaning.

## 5.1.6 Replacement of parts

The inverter consists of many electronic parts such as semiconductor devices.

The following parts may deteriorate with age because of their structures or physical characteristics, leading to reduced performance or fault of the inverter. For preventive maintenance, the parts must be replaced periodically.

Use the life check function as a guidance of parts replacement.

| Part name                        | Estimated lifespan*1 | Description                     |
|----------------------------------|----------------------|---------------------------------|
| Cooling fan, internal fan        | 10 years             | Replace (as required)           |
| Main circuit smoothing capacitor | 10 years*2           | Replace (as required)           |
| On-board smoothing capacitor     | 10 years*2           | Replace the board (as required) |
| Relays                           | —                    | As required                     |
| Packing                          | 2 years*3            | Replace (as required)           |

\*1 Estimated lifespan for when the yearly average surrounding air temperature is 35°C.  
(without corrosive gas, flammable gas, oil mist, dust and dirt etc.)

\*2 Output current: 80% of the inverter rating

\*3 The estimated lifespan is only a guide. To maintain the waterproof and dustproof performances of the inverter, daily and periodic inspections are recommended.

### REMARKS

- For parts replacement, contact the nearest Mitsubishi FA center.

### (1) Displaying the life of the inverter parts

The inverter diagnoses the main circuit capacitor, control circuit capacitor, cooling fan, internal fan, and inrush current limit circuit by itself and estimates their lives.

The self-diagnostic warning is output when the life span of each part is near its end. It gives an indication of replacement time.

**The life warning output can be used as a guideline for life judgment.**

| Parts                        | Judgment level  |
|------------------------------|---|
| Main circuit capacitor       | 85% of the initial capacity                                 |
| Control circuit capacitor    | Estimated remaining life 10%                                |
| Inrush current limit circuit | Estimated remaining life 10% (Power ON: 100,000 times left) |
| Cooling fan                  | Less than 50% of the specified speed.                       |

### REMARKS

- Refer to the FR-A800 Instruction Manual (Detailed) to perform the life check of the inverter parts.

## (2) Replacement procedure of the fan

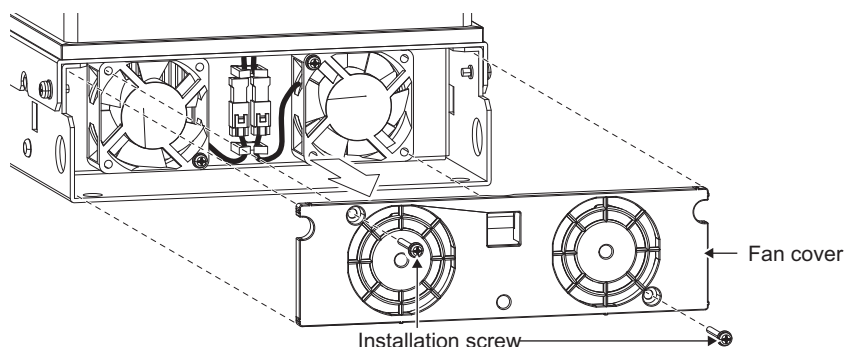
The replacement interval of the cooling fan used for cooling the parts generating heat such as the main circuit semiconductor is greatly affected by the surrounding air temperature. When unusual noise and/or vibration are noticed during inspection, the cooling fan must be replaced immediately.

### REMARKS

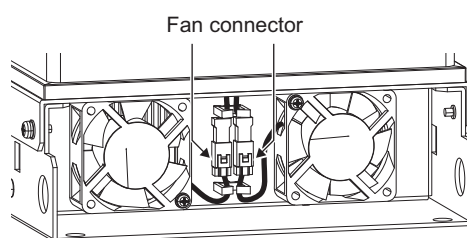
- Switch the power OFF before replacing fans. Even after the power supply is shut off, the inverter is charged and can cause an electric shock. Before replacing the fan, make sure to check that the voltage across inverter main circuit terminals P/+ and N/- has been dropped enough using a tester after 10 minutes or more after the power supply shutoff.

### •Removal of the cooling fan

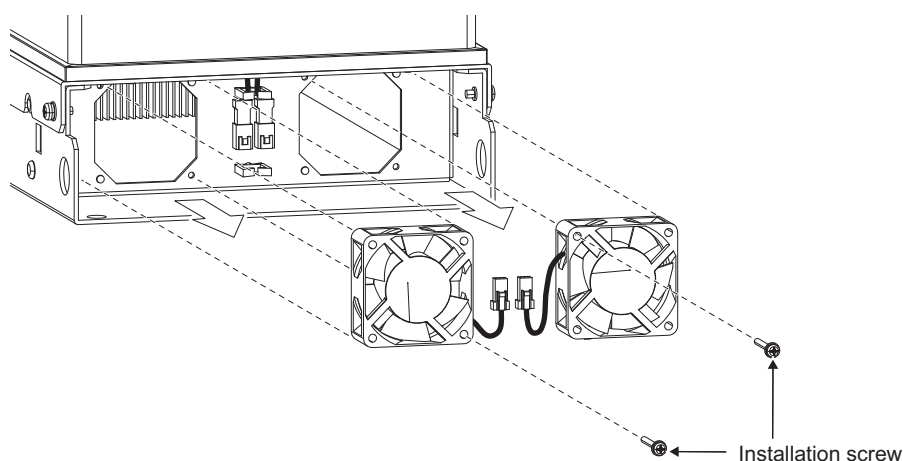
- 1) Remove the installation screws, and then remove the fan cover.



- 2) Disconnect the fan connectors.



- 3) Remove the installation screws, and then remove the fan.

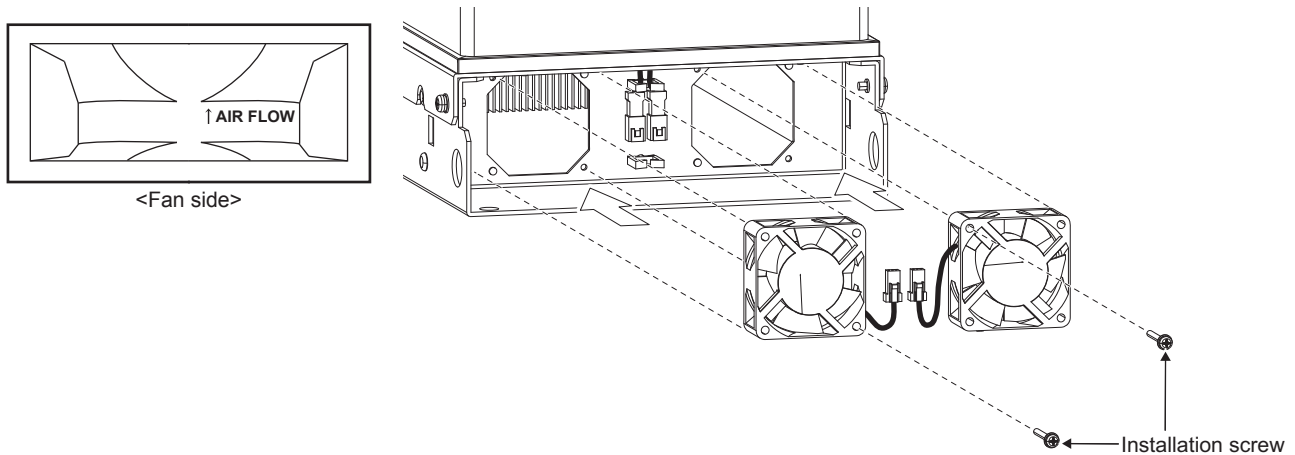




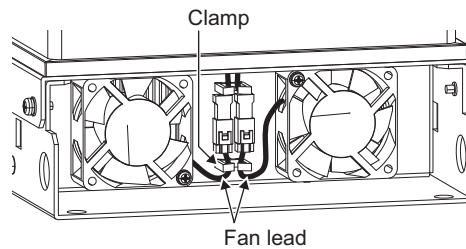
## Inspection item

### •Reinstallation of the cooling fan

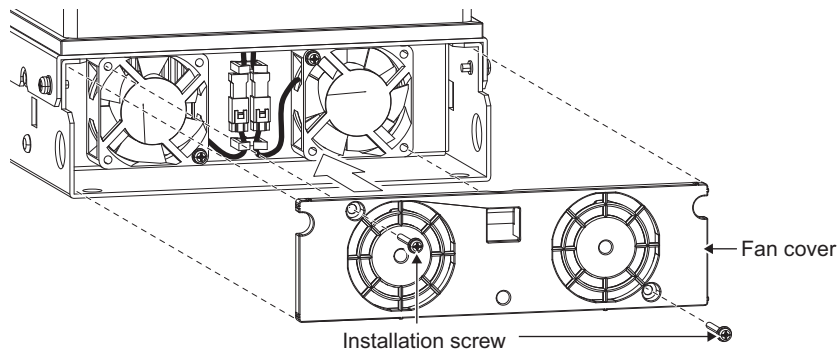
- 1) After confirming the orientation of the fan, reinstall the fan so that the "AIR FLOW" faces up. Then, fix the fan with the installation screws. (tightening torque 1.4 to 1.9 N•m)



- 2) Hook the fan lead on the clamp, and then reconnect the fan connector.



- 3) Attach the fan cover with the installation screws. (tightening torque 1.4 to 1.9 N•m)

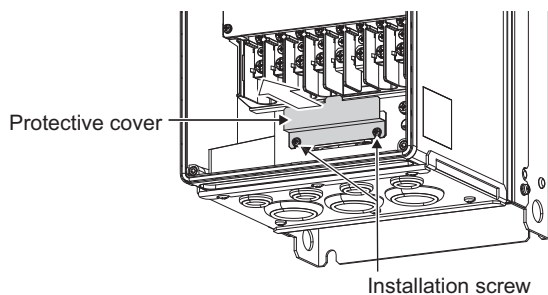


#### REMARKS

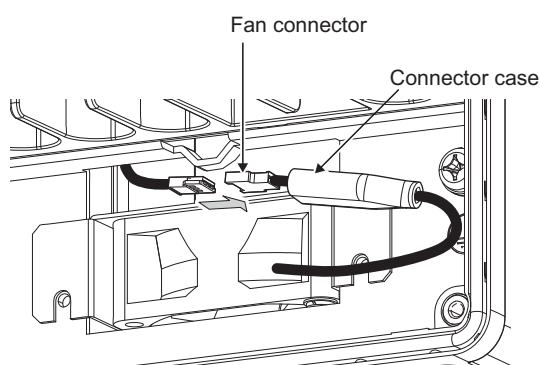
- Installing the fan in the opposite direction of air flow can cause the inverter life to be shorter.
- Prevent the cable from being caught when installing a fan.

### •Removal of the internal fan

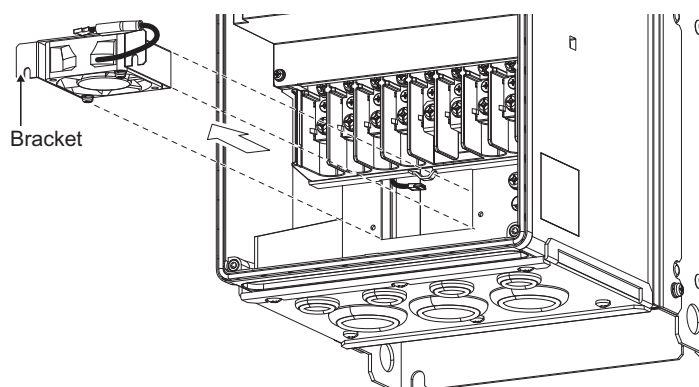
- 1) Remove the inverter front cover. (Refer to [page 15](#))
- 2) Remove the installation screws, and then remove the protective cover.



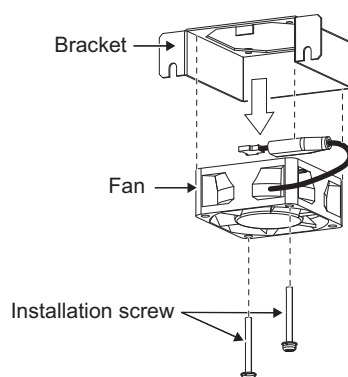
- 3) Move the fan connector case, and then remove the fan connector.



- 4) Remove the bracket.



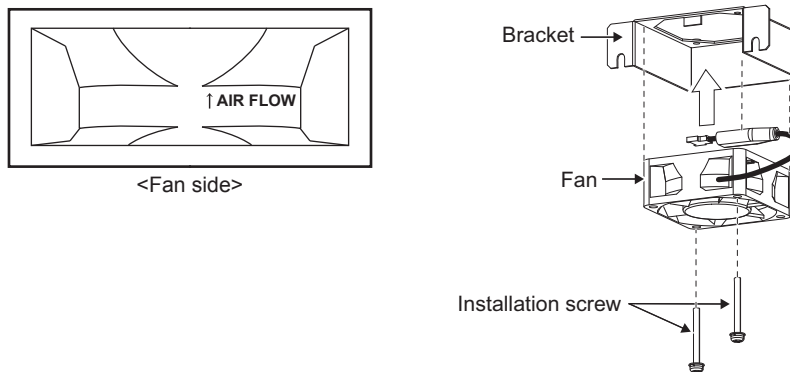
- 5) Remove the installation screws, and then remove the fan.



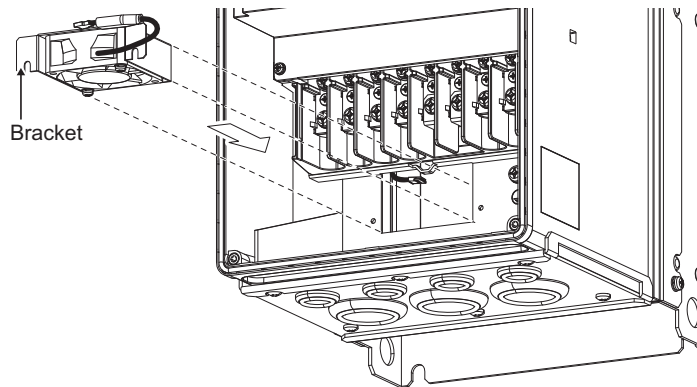
## Inspection item

### •Reinstallation of the internal fan

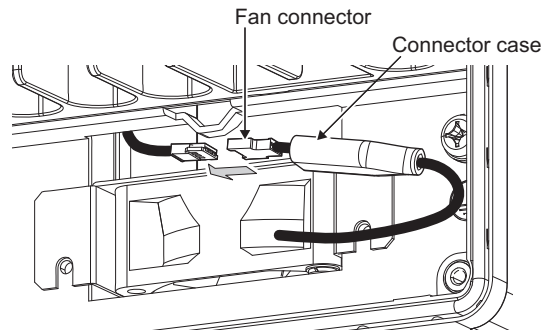
- 1) After confirming the orientation of the fan, fix the fan to the bracket with the installation screws so that the "AIR FLOW" faces up. (tightening torque 1.4 to 1.9 N•m)



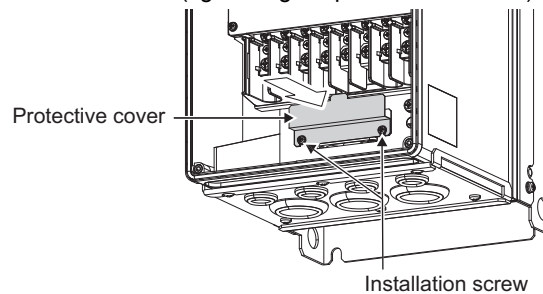
- 2) Attach the bracket to the inverter.



- 3) Reconnect the fan connector, and then place the connector case from the above.



- 4) Fix the protective cover with the installation screws. (tightening torque 1.4 to 1.9 N•m)



- 5) Reinstall the inverter front cover. (Refer to [page 15](#).)

#### REMARKS

- Installing the fan in the opposite direction of air flow can cause the inverter life to be shorter.
- Prevent the cable from being caught when installing a fan.
- The wiring may contact the fan and be damaged. Always insert the protective cover.

### (3) Smoothing capacitors

A large-capacity aluminum electrolytic capacitor is used for smoothing in the main circuit DC section, and an aluminum electrolytic capacitor is used for stabilizing the control power in the control circuit. Their characteristics are deteriorated by the adverse effects of ripple currents, etc. The replacement intervals greatly vary with the surrounding air temperature and operating conditions. When the inverter is operated in air-conditioned, normal environment conditions, replace the capacitors about every 10 years.

The appearance criteria for inspection are as follows:

- Case: Check the side and bottom faces for expansion.
- Sealing plate: Check for remarkable warp and extreme crack.
- Check for external crack, discoloration, liquid leakage, etc. Judge that the capacitor has reached its life when the measured capacitance of the capacitor reduced below 80% of the rating.

#### REMARKS

- The inverter diagnoses the main circuit capacitor and control circuit capacitor by itself and can judge their lives. (Refer to the FR-A800 Instruction manual (Detailed).)

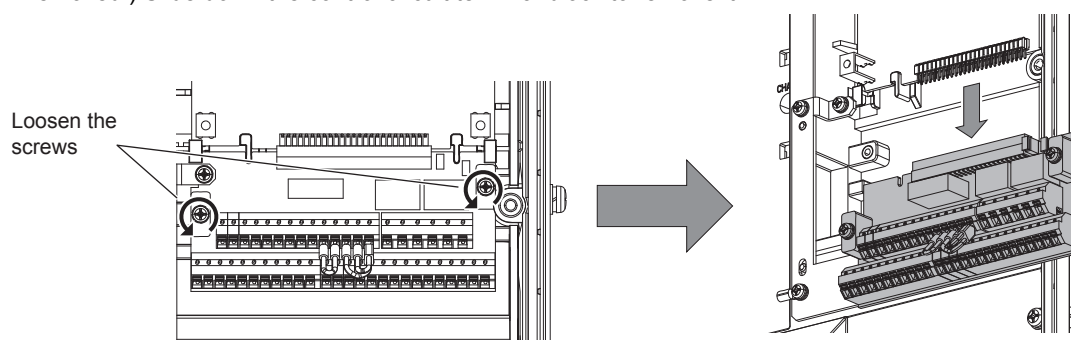
### (4) Relays

To prevent a contact fault, etc., relays must be replaced according to the cumulative number of switching times (switching life).

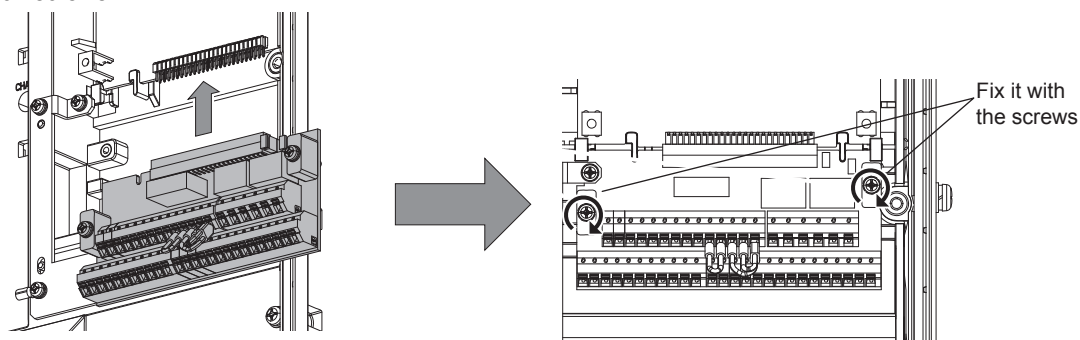
## 5.1.7 Inverter replacement

The inverter can be replaced with the control circuit wiring kept connected. Before replacement, remove the wiring cover of the inverter.

- 1) Loosen the two installation screws at the both side of the control circuit terminal block. (These screws cannot be removed.) Slide down the control circuit terminal block to remove it.



- 2) Be careful not to bend the pins of the inverter's control circuit connector, reinstall the control circuit terminal block and fix it with the installation screws.



#### REMARKS

- Before starting inverter replacement, switch power OFF, wait for at least 10 minutes, and then check the voltage with a tester and such to ensure safety.

## 5.2 Measurement of main circuit voltages, currents and powers

Since the voltages and currents on the inverter power supply and output sides include harmonics, measurement data depends on the instruments used and circuits measured.

When instruments for commercial frequency are used for measurement, measure the following circuits with the instruments given on the next page.

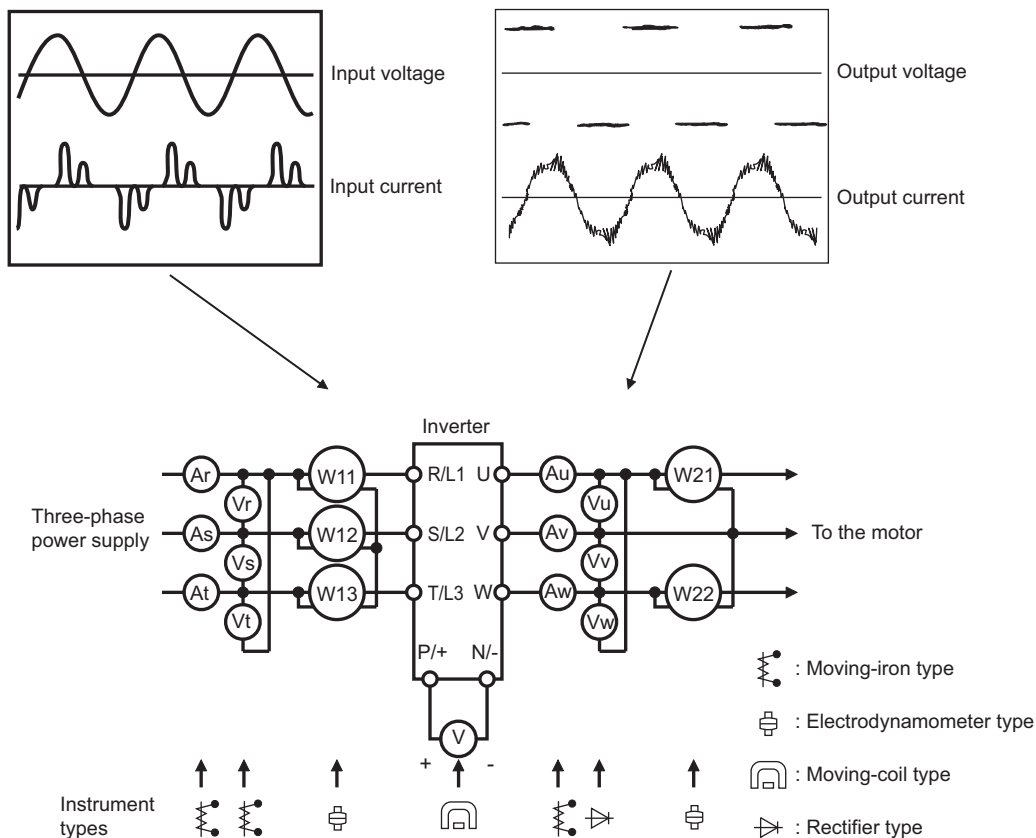
### REMARKS

- When installing meters etc. on the inverter output side

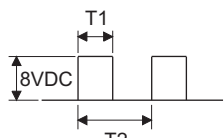
When the inverter-to-motor wiring length is large, especially small-capacity models, the meters and CTs may generate heat due to line-to-line leakage current. Therefore, choose the equipment which has enough allowance for the current rating.

To measure and display the output voltage and output current of the inverter, it is recommended to use the terminal AM and FM/CA output functions of the inverter.

### (1) Examples of measuring points and instruments



(2) Measuring points and instruments

| Item  | Measuring point   | Measuring instrument   | Remarks (reference measured value)   |                    |
|---|---|--|--|--------------------|
| Power supply voltage<br>V1  | Across R/L1 and S/L2,<br>S/L2 and T/L3,<br>T/L3 and R/L1  | Moving-iron type AC voltmeter*4  | Commercial power supply<br>Within permissible AC voltage fluctuation<br>(Refer to <a href="#">page 98</a> .)                     |                    |
| Power supply side<br>current<br>I1                                  | R/L1, S/L2, T/L3 line<br>current  | Moving-iron type AC ammeter*4  |  |                    |
| Power supply side<br>power<br>P1                                    | R/L1, S/L2, T/L3 and<br>Across R/L1 and S/L2,<br>S/L2 and T/L3,<br>T/L3 and R/L1  | Digital power meter (for inverter) or<br>electrodynamic type single-phase<br>wattmeter   | P1 = W11 + W12 + W13 (3-wattmeter method)  |                    |
| Power supply side<br>power factor<br>Pf1                            | Calculate after measuring power supply voltage, power supply side current and power supply side power.<br>$Pf_1 = \frac{P_1}{\sqrt{3}V_1 \times I_1} \times 100 \%$ |  |  |                    |
| Output side voltage<br>V2   | Across U and V, V<br>and W, and W and U   | Rectifier type AC voltage meter*1*4<br>(moving-iron type cannot<br>measure.)   | Difference between the phases is within 1% of the<br>maximum output voltage.   |                    |
| Output side current<br>I2   | U, V and W line<br>currents   | Moving-iron type AC ammeter*2*4  | Difference between the phases is 10% or lower of the<br>rated inverter current.  |                    |
| Output side power<br>P2   | U, V, W and<br>across U and V, V<br>and W   | Digital power meter (for inverter) or<br>electrodynamic type single-phase<br>wattmeter   | P2 = W21 + W22<br>2-wattmeter method (or 3-wattmeter method)   |                    |
| Output side power<br>factor<br>Pf2                                  | Calculate in similar manner to power supply side power factor.<br>$Pf_2 = \frac{P_2}{\sqrt{3}V_2 \times I_2} \times 100 \%$   |  |  |                    |
| Converter output  | Across P/+ and N/-  | Moving-coil type<br>(such as tester)   | Inverter LED is lit. 1.35 × V1   |                    |
| Frequency setting<br>signal   | Across 2, 4(+) and 5<br>Across 1(+) and 5   | Moving-coil type<br>(tester and such may be used.)<br>(internal resistance 50 kΩ or more)  | 0 to 10 VDC, 4 to 20 mA  | "5" is .<br>common |
| Frequency setting<br>power supply                                   | Across 10(+) and 5<br>Across 10E(+) and 5   |  | 0 to ±5 VDC and 0 to ±10 VDC   |                    |
|   |   |  | 5.2 VDC  |                    |
|   |   |  | 10 VDC   |                    |
| Frequency meter signal  | Across AM(+) and 5  |  | Approximately 10 VDC at maximum<br>frequency<br>(without frequency meter)  | "SD" is<br>common  |
|   | Across CA(+) and 5  |  | Approximately 20 mADC at maximum<br>frequency  |                    |
|   | Across FM(+) and<br>SD  |  | Approximately 5 VDC at maximum<br>frequency<br>(without frequency meter)   |                    |
|   |   | <br>Pulse width T1 : Adjust with <b>C0 (Pr.900)</b> .<br>Pulse cycle T2 : Set with <b>Pr.55</b> .<br>(frequency monitor only) |  |                    |
| Start signal<br>Select signal<br>Reset signal<br>Output stop signal | Across STF, STR,<br>RH, RM, RL, JOG,<br>RT, AU, STOP, CS,<br>RES, MRS(+) and<br>SD (for sink logic)   |  | When open<br>20 to 30 VDC<br>ON voltage: 1 V or less   |                    |
| Fault signal  | Across A1 and C1<br>Across B1 and C1  | Moving-coil type<br>(such as tester)   | Continuity check*3<br>[Normal] [Fault]<br>Across A1 and C1 Discontinuity Continuity<br>Across B1 and C1 Continuity Discontinuity |                    |

\*1 Use an FFT to measure the output voltage accurately. A tester or general measuring instrument cannot measure accurately.

\*2 When the carrier frequency exceeds 5 kHz, do not use this instrument since using it may increase eddy current losses produced in metal parts inside the instrument, leading to burnout. In this case, use an approximate-effective value type.

\*3 When the setting of **Pr.195 ABC1 terminal function selection** is the positive logic

\*4 A digital power meter (designed for inverter) can also be used to measure.

### 5.2.1 Measurement of powers

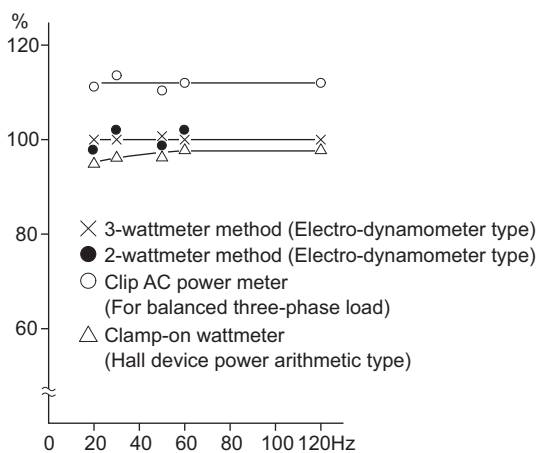
Use digital power meters (for inverter) for the both of inverter input and output side. Alternatively, measure using electrodynamic type single-phase wattmeters for the both of inverter input and output side in two-wattmeter or three-wattmeter method. As the current is liable to be imbalanced especially in the input side, it is recommended to use the three-wattmeter method.

Examples of measured value differences produced by different measuring meters are shown below.

An error will be produced by difference between measuring instruments, e.g. power calculation type and two- or three-wattmeter type three-phase wattmeter. When a CT is used in the current measuring side or when the meter contains a PT on the voltage measurement side, an error will also be produced due to the frequency characteristics of the CT and PT.

[Measurement conditions]

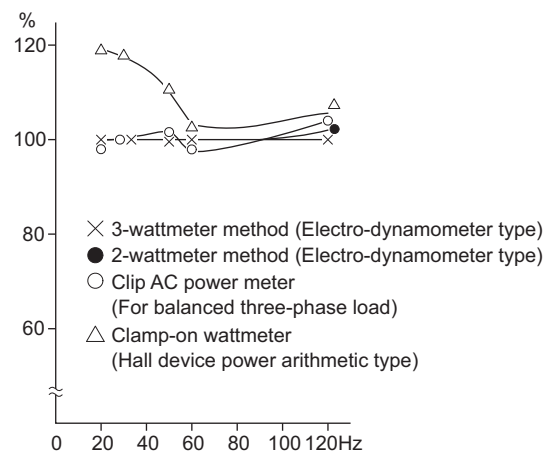
Constant output of 60 Hz or more frequency with a constant-torque (100%). The value obtained by the 3-wattmeter method with a 4-pole 3.7 kW induction motor is assumed to be 100%.



Example of measuring inverter input power

[Measurement conditions]

Constant output of 60 Hz or more frequency with a constant-torque (100%). The value obtained by the 3-wattmeter method with a 4-pole 3.7 kW induction motor is assumed to be 100%.



Example of measuring inverter output power

### 5.2.2 Measurement of voltages and use of PT

#### (1) Inverter input side

As the input side voltage has a sine wave and it is extremely small in distortion, accurate measurement can be made with an ordinary AC meter.

#### (2) Inverter output side

Since the output side voltage has a PWM-controlled rectangular wave, always use a rectifier type voltmeter. A needle type tester cannot be used to measure the output side voltage as it indicates a value much greater than the actual value. A moving-iron type meter indicates an effective value which includes harmonics and therefore the value is larger than that of the fundamental wave. The value monitored on the operation panel is the inverter-controlled voltage itself. Hence, that value is accurate and it is recommended to monitor values (analog output) using the operation panel.

#### (3) PT

No PT can be used in the output side of the inverter. Use a direct-reading meter. (A PT can be used in the input side of the inverter.)

## 5.2.3 Measurement of currents

Use moving-iron type meters on both the input and output sides of the inverter. However, if the carrier frequency exceeds 5 kHz, do not use that meter since an overcurrent losses produced in the internal metal parts of the meter will increase and the meter may burn out. In this case, use an approximate-effective value type.

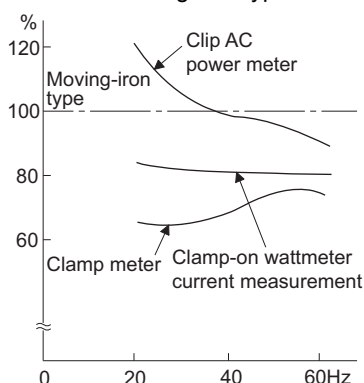
Since current on the inverter input side tends to be unbalanced, measurement of three phases is recommended. Correct value cannot be obtained by measuring only one or two phases. On the other hand, the unbalanced ratio of each phase of the output side current should be within 10%.

When a clamp ammeter is used, always use an effective value detection type. A mean value detection type produces a large error and may indicate an extremely smaller value than the actual value. The value monitored on the operation panel is accurate if the output frequency varies, and it is recommended to monitor values (provide analog output) using the operation panel.

Examples of measured value differences produced by different measuring meters are shown below.

[Measurement conditions]

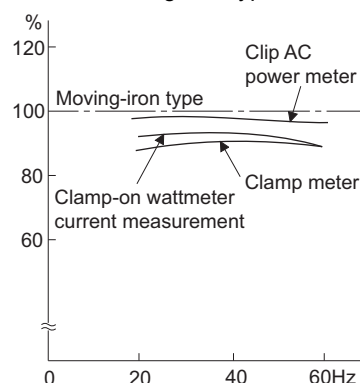
Indicated value of the moving-iron type ammeter is 100%.



Example of measuring inverter input current

[Measurement conditions]

Indicated value of the moving-iron type ammeter is 100%.



Example of measuring inverter output current

## 5.2.4 Use of CT and transducer

A CT may be used in both the input and output sides of the inverter. Use the one with the largest possible VA ability because an error will increase if the frequency gets lower.

When using a transducer, use the effective value calculation type which is immune to harmonics.

## 5.2.5 Measurement of inverter input power factor

Calculate using effective power and apparent power. A power-factor meter cannot indicate an exact value.

$$\begin{aligned} \text{Total power factor of the inverter} &= \frac{\text{Effective power}}{\text{Apparent power}} \\ &= \frac{\text{Three-phase input power found by the 3-wattmeter method}}{\sqrt{3} \times V \text{ (power supply voltage)} \times I \text{ (input current effective value)}} \end{aligned}$$

## 5.2.6 Measurement of converter output voltage (across terminals P and N)

The output voltage of the converter is output across terminals P and N and can be measured with a moving-coil type meter (tester). Although the voltage varies according to the power supply voltage, approximately 540 VDC to 600 VDC is output when no load is connected and voltage decreases during driving load operation.

When energy is regenerated from the motor during deceleration, for example, the converter output voltage rises to nearly 800 VDC to 900 VDC maximum.



### 5.2.7 Measurement of inverter output frequency

In the initial setting of the FM-type inverter, a pulse train proportional to the output frequency is output across the pulse train output terminals FM and SD of the inverter. This pulse train output can be counted by a frequency counter, or a meter (moving-coil type voltmeter) can be used to read the mean value of the pulse train output voltage. When a meter is used to measure the output frequency, approximately 5 VDC is indicated at the maximum frequency.

For detailed specifications of the pulse train output terminal FM, refer to the FR-A800 Instruction Manual (Detailed).

In the initial setting of the CA-type inverter, a pulse train proportional to the output frequency is output across the analog current output terminals CA and 5 of the inverter. Measure the current using an ammeter or tester.

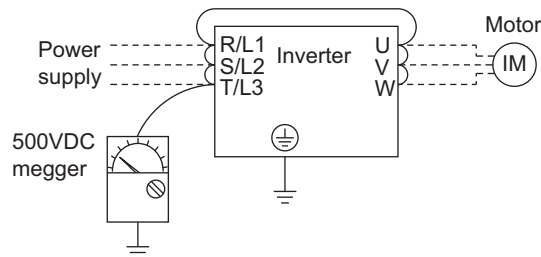
For detailed specifications of the analog current output terminal CA, refer to the FR-A800 Instruction Manual (Detailed).

### 5.2.8 Insulation resistance test using megger

For the inverter, conduct the insulation resistance test on the main circuit only as shown below and do not perform the test on the control circuit. (Use a 500 VDC megger.)

#### REMARKS

- Before performing the insulation resistance test on the external circuit, disconnect the cables from all terminals of the inverter so that the test voltage is not applied to the inverter.
- For the continuity test of the control circuit, use a tester (high resistance range) and do not use the megger or buzzer.



### 5.2.9 Pressure test

Do not conduct a pressure test. Deterioration may occur.

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# **SPECIFICATIONS**

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This chapter explains the "SPECIFICATIONS" of this product.  
Always read the instructions before using the equipment.

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|            |  |            |
|------------|--|------------|
| <b>6.1</b> | <b>Rating.....</b>                               | <b>98</b>  |
| <b>6.2</b> | <b>Common specifications .....</b>               | <b>99</b>  |
| <b>6.3</b> | <b>Inverter outline dimension drawings .....</b> | <b>101</b> |

# 6.1 Rating

| Model FR-A846-□                   |                                    | 00250(7.5K)                       | 00310(11K)   | 00380(15K)   | 00470(18.5K) |              |
|-----------------------------------|------------------------------------|-----------------------------------|--|--------------|--------------|--------------|
| Applicable motor capacity (kW) *1 | LD                                 | 11                                | 15   | 18.5         | 22           |              |
|                                   | ND (initial setting)               | 7.5                               | 11   | 15           | 18.5         |              |
| Output                            | Rated capacity (kVA) *2            | LD                                | 18   | 22           | 27           | 33           |
|                                   |                                    | ND (initial setting)              | 13   | 18           | 24           | 29           |
|                                   | Rated current (A) *3               | LD                                | 23<br>(19.6)   | 29<br>(24.7) | 35<br>(29.8) | 43<br>(36.6) |
|                                   |                                    | ND (initial setting)              | 17<br>(25.5)   | 23<br>(34.5) | 31<br>(46.5) | 38<br>(57)   |
|                                   | Overload current rating *4         | LD                                | 120% 60s, 150% 3s (inverse-time characteristics) at surrounding air temperature 40°C |              |              |              |
|                                   |                                    | ND (initial setting)              | 150% 60s, 200% 3s (inverse-time characteristics) at surrounding air temperature 40°C |              |              |              |
|                                   | Rated voltage *5                   |                                   | Three-phase 380 to 500V  |              |              |              |
|                                   | Regenerative braking               | Maximum brake torque*6            | 10% torque/continuous  |              |              |              |
| Power supply                      | Rated input AC voltage/frequency   |                                   | Three-phase 380 to 500V 50Hz/60Hz *9   |              |              |              |
|                                   | Permissible AC voltage fluctuation |                                   | 323 to 550V 50Hz/60Hz  |              |              |              |
|                                   | Permissible frequency fluctuation  |                                   | ±5%  |              |              |              |
|                                   | Rated input current (A) *7         | LD                                | 23   | 29           | 35           | 43           |
|                                   |                                    | ND (initial setting)              | 17   | 23           | 31           | 38           |
|                                   | Power supply capacity (kVA) *8     | LD                                | 18   | 22           | 27           | 33           |
|                                   |                                    | ND (initial setting)              | 13   | 18           | 24           | 29           |
|                                   | Protective structure *10           | IEC 60529                         | Dust- and water-proof type (IP55)*11   |              |              |              |
| UL50                              |                                    | UL Type12*10                      |  |              |              |              |
| Cooling system                    |                                    | Forced-air-cooling + internal fan |  |              |              |              |
| Approx. mass (kg)                 |                                    | 26                                | 26   | 27           | 27           |              |

\*1 The applicable motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi 4-pole standard motor.

\*2 The rated output capacity indicated assumes that the output voltage is 440 V.

\*3 When an operation is performed with the carrier frequency set to 3 kHz or more, and the inverter output current reaches the value indicated in the parenthesis of the rated current, the carrier frequency is automatically lowered. The motor noise becomes louder accordingly.

\*4 The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.

\*5 The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the maximum point of the voltage waveform at the inverter output side is the power supply voltage multiplied by about  $\sqrt{2}$ .

\*6 Value for the ND rating.

\*7 The rated input current indicates a value at a rated output voltage. The impedance at the power supply side (including those of the input reactor and cables) affects the rated input current.

\*8 The power supply capacity is the value when at the rated output current. It varies by the impedance at the power supply side (including those of the input reactor and cables).

\*9 For the power voltage exceeding 480 V, set **Pr.977 Input voltage mode selection**. (For the details, refer to the FR-A800 Instruction Manual (Detailed).)

\*10 UL Type 12 Enclosure-Suitable for Installation in a Compartment Handling Conditioned Air (Plenum)

\*11 For compliance with IP55, remove the protective bushes and install the recommended cable glands.

## 6.2 Common specifications

|                          |   |                              |   |
|--------------------------|---|------------------------------|---|
| Control specifications   | Control method  |                              | Soft-PWM control, high carrier frequency PWM control (selectable among V/F control, Advanced magnetic flux vector control, Real sensorless vector control), vector control <sup>1</sup> , and PM sensorless vector control  |
|                          | Output frequency range  |                              | 0.2 to 590 Hz (The upper-limit frequency is 400 Hz under Advanced magnetic flux vector control, Real sensorless vector control, vector control <sup>1</sup> , and PM sensorless vector control.)  |
|                          | Frequency setting resolution  | Analog input                 | 0.015 Hz/60 Hz (0 to 10 V/12 bits for terminals 2 and 4)<br>0.03 Hz/60 Hz (0 to 5 V/11 bits or 0 to 20 mA/approx. 11 bits for terminals 2 and 4, 0 to $\pm 10$ V/12 bits for terminal 1)<br>0.06 Hz/60 Hz (0 to $\pm 5$ V/11 bits for terminal 1)   |
|                          |   | Digital input                | 0.01 Hz   |
|                          | Frequency accuracy  | Analog input                 | Within $\pm 0.2\%$ of the max. output frequency ( $25^{\circ}\text{C} \pm 10^{\circ}\text{C}$ )   |
|                          |   | Digital input                | Within 0.01% of the set output frequency  |
|                          | Voltage/frequency characteristics   |                              | Base frequency can be set from 0 to 590 Hz. Constant-torque/variable-torque pattern or adjustable 5 points V/F can be selected.   |
|                          | Starting torque   |                              | 150% 0.3 Hz<br>(Real sensorless vector control, vector control <sup>1</sup> )   |
|                          | Torque boost  |                              | Manual torque boost   |
|                          | Acceleration/deceleration time setting  |                              | 0 to 3600 s (acceleration and deceleration can be set individually), linear or S-pattern acceleration/deceleration mode, backlash countermeasures acceleration/deceleration can be selected.  |
|                          | DC injection brake (induction motor)  |                              | Operation frequency (0 to 120 Hz), operation time (0 to 10 s), operation voltage (0 to 30%) variable  |
|                          | Stall prevention operation level  |                              | Activation range of stall prevention operation (LD rating: 0 to 150%, ND rating: 0 to 220%). Whether to use the stall prevention or not can be selected   |
|                          | Torque limit level  |                              | Torque limit value can be set (0 to 400% variable).   |
| Operation specifications | Frequency setting signal  | Analog input                 | Terminals 2 and 4: 0 to 10 V, 0 to 5 V, 4 to 20 mA (0 to 20 mA) are available.<br>Terminal 1: -10 to +10 V, -5 to +5 V are available.   |
|                          |   | Digital input                | Input using the setting dial of the operation panel or parameter unit<br>Four-digit BCD or 16-bit binary (when used with option FR-A8AX)  |
|                          | Start signal  |                              | Forward and reverse rotation or start signal automatic self-holding input (3-wire input) can be selected.   |
|                          | Input signals (twelve terminals)  |                              | Low-speed operation command, Middle-speed operation command, High-speed operation command, Second function selection, Terminal 4 input selection, Jog operation selection, Electronic bypass function, Output stop, Start self-holding selection, Forward rotation command, Reverse rotation command, Inverter reset  |
|                          | Pulse train input   |                              | 100 kpps  |
|                          | Operational functions   |                              | Maximum and minimum frequency settings, multi-speed operation, acceleration/deceleration pattern, thermal protection, DC injection brake, starting frequency, JOG operation, output stop (MRS), stall prevention, regeneration avoidance, strengthened excitation deceleration, DC feeding, frequency jump, rotation display, automatic restart after instantaneous power failure, electronic bypass sequence, remote setting, automatic acceleration/deceleration, intelligent mode, retry function, carrier frequency selection, fast-response current limit, forward/reverse rotation prevention, operation mode selection, slip compensation, droop control, load torque high-speed frequency control, speed smoothing control, traverse, auto tuning, applied motor selection, gain tuning, machine analyzer <sup>1</sup> , RS-485 communication, PID control, PID pre-charge function, easy dancer control, cooling fan operation selection, stop selection (deceleration stop/coasting), power-failure deceleration stop function, stop-on-contact control, PLC function, life diagnosis, maintenance timer, current average monitor, multiple rating, orientation control <sup>1</sup> , speed control, torque control, position control, pre-excitation, torque limit, test run, 24 V power supply input for control circuit, safety stop function |
|                          | Output signal<br>Open collector output (five terminals)<br>Relay output (two terminals) |                              | Inverter running, Up to frequency, Instantaneous power failure/undervoltage, Overload warning, Output frequency detection, Fault<br>Fault codes of the inverter can be output (4 bits) from the open collector.   |
|                          | Pulse train output  |                              | 50 kpps   |
| Indication               | For meter   | Pulse train output (FM type) | Max. 2.4 kHz: one terminal (output frequency)<br>The monitored item can be changed using <b>Pr.54 FM/CA terminal function selection</b> .   |
|                          |   | Current output (CA type)     | Max. 20 mADC: one terminal (output current)<br>The monitored item can be changed using <b>Pr.54 FM/CA terminal function selection</b> .   |
|                          |   | Voltage output               | Max. 10 VDC: one terminal (output voltage)<br>The monitored item can be changed using <b>Pr.158 AM terminal function selection</b> .  |
|                          | Operation panel (FR-DU08-01)  | Operating status             | Output frequency, Output current, Output voltage, Frequency setting value<br>The monitored item can be changed using <b>Pr.52 Operation panel main monitor selection</b> .  |
|                          |   | Fault record                 | Fault record is displayed when a fault occurs. Past 8 fault records (output voltage/current/frequency/cumulative energization time immediately before the fault occurs) are stored.   |

## Common specifications

|                    |                                     |  |   |
|--------------------|-------------------------------------|--|---|
|                    | <b>Protective/ warning function</b> |  | <p>Overcurrent trip during acceleration, Overcurrent trip during constant speed, Overcurrent trip during deceleration or stop, Regenerative overvoltage trip during acceleration, Regenerative overvoltage trip during constant speed, Regenerative overvoltage trip during deceleration or stop, Inverter overload trip, Motor overload trip, Heatsink overheat, Instantaneous power failure, Undervoltage, Input phase loss*4, Stall prevention stop, Loss of synchronism detection*4, Brake transistor alarm detection, Output side earth (ground) fault overcurrent, Output phase loss, External thermal relay operation*4, PTC thermistor operation*4, Option fault, Communication option fault, Parameter storage device fault, PU disconnection, Retry count excess*4, Parameter storage device fault, CPU fault, Operation panel power supply short circuit RS-485 terminals power supply short circuit, 24 VDC power fault, Abnormal output current detection*4, Inrush current limit circuit fault, Communication fault (inverter), Analog input fault, USB communication fault, Safety circuit fault, Overspeed occurrence*4, Speed deviation excess detection*1*4, Signal loss detection*1*4, Excessive position fault*1*4, Brake sequence fault*4, Encoder phase fault*1*4, 4 mA input fault*4, Pre-charge fault*4, PID signal fault*4, Option fault, Opposite rotation deceleration fault*4, Internal circuit fault, User definition error by the PLC function, Abnormal internal temperature</p> |
|                    | <b>Warning function</b>             |  | <p>Fan alarm, Stall prevention (overcurrent), Stall prevention (overvoltage), Electronic thermal relay function pre-alarm, PU stop, Speed limit indication*4, Safety stop, Maintenance signal output*4, USB host error, Home position return setting error*4, Home position return uncompleted*4, Home position return parameter setting error*4, Operation panel lock*4, Password locked*4, Parameter write error, Copy operation error, Internal-circulation fan alarm</p>  |
| <b>Environment</b> | <b>Surrounding air temperature</b>  |  | -10°C to +40°C (non-freezing)   |
|                    | <b>Surrounding air humidity</b>     |  | 95% RH or less (non-condensing),  |
|                    | <b>Storage temperature*2</b>        |  | -20°C to +65°C  |
|                    | <b>Atmosphere</b>                   |  | Indoors (without corrosive gas, flammable gas, oil mist, dust and dirt, etc.)   |
|                    | <b>Altitude/vibration</b>           |  | Maximum 1000 m above sea level *3, 5.9 m/s <sup>2</sup> or less at 10 to 55 Hz (directions of X, Y, Z axes)   |

\*1 Available only when the option (FR-A8AP) is mounted.

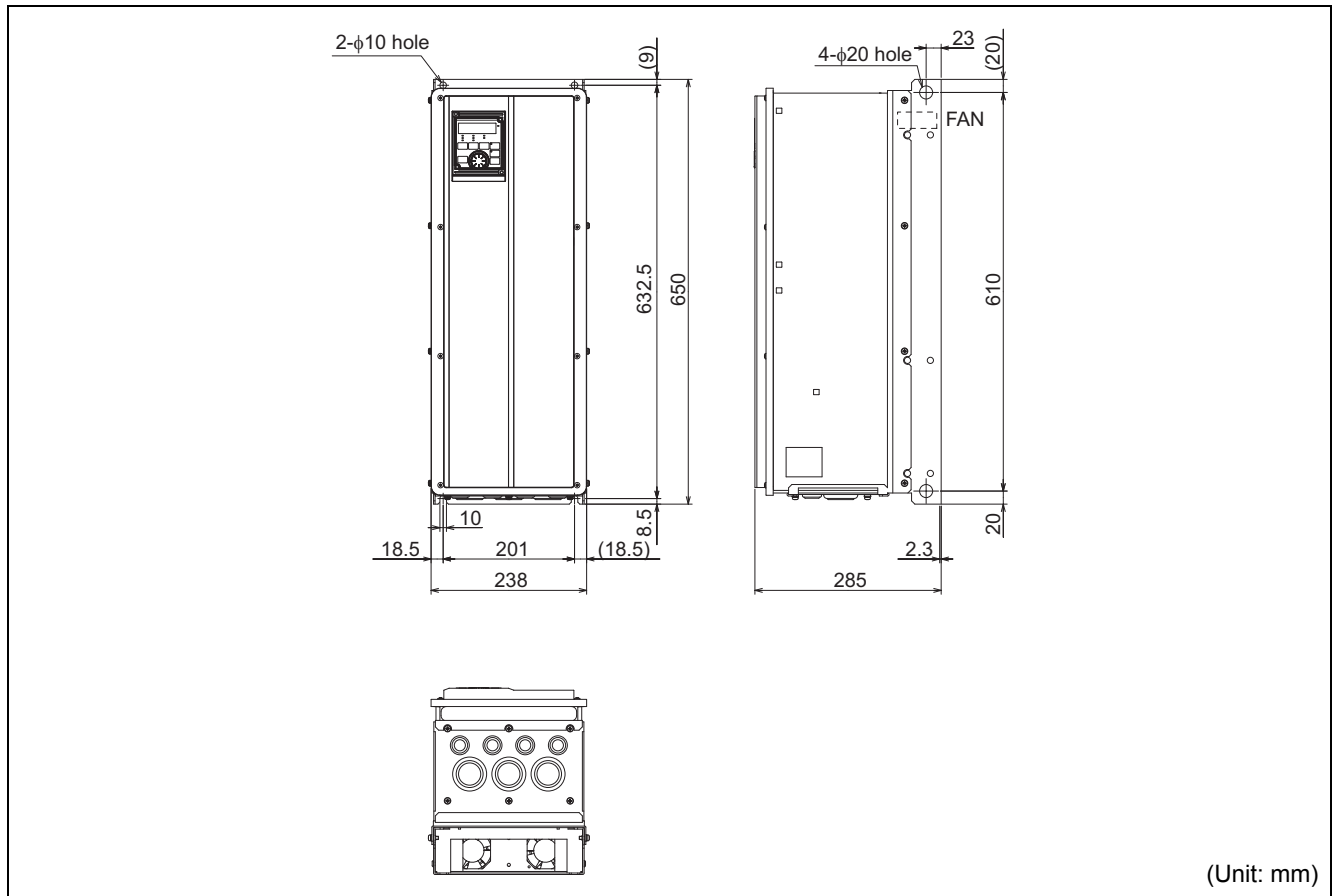
\*2 Temperature applicable for a short time, e.g. in transit.

\*3 For the installation at an altitude above 1,000 m up to 2,500 m, derate the rated current 3% per 500 m.

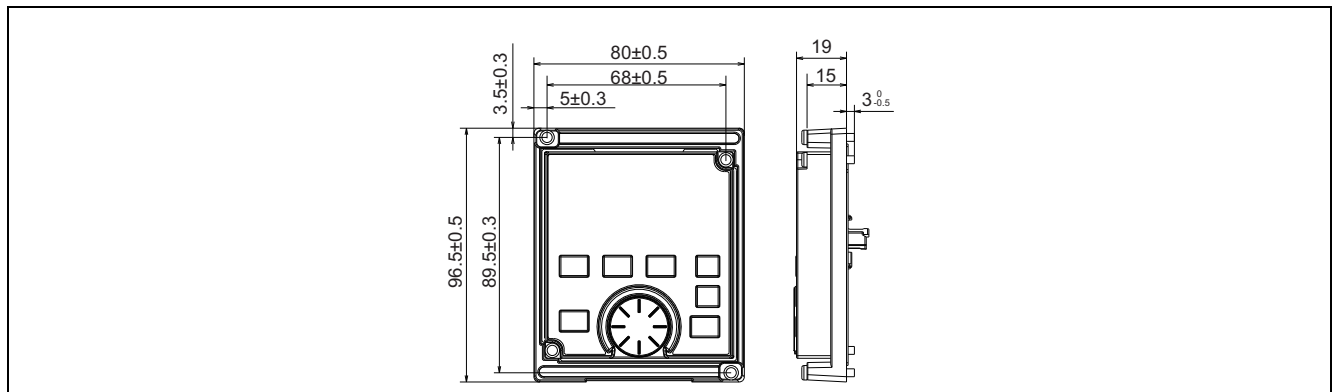
\*4 This protective function is not available in the initial status.

## 6.3 Inverter outline dimension drawings

FR-A846-00250(7.5K), 00310(11K), 00380(15K), 00470(18.5K)



Operation panel (FR-DU08-01)



### REMARKS

- For the outline dimensions of the dedicated motors, refer to the FR-A800 Instruction Manual (Detailed).

# MEMO

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# APPENDIX

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APPENDIX provides the reference information for use of this product.  
Refer to APPENDIX as required.

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|  |            |
|--|------------|
| <b>Appendix 1 Differences and compatibility with the FR-A840 .....</b> | <b>104</b> |
| <b>Appendix 2 Instructions for compliance with the EU Directives..</b> | <b>105</b> |
| <b>Appendix 3 Instructions for UL and cUL .....</b>                    | <b>107</b> |



## Appendix 1 Differences and compatibility with the FR-A840

| Item   | FR-A840  | FR-A846  |
|--|--|--|
| <b>Protective structure</b>  | Enclose type (IP20): FR-A840-00620(22K) or lower<br>Open type (IP00): FR-A840-00770(30K) or higher | Dust- and water-proof type (IP55): all capacities                                    |
| <b>Multiple rating<br/>(Pr.570 Multiple rating setting)</b>  | SLD, LD, ND (initial setting), HD rating<br>(Setting range "0 to 3")                               | LD, ND rating (initial setting)<br>(Setting range "1, 2")                            |
| <b>Brake transistor<br/>(brake resistor usable)</b>  | Built in for FR-A820-00046(0.4K) to 01250(22K)<br>Built in for FR-A840-00023(0.4K) to 03160(55K)   | None (using brake resistor unavailable)  |
| <b>Internal fan</b>  | None   | Provided   |
| <b>Protective function</b>   | —  | Internal-circulation fan alarm (FN2), Abnormal internal temperature (E.IAH) provided |
| <b>Pr.30 Regenerative function selection</b>   | Setting range "0 to 2, 10, 11, 20, 21, 100, 101, 110, 111, 120, 121"                               | Setting range "0, 2, 10, 20, 100, 110, 120"  |
| <b>Pr.70 Special regenerative brake duty</b>   | Provided   | None   |
| <b>Regenerative brake duty<br/>(setting value "9" in Pr.52, Pr.54, Pr.158, Pr.774 to Pr.776, Pr.992, Pr.1027 to Pr.1034)</b> | Provided (setting available)   | None (setting unavailable)   |
| <b>DC reactor</b>  | Option   | Built-in   |
| <b>Operation panel</b>   | FR-DU08: IP40 (except for the PU connector section)  | FR-DU08-01: IP55 (except for the PU connector section)                               |

## Appendix 2 Instructions for compliance with the EU Directives

The EU Directives are issued to standardize different national regulations of the EU Member States and to facilitate free movement of the equipment, whose safety is ensured, in the EU territory.

Since 1996, compliance with the EMC Directive that is one of the EU Directives has been legally required. Since 1997, compliance with the Low Voltage Directive, another EU Directive, has been also legally required. When a manufacturer confirms its equipment to be compliant with the EMC Directive and the Low Voltage Directive, the manufacturer must declare the conformity and affix the CE marking.

### ● The authorized representative in the EU

The authorized representative in the EU is shown below.

Name: Mitsubishi Electric Europe B.V.

Address: Gothaer Strasse 8, 40880 Ratingen, Germany

### ● Note

We declare that this inverter conforms with the EMC Directive in industrial environments and affix the CE marking on the inverter. When using the inverter in a residential area, take appropriate measures and ensure the conformity of the inverter used in the residential area.

### (1) EMC Directive

We declare that this inverter conforms with the EMC Directive and affix the CE marking on the inverter.

- EMC Directive: 2004/108/EC
- Standard(s): EN61800-3:2004 (First environment / PDS Category "C2", Second environment / PDS Category "C3"<sup>\*1</sup>)
  - \*1 The applicable standard depends on the built-in EMC filter.
- This inverter is not intended to be used on a low-voltage public network which supplies domestic premises.
  - Radio frequency interference is expected if used on such a network.
- The installer shall provide a guide for installation and use, including recommended mitigation devices.

Note:

First environment

Environment including residential buildings. Includes buildings directly connected without a transformer to the low voltage power supply network which supplies power to residential buildings.

Second environment

Environment including all buildings except buildings directly connected without a transformer to the low voltage power supply network which supplies power to residential buildings.

### ● Note

Set the EMC filter valid and install the inverter and perform wiring according to the following instructions.

- \*1 This inverter is equipped with an EMC filter. Enable the EMC filter. (For details, refer to [page 66](#).)
- \*2 Connect the inverter to an earthed power supply.
- \*3 Install a motor and a control cable written in the EMC Installation Manual (BCN-A21041-204) according to the instruction.
- \*4 Confirm that the inverter conforms with the EMC Directive as the industrial drives application for final installation.
- \*5 The inverter with a built-in Class C2 EMC filter complies with EN/IEC61000-3-12 provided that the short-circuit power  $S_{sc}$  is greater than or equal to the value provided in the table below at the interface point between the user's supply and the public system. It is the responsibility of the installer or user of the equipment to ensure, by consultation with the distribution network operator if necessary, that the equipment is connected only to a supply with a short-circuit power  $S_{sc}$  greater than or equal to the value mentioned in the table below.

| Inverter model       | Standard         | $S_{sc}$ | $R_{sce}$  |
|----------------------|------------------|----------|------------|
| FR-A846-00250(7.5K)  | EN/IEC61000-3-12 | 2261kVA  | $\geq 120$ |
| FR-A846-00310(11K)   |                  | 3059kVA  |            |
| FR-A846-00380(15K)   |                  | 4124kVA  |            |
| FR-A846-00470(18.5K) |                  | 5055kVA  |            |

## (2) Low Voltage Directive

We have self-confirmed our inverters as products compliant to the Low Voltage Directive (Conforming standard EN 61800-5-1) and affix the CE marking on the inverters.

### ● Outline of instructions

- \*1 Do not use an earth leakage current breaker as an electric shock protector without connecting the equipment to the earth. Connect the equipment to the earth securely.
- \*2 Wire the earth terminal independently. (Do not connect two or more cables to one terminal.)
- \*3 Use the cable sizes on [page 25](#) under the following conditions.
  - Surrounding air temperature: 40°C (104°F) maximumIf conditions are different from above, select appropriate wire according to EN60204 Appendix C TABLE 5.
- \*4 Use a tinned (plating should not include zinc) crimping terminal to connect the earth (ground) cable. When tightening the screw, be careful not to damage the threads.  
For use as a product compliant with the Low Voltage Directive, use PVC cable whose size is indicated on [page 25](#).
- \*5 Use the moulded case circuit breaker and magnetic contactor which conform to the EN or IEC Standard.
- \*6 DC current may flow from the inverter to a protective earth (ground) conductor. When using a residual current device (RDC) or residual current monitor (RDM), connect a type B RCD or RCM to the power supply side.
- \*7 Use the inverter under the conditions of overvoltage category II (usable regardless of the earth (ground) condition of the power supply), overvoltage category III (usable with the earthed-neutral system power supply, 400 V class only) and pollution degree 2 or lower specified in IEC664.
- \*8 On the input and output of the inverter, use cables of the type and size set forth in EN60204 Appendix C.
- \*9 The operating capacity of the relay outputs (terminal symbols A1, B1, C1, A2, B2, C2) should be 30VDC, 0.3A. (Relay output has basic isolation from the inverter internal circuit.)
- \*10 Control circuit terminals on [page 19](#) are safely isolated from the main circuit.
- \*11 Environment (For the detail, refer to [page 16](#).)

|                             | During Operation           | In Storage                  | During Transportation       |
|-----------------------------|----------------------------|-----------------------------|-----------------------------|
| Surrounding air temperature | -10 to +40°C (14 to 104°F) | -20 to +65°C (-4 to +149°F) | -20 to +65°C (-4 to +149°F) |
| Ambient humidity            | 95% RH or less             | 95% RH or less              | 95% RH or less              |
| Maximum altitude            | 2500m (8202 feet)          | 2500m (8202 feet)           | 10000m (32808 feet)         |

- \*12 Install the inverter at a place where ultraviolet radiation is not applied directly.

### ● Wiring protection

Class T, Class J, Class CC fuse, or UL 489 Molded Case Circuit Breaker (MCCB) must be provided. T or UL 489 Molded Case Circuit Breaker (MCCB) must be provided.

| FR-A846-[]                           | 00250<br>(7.5K) | 00310<br>(11K) | 00380<br>(15K) | 00470<br>(18.5K) |
|--------------------------------------|-----------------|----------------|----------------|------------------|
| Rated fuse voltage(V)                | 500 V or more   |                |                |                  |
| Fuse Maximum allowable rating (A) *1 | 60              | 70             | 90             | 100              |
| Molded case circuit breaker (MCCB)   |                 |                |                |                  |
| Maximum allowable rating (A) *1      | 60              | 70             | 90             | 100              |

- \*1 Maximum allowable rating by US National Electrical Code. Exact size must be chosen for each installation.

### ● Short circuit ratings

- 400 V class
- Suitable For Use in A Circuit Capable of Delivering Not More Than 100 kA rms Symmetrical Amperes, 550 V or 600 V Maximum.

## Appendix 3 Instructions for UL and cUL

(Standard to comply with: UL 508C, CSA C22.2 No.14)

### (1) General precaution

CAUTION - Risk of Electric Shock -

The bus capacitor discharge time is 10 minutes. Before starting wiring or inspection, switch power off, wait for more than 10 minutes.

ATTENTION - Risque de choc électrique -

La durée de décharge du condensateur de bus est de 10 minutes. Avant de commencer le câblage ou l'inspection, mettez l'appareil hors tension et attendez plus de 10 minutes.

### (2) Installation

The below types of inverter have been approved as products for a UL type12 enclosure that is suitable for Installation in a Compartment Handling Conditioned Air (Plenum).

Install the inverter so that the ambient temperature, humidity and ambience of the inverter will satisfy the specifications. (Refer to [page 16](#).)

The drive must be installed in clean air according to enclosure classification.

Cooling air must be clean, free from corrosive materials and electrically conductive dust regarding the UL Type 12 enclosure.

This enclosure provides protection from airborne dust and light sprays or splashing water from all directions.

### ● Wiring protection

For installation in the United States, Class T, Class J, or Class CC fuse, or UL 489 Molded Case Circuit Breaker (MCCB) must be provided, in accordance with the National Electrical Code and any applicable local codes.

For installation in Canada, Class T, Class J, or Class CC fuse, or UL 489 Molded Case Circuit Breaker (MCCB) must be provided, in accordance with the Canadian Electrical Code and any applicable local codes.

| FR-A846-[]  | 00250<br>(7.5K) | 00310<br>(11K) | 00380<br>(15K) | 00470<br>(18.5K) |
|---|-----------------|----------------|----------------|------------------|
| Rated fuse voltage(V)   | 500 V or more   |                |                |                  |
| Fuse Maximum allowable rating (A) *1                                  | 60              | 70             | 90             | 100              |
| Molded case circuit breaker (MCCB)<br>Maximum allowable rating (A) *1 | 60              | 70             | 90             | 100              |

\*1 Maximum allowable rating by the US National Electrical Code. Exact size must be chosen for each installation.

### (3) Wiring to the power supply and the motor

For wiring the input (R/L1, S/L2, T/L3) and output (U, V, W) terminals of the inverter, use the UL listed copper, stranded wires (rated at 75°C) and round crimping terminals. Crimp the crimping terminals with the crimping tool recommended by the terminal maker.

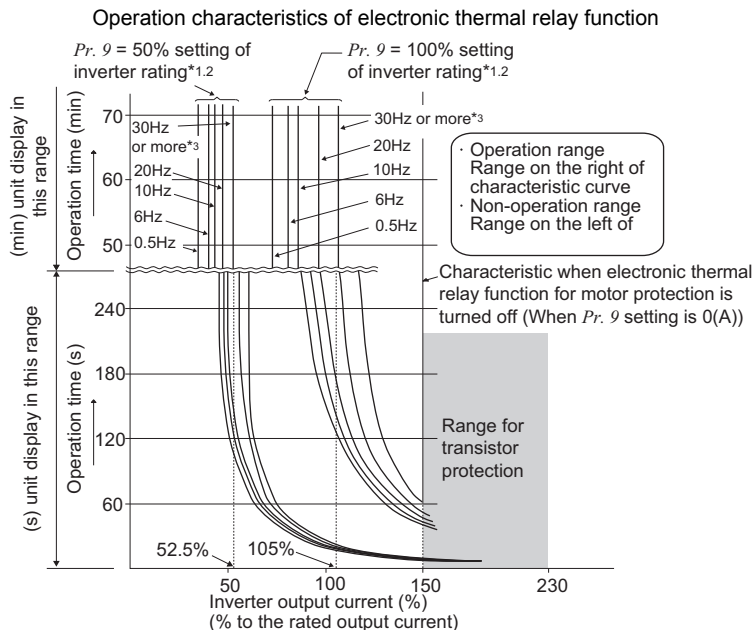
### (4) Short circuit ratings

- 400 V class

Suitable For Use in A Circuit Capable of Delivering Not More Than 100 kA rms Symmetrical Amperes, 550 V or 600 V Maximum.

## (5) Motor overload protection

When using the electronic thermal relay function as motor overload protection, set the rated motor current in **Pr.9 Electronic thermal O/L relay**.



This function detects the overload (overheat) of the motor, stops the operation of the inverter's output transistor, and stops the output. (The operation characteristic is shown on the left.)

- When using the Mitsubishi constant-torque motor

- Set one of "1", "13" to "16", "50", "53", "54" in **Pr.71**. (This provides a 100% continuous torque characteristic in the low-speed range.)
- Set the rated current of the motor in **Pr.9**.

- \*1 When a value 50% of the inverter rated output current (current value) is set in **Pr.9**
- \*2 The % value denotes the percentage to the rated inverter current. It is not the percentage to the rated motor current.
- \*3 When you set the electronic thermal relay function dedicated to the Mitsubishi constant-torque motor, this characteristic curve applies to operation at 6 Hz or higher.

### REMARKS

- The internal accumulated heat value of the electronic thermal relay function is reset by inverter power reset and reset signal input. Avoid unnecessary reset and power-OFF.
- When multiple motors are driven with a single inverter or when a multi-pole motor or a special motor is driven, install an external thermal relay (OCR) between the inverter and motors. Note that the current indicated on the motor rating plate is affected by the line-to-line leakage current (refer to [page 62](#)) when selecting the setting for an external thermal relay. The cooling effect of the motor drops during low-speed operation. Use a thermal protector or a motor with built-in thermistor.
- When the difference between the inverter and motor capacities is large and the setting is small, the protective characteristics of the electronic thermal relay function will be deteriorated. In this case, use an external thermal relay.
- A special motor cannot be protected by the electronic thermal relay function. Use an external thermal relay.
- Set **Pr.9** = "0" for vector-control-dedicated motors (SF-V5RU) because they are equipped with thermal protectors.
- Electronic thermal relay may not operate when 5% or less of rated inverter current is set to electronic thermal relay setting.
- Motor over temperature sensing is not provided by the drive.

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- **When playing the enclosed CD-ROM on Windows OS**

- Operating environment
  - The following system is required to read instruction manuals contained in the enclosed CD-ROM.

| Item         | Specifications   |
|--------------|--|
| OS           | Microsoft Windows XP Professional or Home Edition, Windows XP Tablet PC Edition, Windows vista, Windows 7, Windows 8 |
| CPU          | Intel Pentium or better processor  |
| Memory       | 128MB of RAM   |
| Hard disk    | 90MB of available hard-disk space  |
| CD-ROM drive | Double speed or more (more than quadruple speed is recommended)  |
| Monitor      | 800x600 dot or more  |
| Application  | Adobe Reader 7.0 or more<br>Internet Explorer 6.0 or more  |

- Operating method of the enclosed CD-ROM

How to read instruction manuals

- Step 1. Start Windows and place the enclosed CD-ROM in the CD-ROM drive.  
Step 2. The main window automatically opens by the web browser.  
Step 3. Choose your language by a language choice menu of the page left edge.  
Step 4. Click a manual you want to read in the "INSTRUCTION MANUAL" list.  
Step 5. PDF manual you clicked opens.

\* Manual opening of the enclosed CD-ROM

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Step 2. Select a CD-ROM drive (example: D drive) of "My computer" and click the right mouse button. Then, click "open" in the context menu.  
Step 3. Open "index.html" in the opened folder.  
Step 4. The main window opens by the web browser. Operates according to the steps from "Step 3" of "How to read instruction manuals"

- PDF data of the instruction manual are stored in "MANUAL" folder on the enclosed CD-ROM.

## REVISIONS

\*The manual number is given on the bottom left of the back cover.

| Print Date | *Manual Number      | Revision      |
|------------|---------------------|---------------|
| Feb. 2014  | IB(NA)-0600531ENG-A | First edition |
|            |                     |               |

**⚠ For Maximum Safety**

- Mitsubishi inverters are not designed or manufactured to be used in equipment or systems in situations that can affect or endanger human life.
- When considering this product for operation in special applications such as machinery or systems used in passenger transportation, medical, aerospace, atomic power, electric power, or submarine repeating applications, please contact your nearest Mitsubishi sales representative.
- Although this product was manufactured under conditions of strict quality control, you are strongly advised to install safety devices to prevent serious accidents when it is used in facilities where breakdowns of the product are likely to cause a serious accident.
- Please do not use this product for loads other than three-phase induction motors.



|               |  |
|---------------|--|
| MODEL         | FR-A806<br>INSTRUCTION MANUAL (HARDWARE) |
| MODEL<br>CODE | 1A2-P56                                  |